COL:750

Foundations of Automatic Verification

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Course Webpage

https://priyanka-golia.github.io/teaching/COL-750/index.html



F = True

- = p (atomic proposition)
- $=F_1 \wedge F_2, F_1 \vee F_2, F_1 \rightarrow F_2, F_1 \leftrightarrow F_2$ $= \neg F_1$
- = $\mathbf{N} F_1$ N is "Next". F_1 is True at next step. Often represented as \mathbf{O}, \mathbf{X} .
- $= F_1 \cup F_2$ U is "Until". F_2 is True at "some point, say t", and until then F_1 is True. At "t", F_1 doesn't have to hold any more!

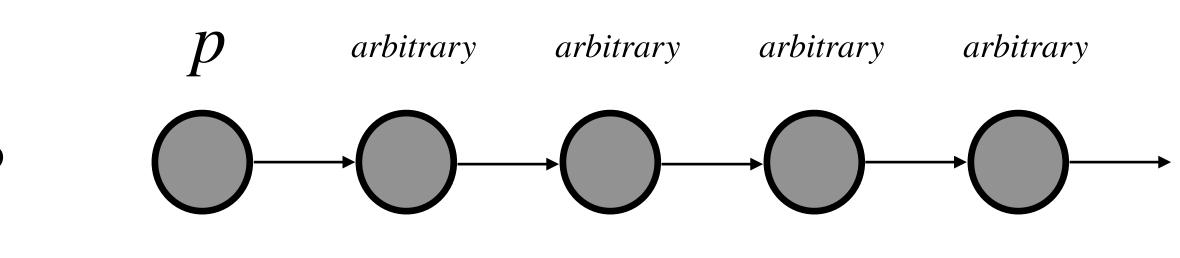
 $F = N F_1$ N is "Next". F_1 is True at next step. Often represented as O, X.

accelerate \rightarrow **N** moving shoot $\rightarrow N$ (goal \lor miss) Mario will keep jumping until he lands. jumping U landed The emergency light will stay on until the power comes back.

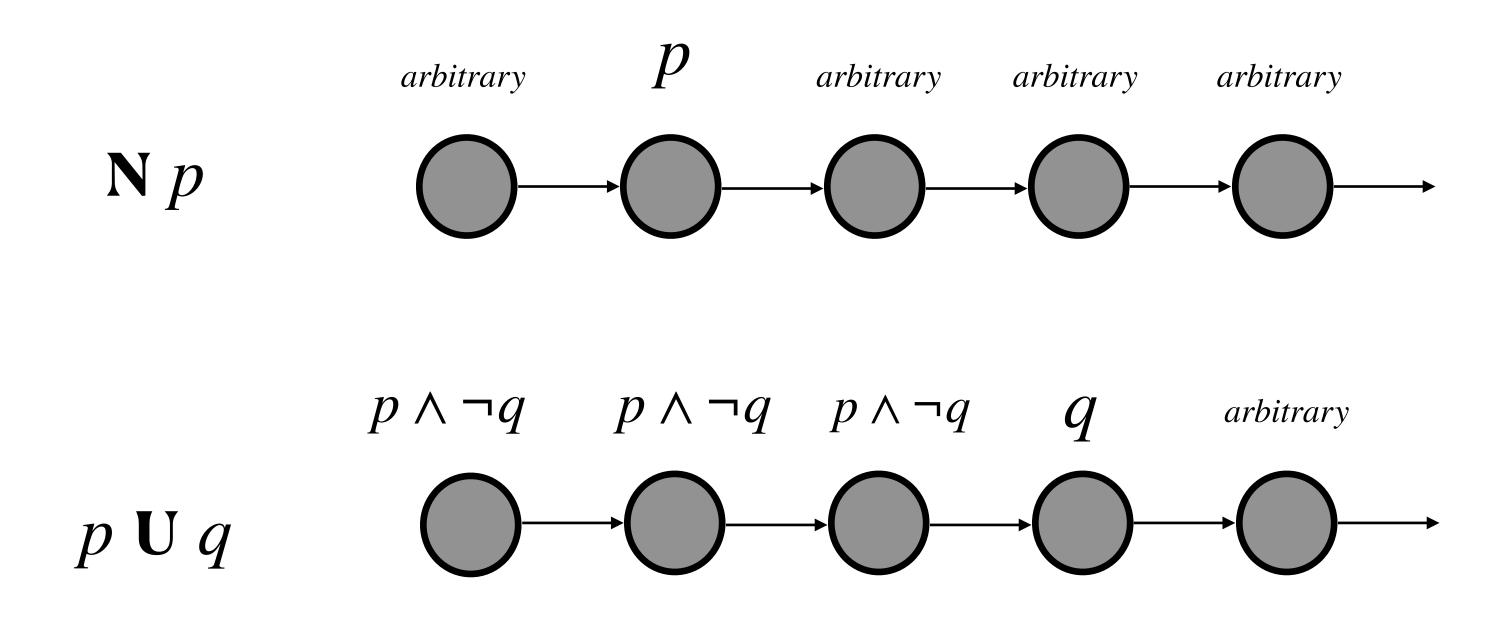
If you press the accelerator, the car will move in the next step. If you shoot the ball, the result will be known in the next step. $F = F_1 U F_2$ U is "Until". F_2 is True at "some point", and until then F_1 is True.

