

heuristics to improve the performance of SAT solver

Lazy datastructure

- 2 watched literals
- Pure literals

Runtime choices

- Variable ordering ✓
- Restarts
- learned clause deletion
- Phase saving.

Optimal storage

- variables
- clauses
- occurrence maps

Pre/In processing techniques

Variable ordering, Decision heuristics, Branching heuristics

✓ # of variables occurrences in remaining unsatisfied clauses
↳ different variants were studied in 90's

2. Dynamic heuristics

- focus on variables which were useful recently in deriving learned clauses.
- can be interpreted as reinforcement learning
- VSIDS: Variable State Independent Decaying Sum
↳ different variants were studied

3. Look-ahead

↳ spent more time in selecting good variables.

DLIS (Dynamic Largest Individual Sum)

→ for any variable v :

Implemented in
Grasp

Requires # literals
queries for each
decision.

→ $C_{v,p}$: # of unresolved (unsatisfied) clause
in which v appears positively.

→ $C_{v,n}$: # of unresolved (unsatisfied) clause
in which v appears negatively.

→ let 'a' be the literal for which $C_{a,p}$ is Maximal

→ let 'b' be the literal for which $C_{b,n}$ is maximal

→ if $C_{a,p} > C_{b,n}$ then choose a and set to 1
else choose b & set to 0.

Jeroslow-Kang Method

→ gives an exponentially higher weight to literals in shorter clauses.

→ for every literal l_i

$$J(l) = \sum_{l \in C, C \in F} 2^{-|C|}$$

MDM (Maximum Occurrence of clauses of Minimum Size)

→ decide a number W , such that if $|C| < W$ then clause C is considered to be the small.

→ let $f^*(x)$ be the # of small clauses containing x .
choose x that maximizes.

$$(f^*(x) + f^*(\neg x)) \times 2^k + f^*(x) \times f^*(\neg x)$$

→ k is choose heuristically.

→ Give preference to satisfying small clauses.

→ Among those, give preference to Balanced variables.

$$\begin{array}{l} \rightarrow f^*(x) = 3 \ \& \ f^*(\neg x) = 3 \text{ is preferred over} \\ f^*(x) = 1 \ \& \ f^*(\neg x) = 5. \end{array}$$

Variable State Independent Decaying Sums (VSIDS)

Implemented
in Chaff.

→ Each literal (l) has a counter $S(l)$, initialized to zero.

→ For every new clause $C = [l_1, l_2, \dots, l_n]$, $S(l_i)$ is incremented.

→ The unassigned variables of polarity with highest counter is chosen.

→ Ties are broken randomly.

→ Periodically (once in 256 conflicts), all counters are halved.
↳ can change

VSIDs example :-

Heuristic Related data

literal	score
a	4
$\neg a$	5
b	3
$\neg b$	3
c	2
$\neg c$	3
d	2
$\neg d$	4
e	2
$\neg e$	6
⋮	⋮

initial value,
occurrences of $\neg a$ in
Formula F.

count literal
appearances in
formula F.

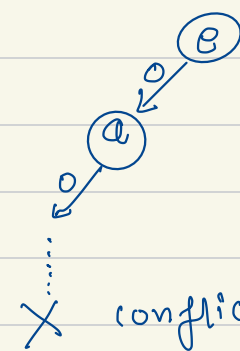
VSIDS example :-

Heuristic Related data

literal	score
a	4
$\neg a$	5
b	3
$\neg b$	3
c	2
$\neg c$	3
d	2
$\neg d$	4
e	2
$\neg e$	6
⋮	⋮
v	

initial value, occurrences of 'a' in Formula F.

count literal appearances in formula F.



