# COL:750

# **Foundations of Automatic Verification**

Course Webpage

https://priyanka-golia.github.io/teaching/COL-750/index.html

## Instructor: Priyanka Golia



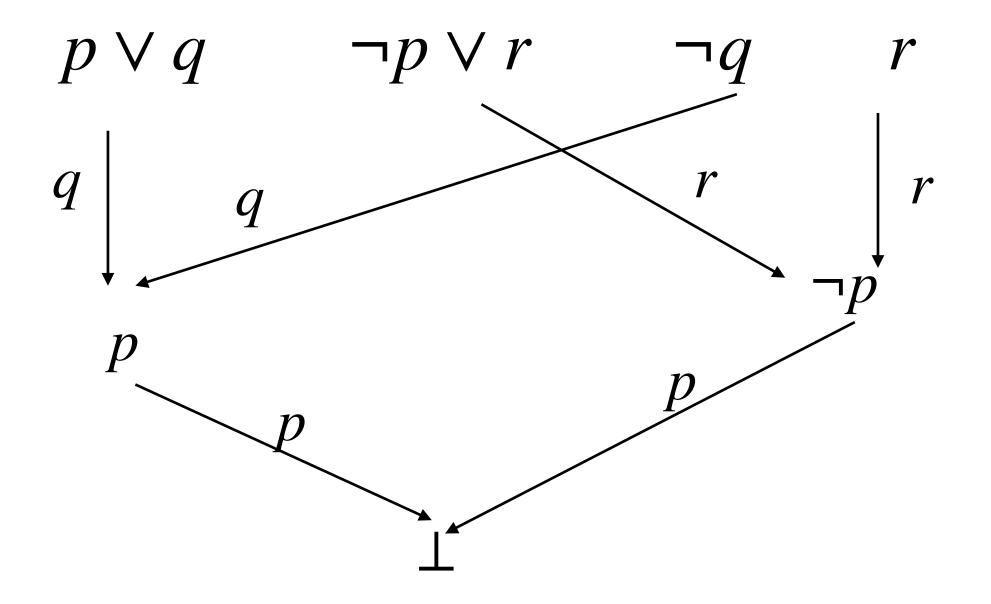
## Compute Interpolants

$$A = (p \lor q) \land (\neg p \lor r) \qquad B$$

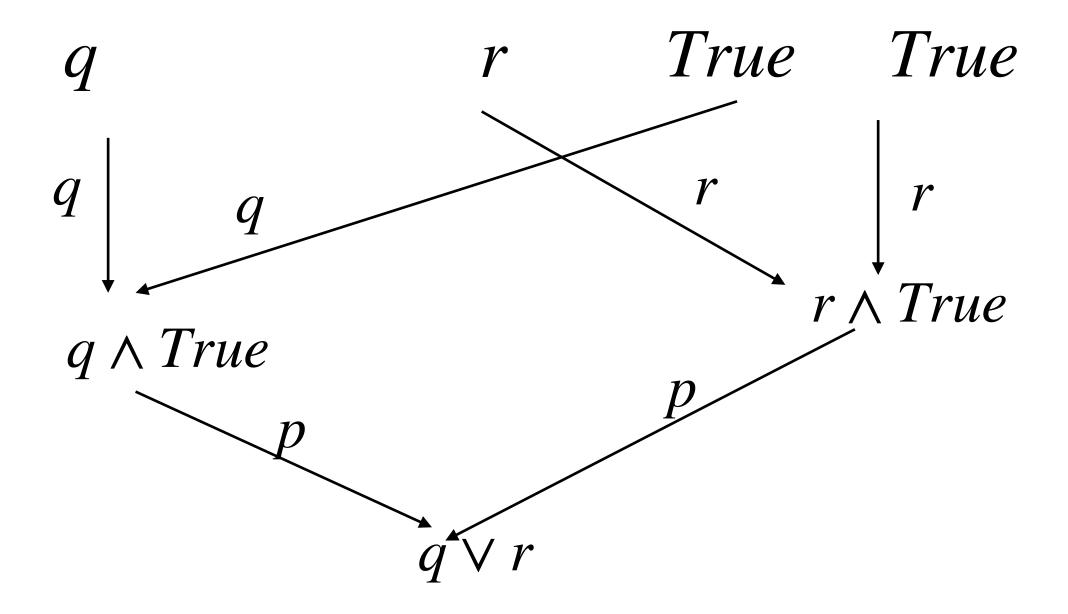
### $= \neg q \land \neg r$

### Compute Interpolants

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 $= \neg q \land \neg r$ 



Inductive Invariants

- Post-image (Q) = { $s' | \exists s \in Q . T(s, s')$ }
- Inductive invariant ( $I_s$ ) for  $\forall \Box p$ 
  - 1.  $I_{c}$  must include the set of initial states,  $I \subseteq I_{c}$
  - 2.  $I_s$  must not include a state that is labeled with  $\neg p$ ,  $\forall s \in I_s$ ,  $s \models p$
  - 3.  $I_s$  must be closed under transition relation, post-image( $I_s$ )  $\subseteq I_s$  holds.

