COL:750

Foundations of Automatic Verification

Course Webpage

https://priyanka-golia.github.io/teaching/COL-750/index.html

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Model Checking using Interpolants

Inductive Invariants

- Post-image (Q) = { $s' | \exists s \in Q . T(s, s')$ }
- Inductive invariant (I_s) for $\forall \Box p$
 - 1. I_{c} must include the set of initial states, $I \subseteq I_{c}$
 - 2. I_s must not include a state that is labeled with $\neg p$, $\forall s \in I_s$, $s \models p$
 - 3. I_s must be closed under transition relation, post-image(I_s) $\subseteq I_s$ holds.

If there exists a inductive invariant for $\forall \Box P$, then $M \models \forall \Box p$

Model Checking using Interpolants

Can you use interplants to compute inductive invariants?

- 1. Constructs an over-approximation of the reachable states
- 2. Terminates when it finds an inductive invariant or a counterexample

Actual reachable set: R

- Over-approximation $(O_p): R \to O_p$
- 1. Proofs on over-approximation holds.
- 2. Counterexample can be spurious.
- Under-approximation $(U_p): U_p \to R$
- 1. Proofs on over-approximation can be spurious.
- 2. Counterexample holds



Model Checking using Interpolants

General idea:

1. Perform BMC

2. If BMC is UNSAT:

Iteratively compute and refine an overapproximation of states reachable in K steps.

> Compute Interpolant as over-approximation. If interpolant is inductive Return True.

else

use interpolant to over-approximate.

If BMC is SAT: 3.

Check if over-approximation is same as initial states

otherwise increase K.

procedure CraigReachability(model $M, p \in AP$) if $S_0 \land \neg p$ is SAT return " $M \not\models AG p$ "; k := 1; $Q := S_0;$ while *true* do $A := Q(s_0) \wedge R(s_0, s_1);$ $B := \bigwedge_{i=1}^{k-1} R(s_i, s_{i+1}) \land \bigvee_{i=1}^k \neg p(s_i);$ if $A \wedge B$ is SAT then if $Q = S_0$ then return " $M \not\models AG p$ "; Increase *k* $Q := S_0$ else compute interpolant *I* for *A* and *B* if $I \subseteq Q$ then return " $M \models AG p$ "; $Q := Q \cup I$ end if end while end procedure



Inductive Trace

- An Inductive trace of a transition system T is a sequence of formula $[F_0, \ldots, F_K]$ such that:
- 1. $I \rightarrow F_o$ 2. $\forall i \in [o, \dots, K], F_i(s) \land T(s, s') \rightarrow F_{i+1}(s')$
- Example: state variables {*a*, *b*} initial condition $I = \neg a \land \neg b$ transition function. *next* a = b *next* b = a

Let
$$F_o = I = \neg a \land \neg b$$
 $(\neg a_o \land \neg b_o) \land (\neg a_o \land (\neg a_o \land \neg b_o) \land (\neg a_o \land (\neg a_o \land a_o) \land (\neg a_o \land (\neg a_o \land a_o) \land (\neg a_o \land (\neg a_o \land (\neg a_o \land a_o)) \land (\neg a_o \land (\neg a_o$

Interpolant $\neg b_1$ $F_o \wedge T(s_o, s_1) \rightarrow \neg b_1$

Checking for property $\forall \Box \neg b$ Reachability to a state with b UNSAT $(a_1 \leftrightarrow b_o) \land (b_1 \leftrightarrow a_o) \land b_1$ B $F_1 = \neg b$



Inductive Trace

An Inductive trace of a transition system T is a sequence of formula $[F_o, \ldots, F_K]$ such that:

 $I \to F_o$ $\forall i \in [o, \dots, k-1], F_i(s) \land T(s, s') \rightarrow F_{i+1}(s')$

A Trace is *Good* iff $\forall i, F_i \rightarrow \neg Bad$

A Trace is *Monotone* iff $\forall i, F_i \subseteq F_{i+1}$

A Trace is *Closed* iff $\exists 1 \leq i \leq K, F_i \rightarrow (F_i)$

A transition system T is called SAFE if and only if it admits a good, monotone, closed trace.

For all F_i , property doesn't hold True!!!