EmergencyLight U PowerRestored

LTL Syntax Sequence of states (paths).



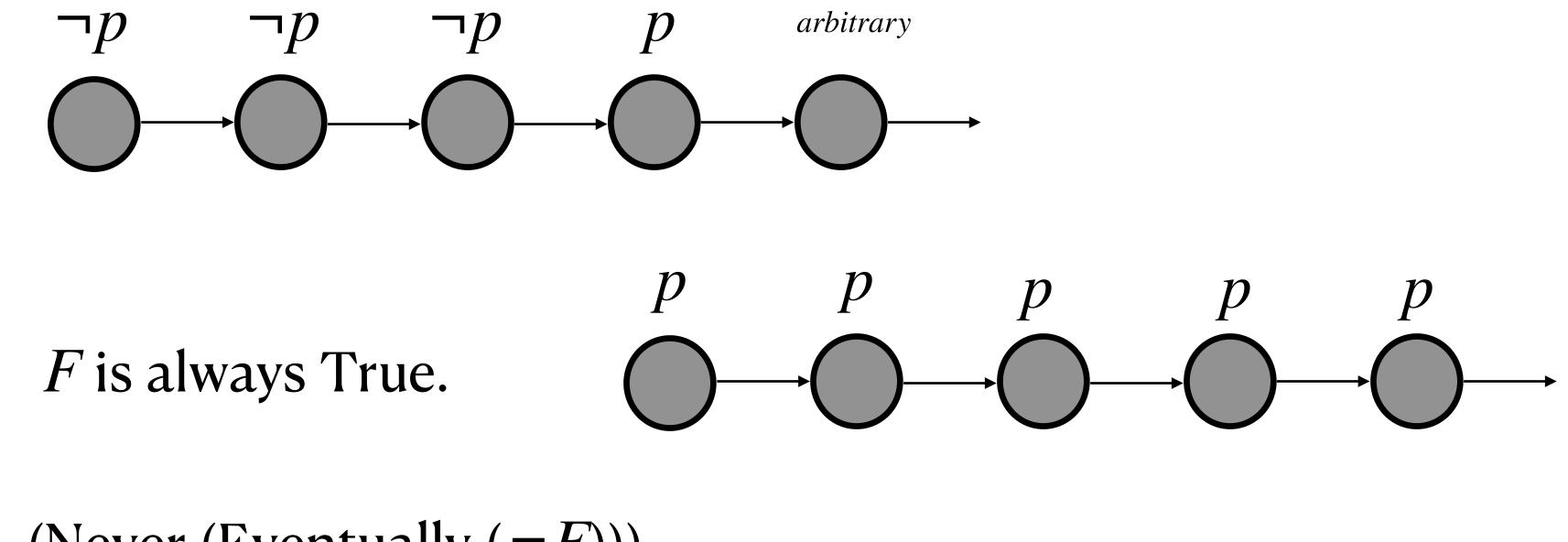
Atomic prop. P



Primary temporal operators: N U

Eventually $\langle \rangle F$ F will become true at some point in the future.