If there exists a inductive invariant for  $\forall \Box P$ , then  $M \models \forall \Box p$ 

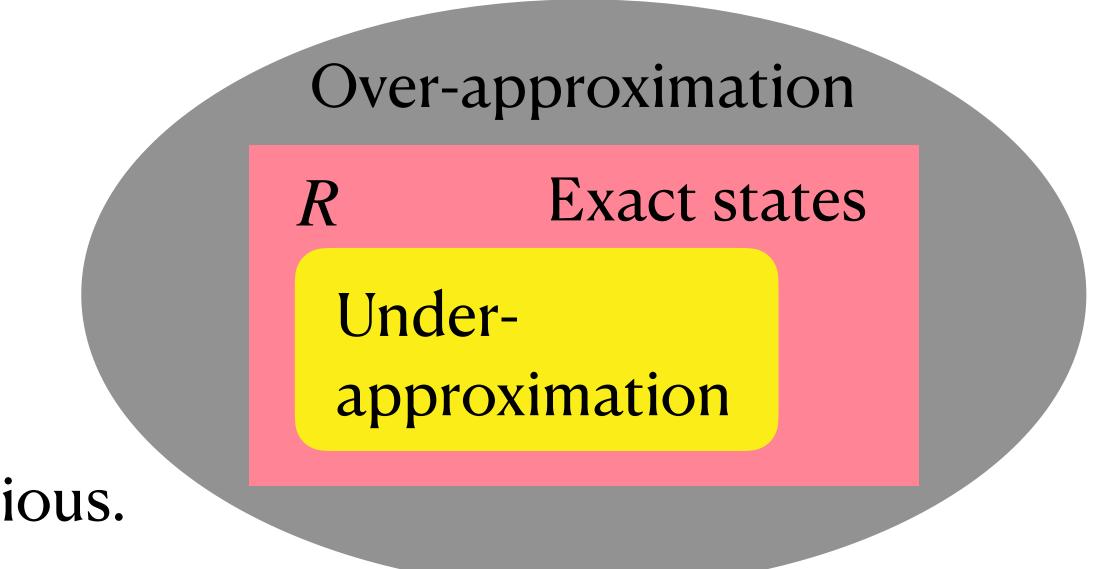
Can you use interplants to compute inductive invariants?

Can you use interplants to compute inductive invariants?

- 1. Constructs an over-approximation of the reachable states
- 2. Terminates when it finds an inductive invariant or a counterexample

Actual reachable set: R

- Over-approximation  $(O_p): R \to O_p$
- 1. Proofs on over-approximation holds.
- 2. Counterexample can be spurious.
- Under-approximation  $(U_p): U_p \to R$
- 1. Proofs on over-approximation can be spurious.
- 2. Counterexample holds



- General idea:
- 1. Perform BMC
- 2. If BMC is UNSAT:

Iteratively compute and refine an over-approximation of states reachable in K steps.

3. If BMC is SAT:

Check if over-approximation is same as initial states otherwise increase K.

General idea:

- 1. Perform BMC
- 2. If BMC is UNSAT:

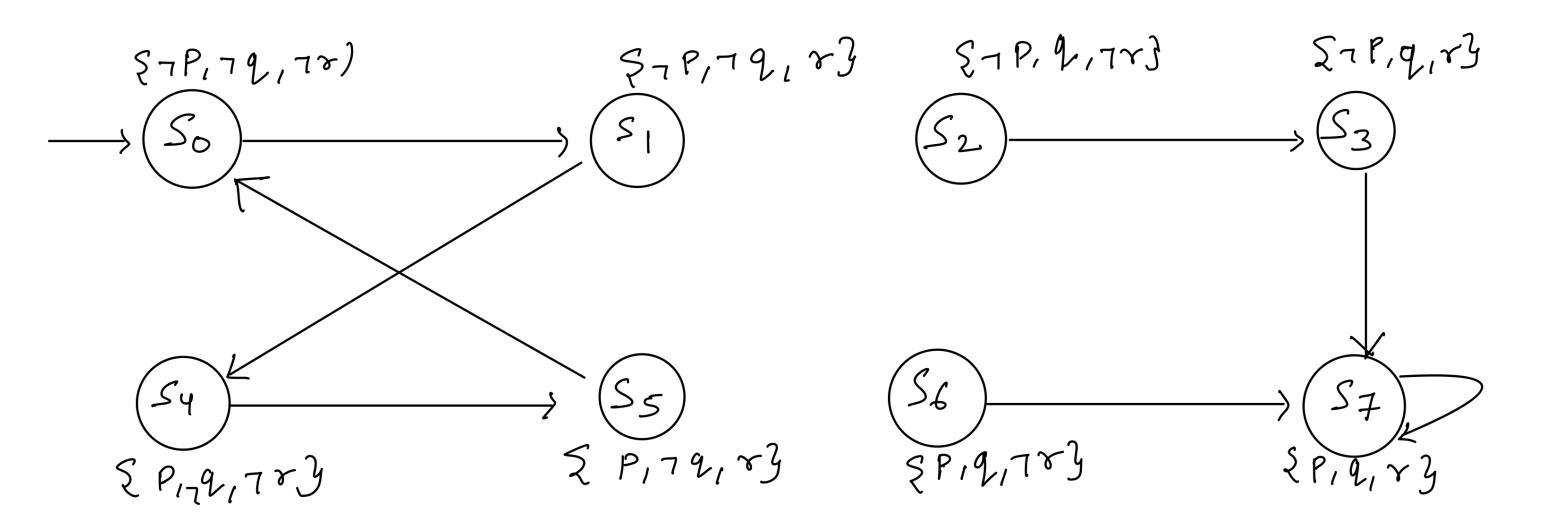
Iteratively compute and refine an over-approximation of states reachable in K steps.