$(\neg a \vee a \vee c \vee \neg b \vee k)$
Conflict clauses

VSIDS example :-

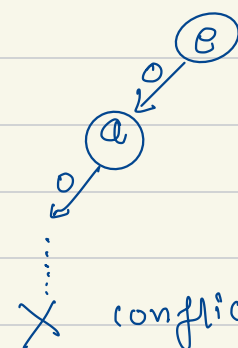
of conflict = 1

Heuristic Related data

literal	score
a	4 + 1
$\neg a$	5
b	3
$\neg b$	3 + 1
c	2 + 1
$\neg c$	3
d	2
$\neg d$	4
e	2
$\neg e$	6
⋮	⋮ + 1
	⋮

initial value,
occurrences of 'a' in
Formula F.

count literal
appearances in
formula F.



($\neg a \vee a \vee c \vee \neg b \vee k$)
Conflict clauses

Why VSIDS was a breakthrough?

- Pre-chaff static heuristics
 - Go over all clauses that are not satisfied & compute some function $f(a)$ for each literal "a".

- VSIDS
 - extremely low overhead
 - dynamic & local
 - ↳ conflict driven
 - focuses the search to learn from the local content.

EVSIDS (Exponential VSIDS '03)

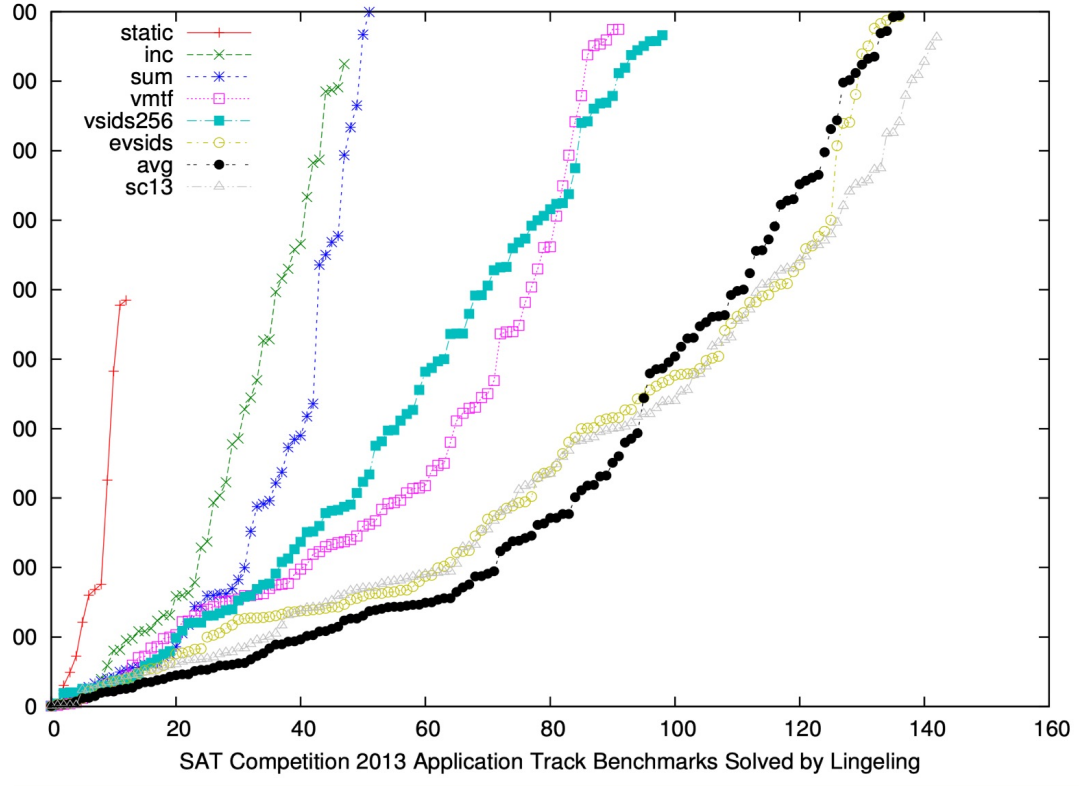
→ dynamically adjust increment: $\delta' = \delta \cdot 1/f$

δ : is score of a literal

f : need to be chosen
typically 0.95

→ Rescale when score for any variables becomes higher than 10^{100} .