 $\Diamond F \equiv True \ \mathbf{U} F$



Always (valid) $\Box F$ F is always True.

 $\Box F \equiv \neg \Diamond \neg F$

(Never (Eventually $(\neg F)$)).

Primary temporal operators: NU

Weak Until $-F_1 extbf{W} F_2$, F_1 must remain true until F_2 becomes true, but F_2 doesn't necessarily need to become true at any point.

$F_1 \mathbf{W} F_2 \equiv (F_1 \mathbf{U} F_2) \lor (\Box F_1)$ It is considered weake F_2 to eventuallyTrue.

System is in safe mode W system is ready

It is considered weaker version of U, which requires F_2 to eventuallyTrue.

Primary temporal operators: N U

Release $-F_1 \ \mathbf{R} \ F_2$, F_2 must remain true until and including the point to become true at any point.

$$F_1 \mathbf{R} \ F_2 \equiv ((F_2 \land \neg F_1) \ \mathbf{W} \ (F_2 \land F_1))$$

where F_1 first becomes true, but F_1 doesn't necessarily need

LTL: Operator Precedence How to read **N** *p* **U** *q*?

 \neg , \Diamond , \Box , N Binds stronger than U, \land , \lor , \rightarrow , \leftrightarrow

The next state must satisfy p, and p must hold until q happens $\mathbf{N} p \mathbf{U} q \equiv ((\mathbf{N} p) \mathbf{U} q)$ $[p \lor q \equiv ([p) \lor q)]$ Either p always holds or q must hold in the current state.

Binds from right to left: $\neg Np \equiv \neg (Np)$

U Binds stronger than $\land, \lor, \rightarrow, \leftrightarrow$ $pUq \lor r \equiv (pUq) \lor r$



LTL: Common Cases

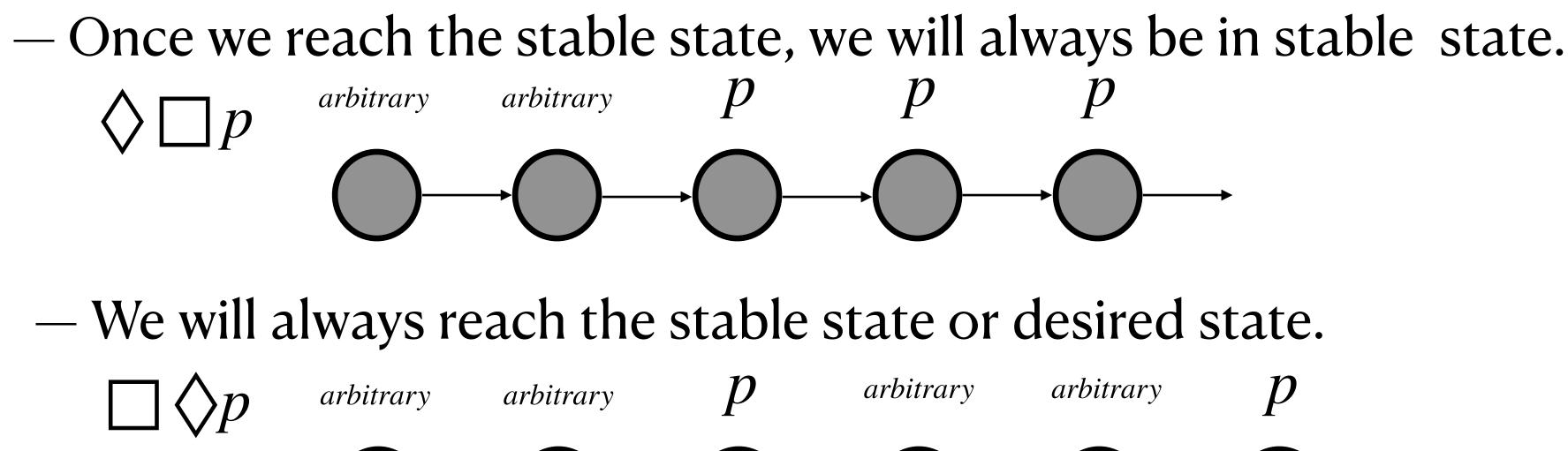
Response — If p then eventually q. $p \rightarrow \Diamond q$