Compute Interpolant as over-approximation. If interpolant is inductive Return True. use interpolant to over-approximate.

else

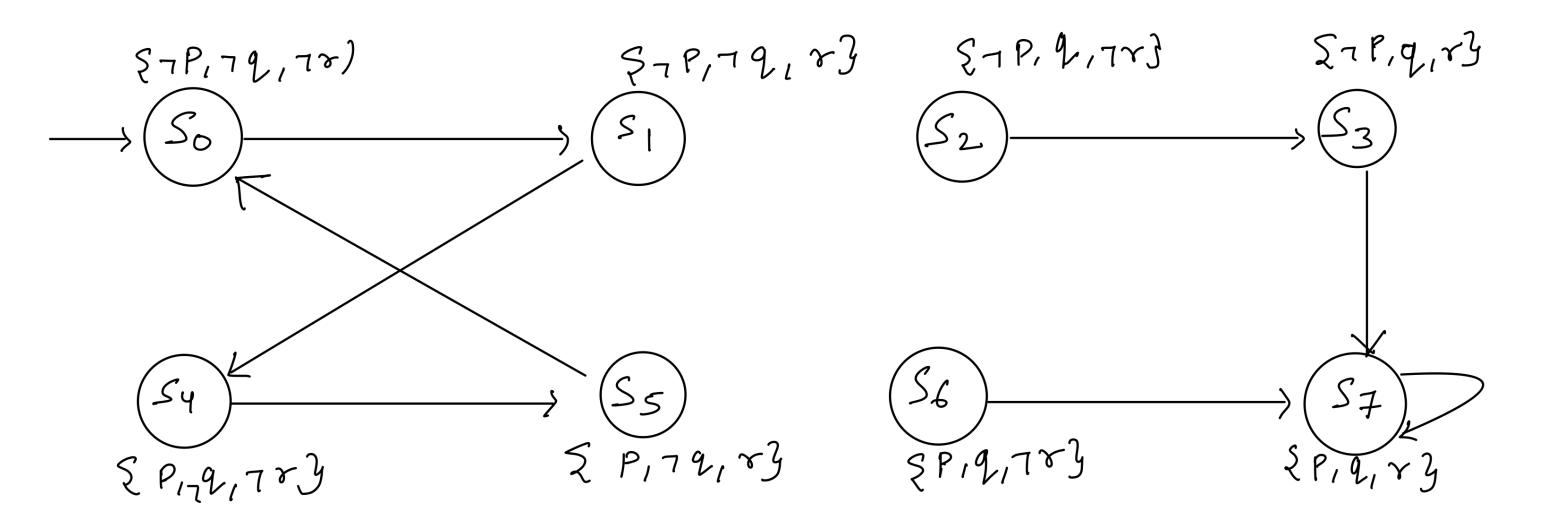
BMC is SAT:

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Reachability analysis — can we reach to state where  $p \land q \land r$  holds initial states?