MiniSAT uses EVSIDS



Learned clause deletion

- CDCL may learn a lot of clauses.
- In terms of storage solver needs to delete some clauses periodically.
 - How does it affect the soundness & completeness of a CDCL based SAT solver?

clause deletion

→ which clause to delete?

- delete longer clauses with higher prob.
- never delete unit clause
- never delete "active clause", clauses which are participating in unit propagation.

→ when to delete a clause?

- At restart
- if # of learned clause = predefined threshold.

clause deletion

- MinisAT reduce (deletes) half of the clauses.
- keep the most active, then shortest, then youngest (FIFO) clauses.

Restarts :-

→ SAT solvers are likely to get stuck in a local search space.

→ restart CDCL with a different variable ordering.

→ keep learned clauses across restart.

→ slowly increase the intervals of restarts such that tools becomes a **complete solver**.

→ usually depends on # of conflict clauses or # of decision levels.

Phase Saving & Rapid Restarts

↳ polarity of a variable.

"phase saving" → pick the phase of last assignment
↳ if not forced, don't change.

rapid restarts :- theoretically shown that it
avoids local minima

↳ practically works well with
phase-saving.

Pre (in) Processing

- Eliminate tautologies / unit clauses / Pure literal elimination.
 - Subsumption / self-subsuming resolution.
 - Blocked clause elimination.
 - literal equivalence.
 - Bounded variable addition / elimination
- first used in*
kissat

Blocked clause elimination (BCE)

F
formula

one clause
C & F with L.

$a \vee b \vee c$

all clauses
with $\neg l$

$\neg l \vee \neg a \vee c$

$\neg l \vee \neg b \vee d$

Resolutions with C, all the resolvents of C on L.
tautological

BCF :

A clause $C \in F$ is a blocked clause in F , if there is literal $l \in C$ such that for each $C' \in F$ with $\neg l \in C'$, the resolvent $(C \setminus \{l\} \cup (C' \setminus \{\neg l\}))$ obtained from resolving C and C' on l is a tautology.

$$F = (a \vee b) \wedge (a \vee \neg b \vee \neg c) \wedge (\neg a \vee c)$$

$$F = (a \vee b) \wedge (a \vee \neg b \vee \neg c) \wedge (\neg a \vee c)$$

1st clause

$$\begin{cases} a \rightarrow c_1 \neq c_3 \rightarrow b \vee c & (\text{not tautology}) \\ b \rightarrow c_1 \neq c_2 \rightarrow a \vee \neg c & (\text{not tautology}) \end{cases}$$

2nd clause

$$\begin{cases} a \rightarrow c_2 \neq c_3 \rightarrow (b \vee c \vee \neg c) & \text{tautology} \\ b \rightarrow c_1 \neq c_2 \rightarrow \neg(a \vee \neg c) & \text{not tautology} \\ c \rightarrow c_2 \neq c_3 \rightarrow (a \vee \neg a \vee b) & \text{tautology} \end{cases}$$

3rd clause

$$\begin{cases} \neg a \rightarrow \begin{cases} c_1 \neq c_3 & b \vee c \rightarrow \text{not tautology} \\ c_2 \neq c_3 & b \vee c \vee \neg c \rightarrow \text{tautology} \end{cases} \\ c \rightarrow c_2 \neq c_3 & (a \vee \neg a \vee b) \text{ tautology} \end{cases}$$

$$F = (a \vee b) \wedge (a \vee \neg b \vee \neg c) \wedge (\neg a \vee c)$$

→ only first clause is not blocked

→ second clause has two blocked literals
└ $a \vee \neg c$

→ third clause has c has blocked literals.

$$F = (a \vee b) \wedge (a \vee \neg b \vee \neg c)$$

↙
Now, all clauses are blocked, hence all clauses
can be removed

SAT solving is algorithm, science or art