Precedence $-\text{If } p \text{ then } q \text{ until } r. \quad p \rightarrow q \text{ U } r \equiv p \rightarrow (q \text{ U } r)$

Stability arbitrary $\Diamond \Box p$

— We will always reach the stable state or desired state. Progress arbitrary arbitrary *p* arbitrary

Correlation — Eventually p implies eventually q. $\Diamond p \rightarrow \Diamond q$



LTL: Formulas

Duality Law $\neg N p \equiv N \neg p$ $\neg \Diamond p \equiv \Box \neg p \qquad \neg \Box p \equiv \Diamond \neg p$ $\Box \diamondsuit \Box P \equiv \diamondsuit \Box p$ $\Diamond \Box \Diamond P \equiv \Box \Diamond p$ $(p \lor q) \equiv (p \lor q) q$ $(p \land q) \not\equiv (p \land q)$ $\Box (p \land q) \equiv \Box p \land \Box q$ $\Box p \equiv p \land (\mathbf{N} (\Box p))$

Expansion Law $p U q \equiv q \lor (p \land (N (p U q)))$

Absorption Law Distributive Law $N(p U q) \equiv ((N p) U (N q))$

 $\Diamond p \equiv p \lor (\mathbf{N} (\Diamond p))$

LTL: Examples

Traffic light is green infinitely often.

Once red, the light can't become green immediately. \Box (*red* $\rightarrow \neg N$ *green*)

Once red, the light always becomes green eventually after being yellow for some time.

If an intruder is detected, then an alert must be raised at the 3 step.

A robot must keep moving until it reaches the charging station, and once charged, it must always eventually move again.

$$\Diamond$$
 green

 $\Box(red \rightarrow (\Diamond green \land (\neg green \lor u yellow))) \qquad \Box(red \rightarrow \aleph(red \lor (yellow \land \aleph(yellow \lor u green))))$

 $\Box (IntruderDettected \rightarrow (\mathbf{N} \neg alert \land \mathbf{N} \mathbf{N} \neg alert \land \mathbf{N} \mathbf{N} \mathbf{N} alert))$

(Move U AtChargeStation) $\land \Box$ (Charged $\rightarrow \Diamond$ Move)





LTL: Examples

If an intruder is detected, then an alert must be raised at the 3 step.

always eventually move again.

$[(IntruderDettected \rightarrow (N \neg alert \land N \land N \neg alert \land N \land N \land alert))$

A robot must keep moving until it reaches the charging station, and once charged, it must

(Move U AtChargeStation) $\land \Box$ (Charged $\rightarrow \Diamond$ Move)



LTL: Semantics

We interpret our temporal formulae in a discrete, linear model of time.

time) to a set of propositions

Let $\pi = a_0, a_1, a_2, ...$ $\pi(i) = a_i$ AP at i^{th} level. $\pi^i = a_i, a_{i+1}, a_{i+2}, \dots$ Suffix of π

- $M = \langle N, I \rangle$, where N is a set of Natural number and $I: N \mapsto 2^{\Sigma}$
 - I maps each Natural number (representing a moment in

LTL: Semantics Semantics with respect to a given Trace (or Path) π

Let $\pi = a_0, a_1, a_2, \dots$ $\pi(i) = a_i$ AP at i^{th} level. $\pi^i = a_i, a_{i+1}, a_{i+2}, \dots$

 $\pi^i \models p \quad \text{Iff } p \in \pi(i)$ $\pi \models p$ Iff $p \in \pi(0)$ $\pi \models \mathbf{N} F_1 \qquad \qquad \text{Iff } \pi^1 \models F_1 \qquad \qquad \pi^i \models \mathbf{N} F \qquad \qquad \text{Iff } \pi^{i+1} \models F_1$ $\pi \models F_1 \cup F_2$ Iff $\exists j \ge 0$, $\pi^j \models F_2$, and $\pi^i \models F_1$ for all $0 \le i < j$ $\pi \models \diamondsuit F_1 \qquad \text{Iff } \exists j \ge 0, \ \pi^j \models F_1$ $\pi \models \Box F_1 \qquad \text{Iff } \forall j \ge 0, \ \pi^j \models F_1$ $\pi \models \Box \diamondsuit F_1 \quad \text{Iff } \exists^{\infty} j \ge 0, \ \pi^j \models F_1 \quad \exists^{\infty} = \forall i \ge 0, \exists j \ge i$ $\pi \models \bigotimes \Box F_1 \quad \text{Iff } \forall^{\infty} j \ge 0, \ \pi^j \models F_1 \quad \exists^{\infty} = \exists i \ge 0, \forall j \ge i$