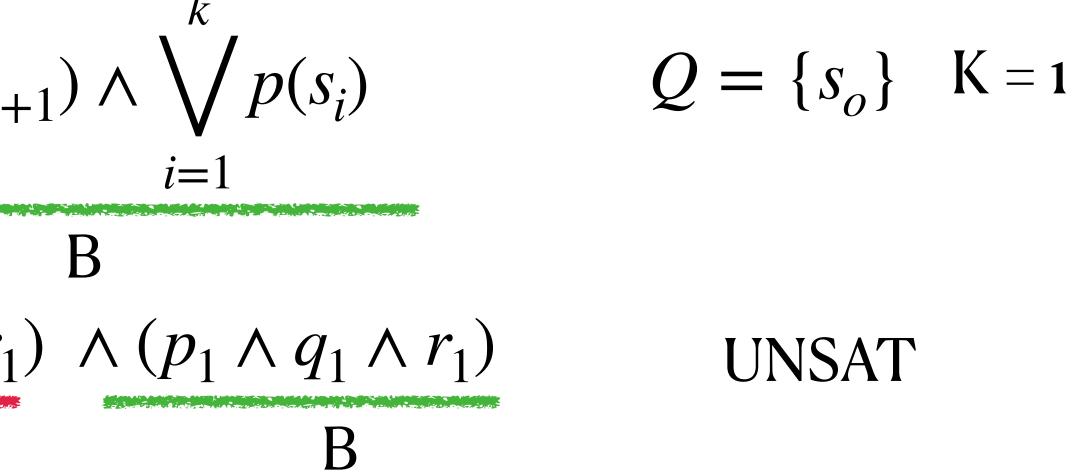
1. Does initial state is a bad state?  $CheckSAT\{s_o \land p_o\}$   $(\neg p_o \land \neg q_o \land \neg r_o) \land (p_o \land q_o \land r_o)$ UNSAT – good to go!

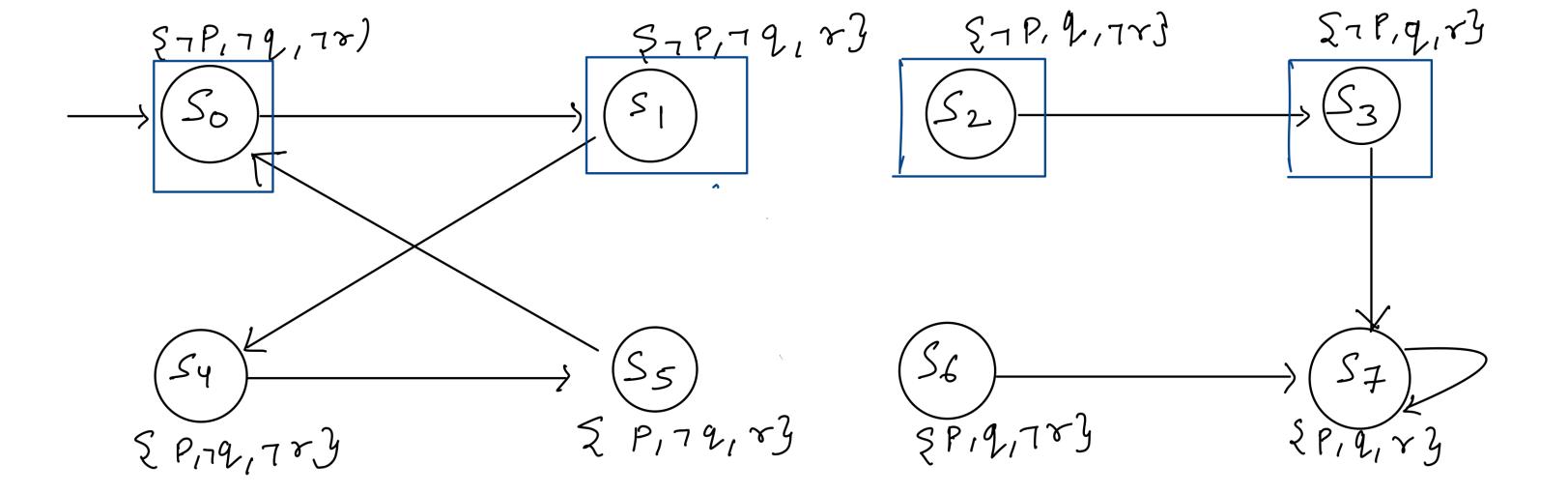


Reachability analysis — can we reach to state where  $p \land q \land r$  holds initial states?

 $Q(s_o) \wedge T(s_o, s_1) \wedge \bigwedge^{k-1} T(s_i, s_{i+1}) \wedge \bigvee^k p(s_i)$ i=1 $(\neg p_o \land \neg q_o \land \neg r_o) \land (\neg p_1 \land \neg q_1 \land r_1) \land (p_1 \land q_1 \land r_1)$ 

A





Reachability analysis — can we reach to state where  $p \land q \land r$  holds initial states?

$$(\neg p_o \land \neg q_o \land \neg r_o) \land (\neg p_1 \land \neg q_1 \land r_o)$$
A