Monotonicity ensures that as time progresses, we do not "forget" any reachable state It aligns with the notion that reachable states can only grow (never shrink) as time increases

$$F_o \vee \ldots \vee F_{i-1})$$

Each F_i is called Frames

The goal is to find an inductive invariant

An Inductive trace of a transition system T is a sequence of formula $[F_0, \ldots, F_K]$ such that:

1. $I \rightarrow F_o$ 2. $\forall i \in [o, \dots, K], F_i(s) \land T(s, s') \rightarrow F_{i+1}(s')$

- By learning inductive facts incrementally

A trace called clausal if every F_i is in CNF.





Overapproximation of states reachable from F_o in 1 transition.

Overapproximation of states reachable from F_1 in 1 transition.







Overapproximation of states reachable from F_o in 1 transition.

Overapproximation of states reachable from F_1 in 1 transition.





Overapproximation of states reachable from F_o in 1 transition.

Overapproximation of states reachable from F_1 in 1 transition.

state



IC3 : Incremental Construction of Inductive Clauses for Indubitable Correctness. If $s_o - > s_1 - > Badstate$ states Initial states • Fo FI F2,

Then found a counter example!!

Overapproximation of states reachable from F_o in 1 transition.

Overapproximation of states reachable from F_1 in 1 transition.





What if there doesn't exist a transition from $s_o - > s_1$?

states

Overapproximation of states reachable from F_o in 1 transition.

Overapproximation of states reachable from F_1 in 1 transition.





What if there doesn't exist a transition from $s_o - > s_1$?



Example: state variables {*a*, *b*} Checking for property $\forall \Box \neg b$ initial condition $I = \neg a \land \neg b$ Reachability to a state with b transition function. *next* a = b *next* b = aUNSAT $(a_1 \leftrightarrow b_o) \land (b_1 \leftrightarrow a_o) \land b_1$ R Interpolant $\neg b_1$ $F_o \wedge T(s_o, s_1) \rightarrow \neg b_1$ $F_1 = \neg b$

 $F_1 \wedge T(s_1, s_2) \wedge b_2$ SAT $\neg b_1 \land (a_2 \leftrightarrow b_1) \land (b_2 \leftrightarrow a_1) \land b_2$

From F_1 in one transition bad state is reachable!!!

 $\sigma: \langle a_1 = 1, b_1 = 0, a_2 = 0, b_2 = 1 \rangle$



Example: state variables {*a*, *b*} Checking for property $\forall \Box \neg b$ initial condition $I = \neg a \land \neg b$ Reachability to a state with b transition function. *next* a = b *next* b = a





We need to check if s_1 is reachable from F_{α}

$$b_1 \wedge (a_2 \leftrightarrow b_1) \wedge (b_2 \leftrightarrow a_1) \wedge b_2$$

$$\sigma : \langle a_1 = 1, b_1 = 0, a_2 = 0, b_2 = 1 \rangle$$

$$= a_1 \wedge \neg b_1$$

We extract state s_1 from $\sigma \models F_1 \land T(s_1, s_2) \land b$



Example: state variables {*a*, *b*} initial condition $I = \neg a \land \neg b$ transition function. *next* a = b *next* b = a

$$F_o = \neg a_o \wedge \neg b_o \qquad F_1^{old} = \neg b_1 \qquad s_1 =$$



Checking for property $\forall \Box \neg b$ Reachability to a state with b

We need to check if s_1 is reachable from F_o $= a_1 \wedge \neg b_1$

$$\neg b_o \land (a_1 \leftrightarrow b_o) \land (b_1 \leftrightarrow a_o) \land (a_1 \land \neg b_1)$$
UNSAT

 s_1 is not reachable from F_{α}

We need to block s_1 from F_1







Example: state variables {*a*, *b*} initial condition $I = \neg a \land \neg b$ transition function. *next* a = b *next* b = a

$$F_o = \neg a_o \wedge \neg b_o \qquad F_1^{old} = \neg b_1 \qquad s_1$$



Checking for property $\forall \Box \neg b$ Reachability to a state with *b*

 s_1 is not reachable from F_o $= a_1 \wedge \neg b_1$ We need to block s_1 from F_1

$$\begin{split} F_1 &= F_1^{old} \wedge \neg (a_1 \wedge \neg b_1) \\ F_1 &= F_1^{old} \wedge (\neg a_1 \vee b_1) \\ F_1 &= \neg b_1 \wedge (\neg a_1 \vee b_1) \end{split} \text{BlockClause c} \end{split}$$



When to stop?