Suffix of π

AP - is a set of atomic propositions (Boolean valued variables, predicates)

Kripke structure over AP as a 4-tuple M = (S, I, R, L)

- S = a finite set of states.
- I = a set of initial states $I \subseteq S$
- R = a transition relation $R \subseteq S \times S$
- L = a labelling function $L: S \rightarrow 2^{AP}$

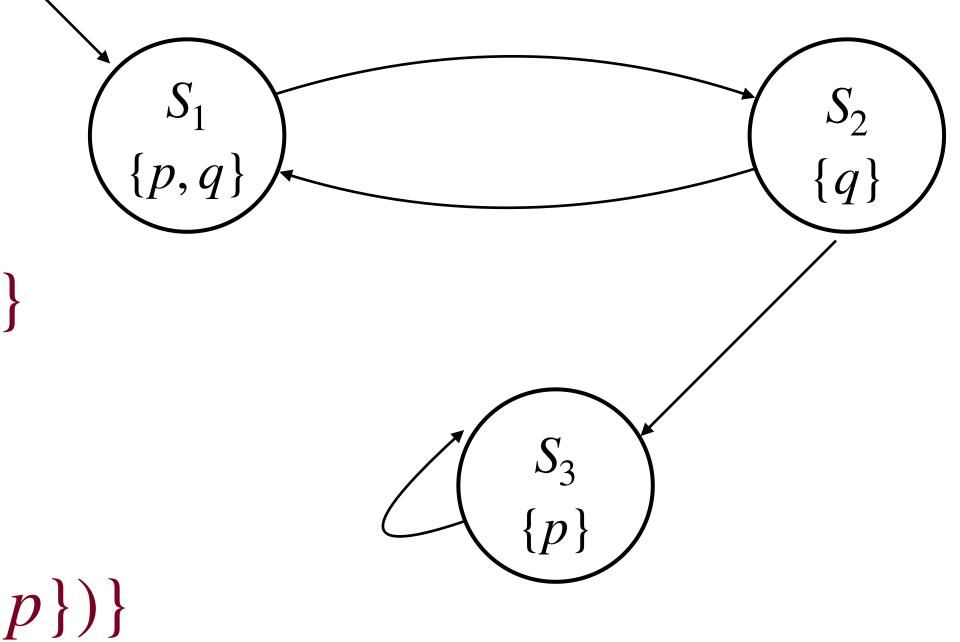
Kripke structure over AP as a 4-tuple M = (S, I, R, L)

- S = a finite set of states. $S = \{s_1, s_2, s_3\}$
- I = a set of initial states $I \subseteq S$ $I = \{s_1\}$
- R = a transition relation $R \subseteq S \times S$