Interpolant :=  $\neg p_1$ 

 $I_{S} = \{s_{o}, s_{1}, s_{2}, s_{3}\}$ 

 $I_s: \{s \mid I \in L(s)\}$ 

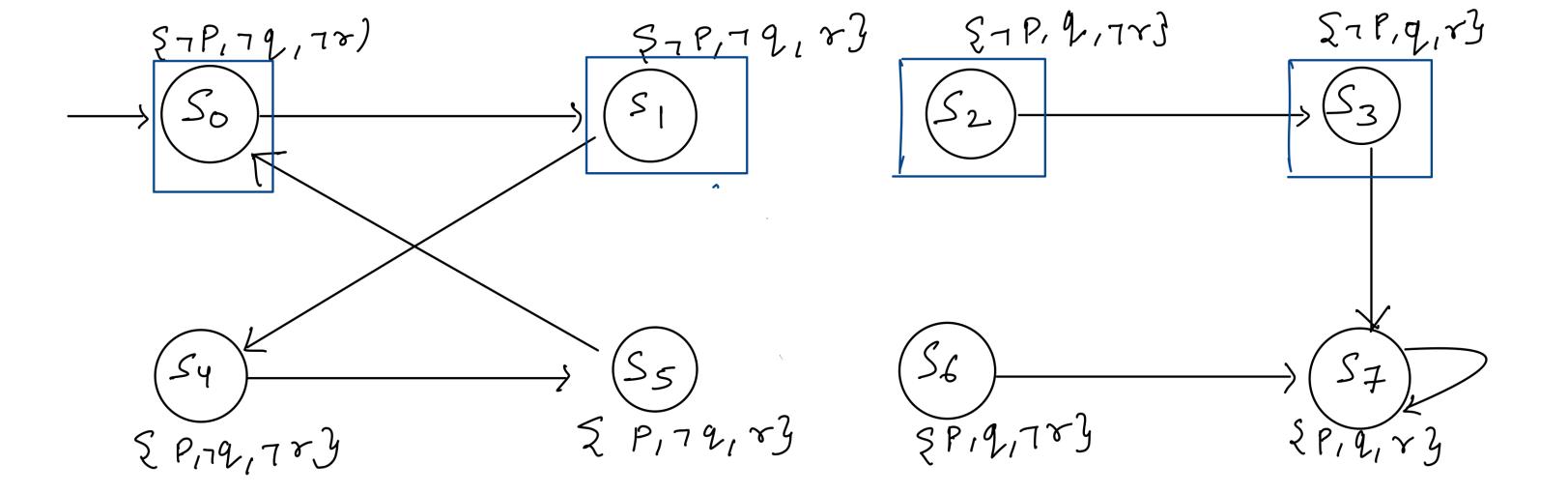
 $\wedge (p_1 \wedge q_1 \wedge r_1)$  $(r_1)$ 

B

UNSAT

 $Q = Q \cup I_{s}$ 

Check the reachability with Over-approximate set



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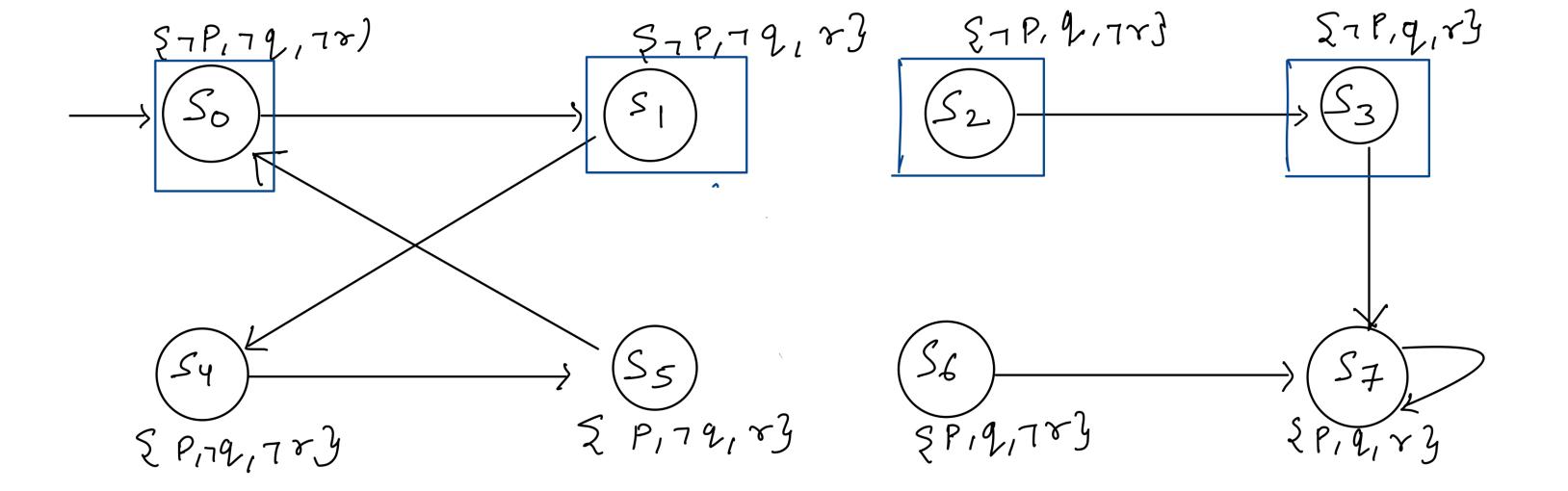
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UNSAT