How to update "new" information?



$$\exists i F_i = F_{i+1}$$

A transition system T is called SAFE if and only if it admits a good closed trace.

Or, found a counter example

Do we need to update F_3, \ldots, F_i ? Do we need to update F_1 ?





A Trace is *Monotone* iff $\forall i, F_i \subseteq F_{i+1}$

Monotonicity $-S_2$ is appearing in the later frames as well!!

Then, should we block S_2 from all later frames?

Do we need to update F_3, \ldots, F_i ?





A Trace is *Monotone* iff $\forall i, F_i \subseteq F_{i+1}$



- S_2 is appearing in the later frames as well!!
 - Then, should we block *S*₂ from all later frames?

- <- what about this case?
- $\forall i: F_i(s) \land T(s, s') \to F_{i+1}(s')$

 $S_2 \in F_i$ Then, we can't block it from F_i !!!



How to update "new" information?





Longer Cex may be there!! Block S_2 from F_i But, can't block S_2 from F_i Do we need to update F_3, \ldots, F_i ?

Blocking clause for S_2 is c.

Bad

s stat co.

For $j \in [2,K]$ If $F_j \wedge T \to \neg c$, i.e. $SAT\{F_j \wedge T \wedge c\}$ Bad state Then Stop Else

$$F_j \leftarrow F_j \land \neg c$$





How to update "new" information?



Bad

> stat co.



Longer Cex may be there!! Block S_2 from F_i But, can't block S_2 from F_i Do we need to update F_3, \ldots, F_i ?

PushForward (F, K, i) { For $j \in [i, K]$ For every clause c in F_i Bad State If $F_j \wedge T \to \neg c$, i.e. $SAT\{F_j \wedge T \wedge c\}$ Then continue Else $F_j \leftarrow F_j \land \neg c$ Ĵ







A Trace is *Monotone* iff $\forall i, F_i \subseteq F_{i+1}$ Block Clause: *c*

Now, we have updated $F_2 = F_2^{old} \wedge c!$ Is still the case $F_1 \subseteq F_2$

Yes, because S_2 was anyway not reachable from F_1 , that is, $S_2 \notin F_1$!!

Do we need to update F_1 ?

How to update "new" information?

No harm in blocking



How to update No harm in "new" No harm in blocking information? $S_i, S_j, S_{1j}, S_{2,j}$ blocking S_i from F_i from F_2 S2 $\left(S_{1}\right)$ ` مرک) Si° S_{12} *_____* 522 F,° F Fj F2 We can We block We can also S_2, S_{12}, S_{22} also block block S_i from F_2 S_j, S_{1j} from from F_i

Bad state

BackwordPropogration(F,T,s,i) While CheckSAT{ $F_i \wedge T \wedge s$ } do: $s_i \leftarrow \text{predecessor of } s \text{ extracted}$ from satisfying assigned For $j \in [0,i]$ $F_j \leftarrow F_j \land \neg s_i$ BackwordPropogration(F, T, s_i , i - 1)



How to update No harm in "new" No harm in blocking information? $S_i, S_j, S_{1j}, S_{2,j}$ blocking S_i from F_i from F_2 S2 $\left(S_{1}\right)$ مرک Si° 512 (کر ا S22 F,° F Fj F2 We can We block We can also S_2, S_{12}, S_{22} also block block S_i from F_2 S_j, S_{1j} from from F_i

BackwordPropogration(F,T,s,i) While CheckSAT{ $F_i \land T \land s$ } If i = 0: found CEX Return Bad state $s_i \leftarrow \text{predecessor of } s \text{ extracted}$ from satisfying assigned For $j \in [0,i]$ $F_i \leftarrow F_i \land \neg s_i$ BackwordPropogration(F, T, s_i , i - 1)







 $T(a, b, c, a', b', c') = (a' \leftrightarrow b) \land (b' \leftrightarrow c)$

 $\forall \Box \neg a \lor \neg b \lor \neg c$