 $R = \{(s_1, s_2), (s_2, s_1), (s_2, s_3), (s_3, s_3)\}$

L = a labelling function $L: S \rightarrow 2^{AP}$

 $L = \{(s_1, \{p, q\}), (s_2, \{q\}), (s_3, \{p\})\}$



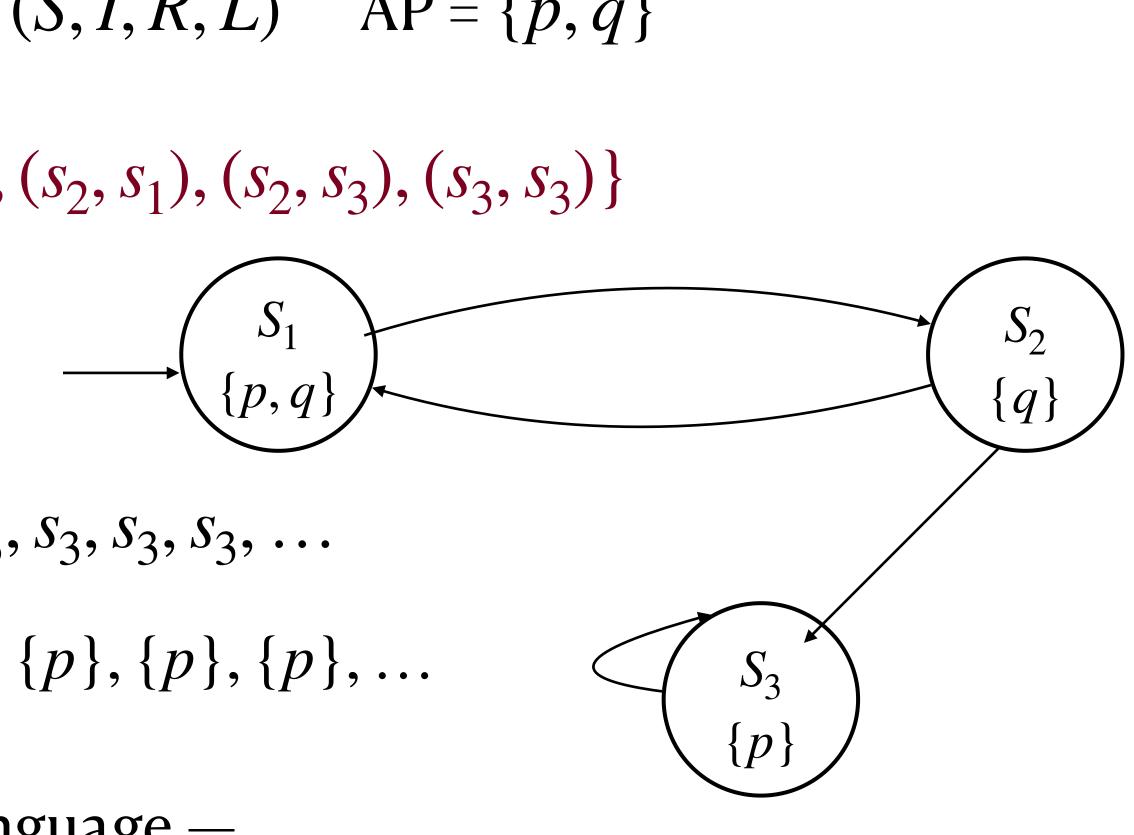
 $AP = \{p, q\}$

Kripke structure over AP as a 4-tuple M = (S, I, R, L) AP = {p, q }

- $S = \{s_1, s_2, s_3\} \quad I = \{s_1\} \quad R = \{(s_1, s_2), (s_2, s_1), (s_2, s_3), (s_3, s_3)\}$
- $L = \{(s_1, \{p, q\}), (s_2, \{q\}), (s_3, \{p\})\}$

M may produce a path $w = s_1, s_2, s_1, s_2, s_3, s_3, s_3, s_3, \dots$ $\pi^{s_1} \ \pi = \{p, q\}, \{q\}, \{p, q\}, \{q\}, \{p\}, \{p\}, \{p\}, \dots$

M can produce words belonging to the language – $(\{p,q\}\{q\})^{\omega} \cup (\{p,q\}\{q\})^{\omega}$



Given a kripke structure M and a path π in M, a state $s \in S$, and an LTL formula F:

- 1. $\langle M, \pi \rangle \models F$ iff $\pi^{s_o} \models F$, where s_o is initial state of π
- 2. $\langle M, s \rangle \models F$ iff $\langle M, \pi \rangle \models F$ for paths starting at s_o .
- 3. $\langle M \rangle \models F$. iff $\langle M, s_o \rangle \models F$ for every $s_o \in I$, where I initial states of M.

LTL: Semantics

A formula F is satisfiable if there exists at least one Kripke Structure M, and at least one initial state s_o such that:

$$< M, s_o > \models F$$

A formula F is valid if for all Kripke Structures M, and for all initial states S_{o} : $< M, s_o > \models F$

LTL model checking — Given formula F, and Kripke Structure M checks if $\langle M, s_o \rangle \models F$ holds for every initial state $s_o \in I$

Course Webpage



Thanks!