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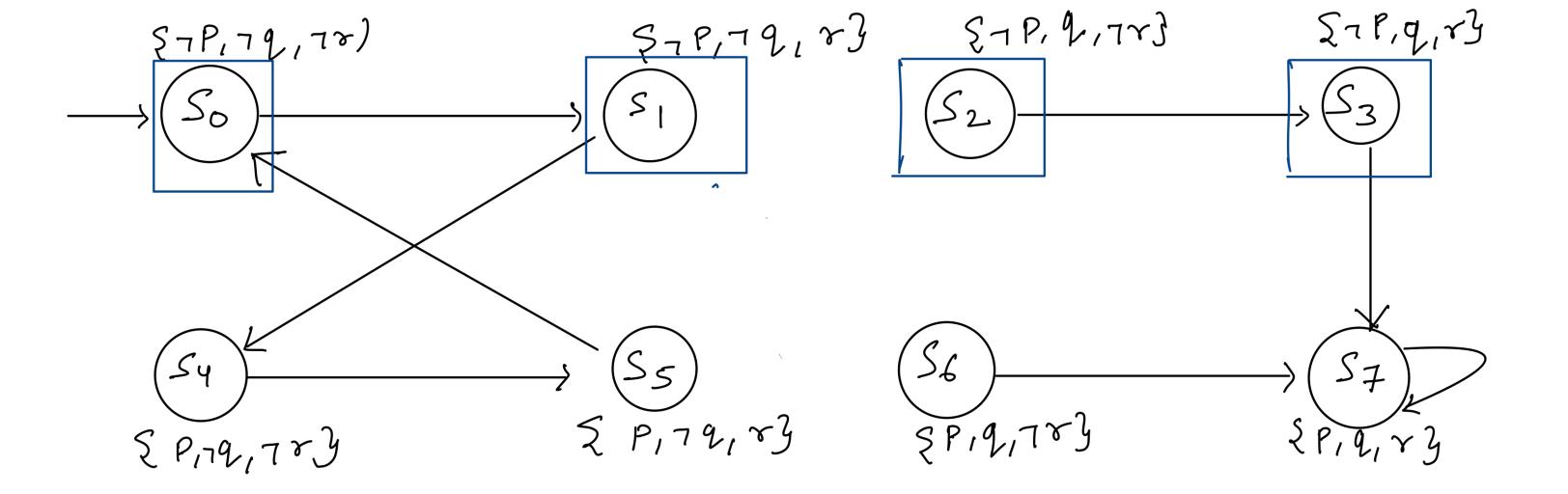


Reachability analysis — can we reach to state where  $p \land q \land r$  holds initial states?

Check the reachability with  $Q = Q \cup I_{s}$ Over-approximate set

Is Q an inductive invariant? No! post-image( $s_1$ )  $\notin Q$ 

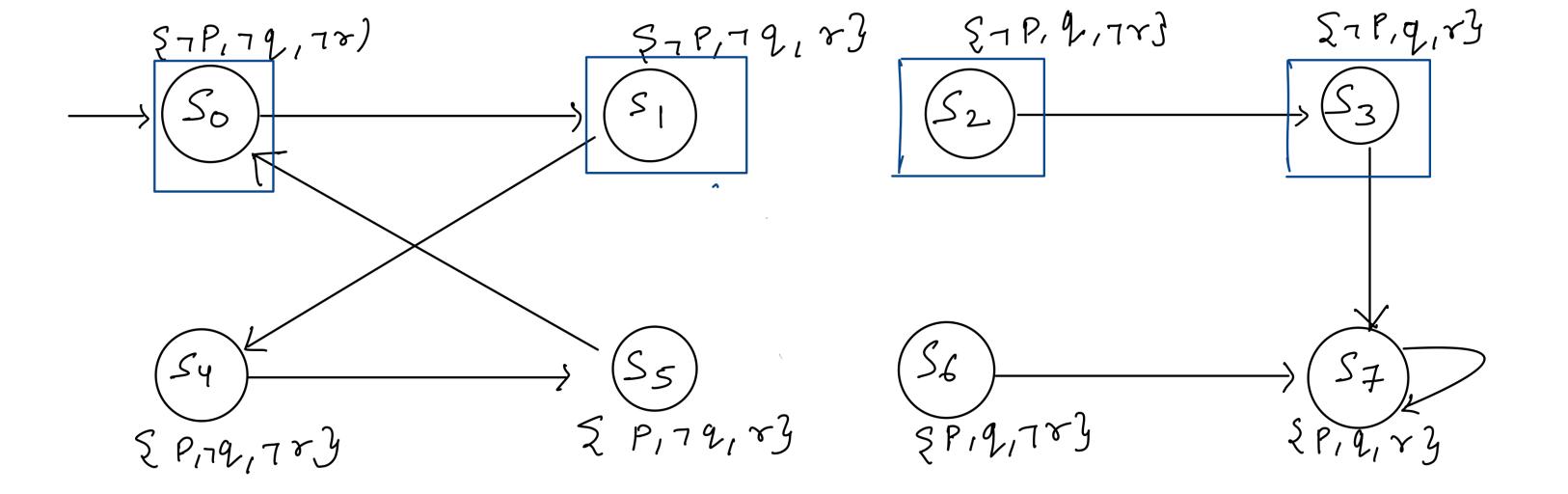
$$Q = \{s_o, s_1, s_2, s_3\}$$



Reachability analysis — can we reach to state where  $p \land q \land r$  holds initial states?

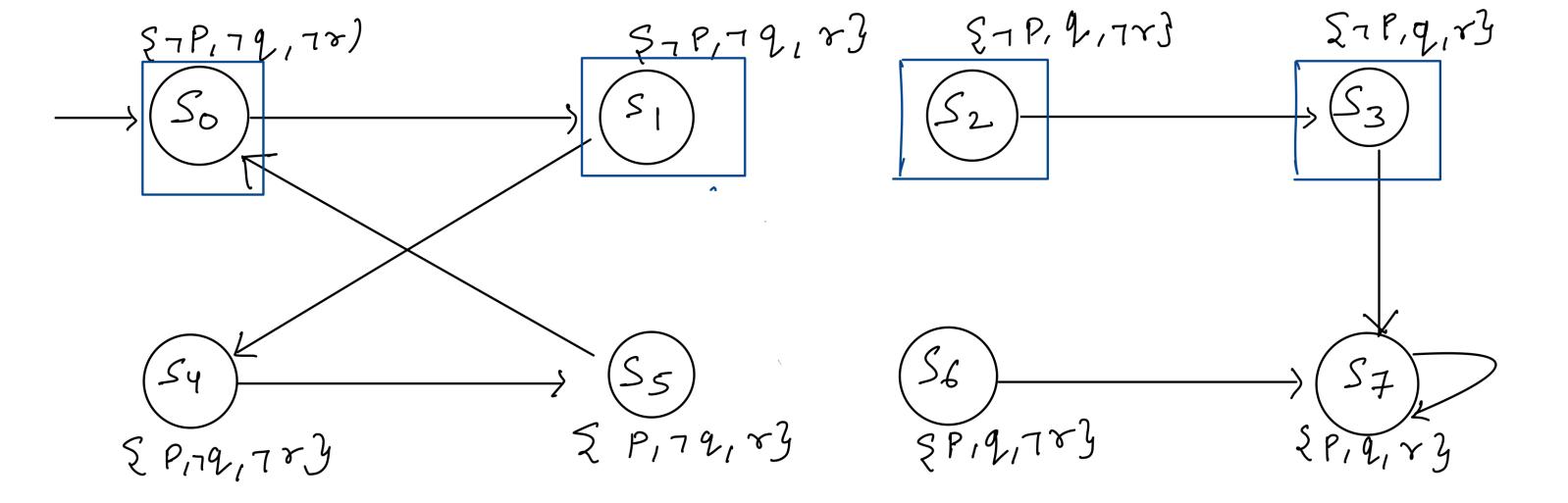
 $Q = \{s_o, s_1, s_2, s_3\} \qquad Q(s_o) \wedge T(s_o, s_1) \wedge \bigwedge^{k-1}$ A

$$\sum_{i=1}^{l} T(s_i, s_{i+1}) \wedge \bigvee_{i=1}^{k} p(s_i)$$
B



Reachability analysis — can we reach to state where  $p \land q \land r$  holds initial states?

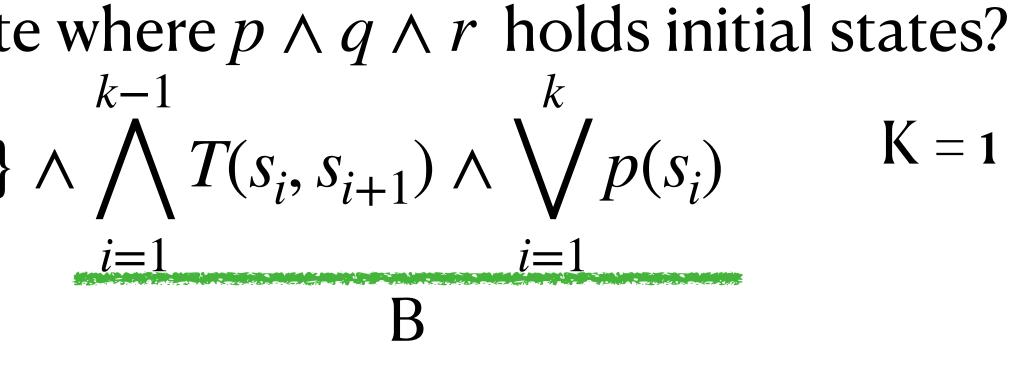
$$Q = \{s_o, s_1, s_2, s_3\} \bigvee_{\forall s \in Q} \{Q(s_o) \land T(s_o, s_1)\} \land \bigwedge_{i=1}^{k-1} T(s_i, s_{i+1}) \land \bigvee_{i=1}^k p(s_i)$$
A  
B

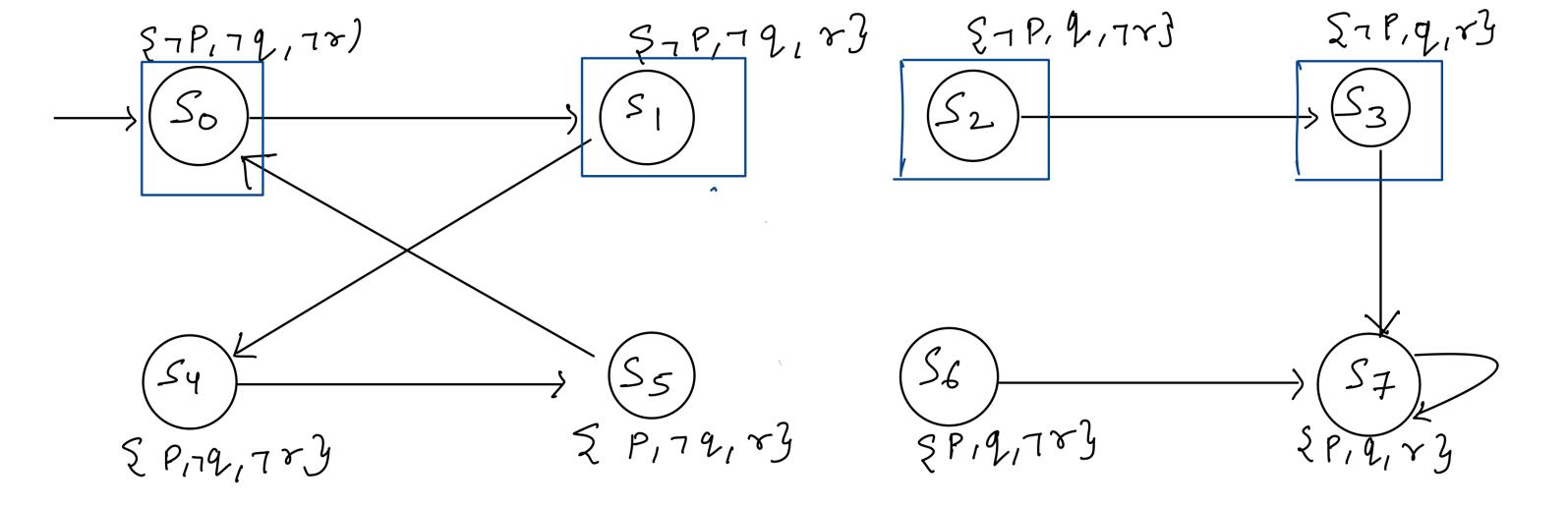


Let us consider the above example: Look carefully at the labelling function.  $F = \forall \Box \neg (p \land q \land r)$ . Only Bad state is  $S_7$ Reachability analysis — can we reach to state where  $p \land q \land r$  holds initial states?  $Q = \{s_o, s_1, s_2, s_3\} \quad \bigvee \{Q(s_o) \land T(s_o, s_1)\} \land \bigwedge^{k-1} T(s_i, s_{i+1}) \land \bigvee^k p(s_i)$  $\forall s \in O$ A

 $A = [(\neg p_o \land \neg q_o \land \neg r_o) \land (\neg p_1 \land \neg q_1 \land r_1)] \lor [(\neg p_o \land \neg q_o \land r_o) \land (p_1 \land \neg q_1 \land \neg r_1)] \lor [(\neg p_o \land q_o \land \neg r_o) \land (\neg p_1 \land q_1 \land r_1)] \lor [(\neg p_o \land q_o \land r_o) \land (p_1 \land q_1 \land r_1)] \lor [(\neg p_o \land q_o \land \neg r_o) \land (\neg p_1 \land q_1 \land r_1)] \lor [(\neg p_o \land q_o \land r_o) \land (p_1 \land q_1 \land r_1)] \lor [(\neg p_o \land q_o \land \neg r_o) \land (\neg p_1 \land q_1 \land r_1)] \lor [(\neg p_o \land q_o \land r_o) \land (p_1 \land q_1 \land r_1)] \lor [(\neg p_o \land q_o \land \neg r_o) \land (\neg p_1 \land q_1 \land r_1)] \lor [(\neg p_o \land q_o \land r_o) \land (p_1 \land q_1 \land r_1)] \lor [(\neg p_o \land q_o \land \neg r_o) \land (\neg p_1 \land q_1 \land r_1)] \lor [(\neg p_o \land q_o \land r_o) \land (p_1 \land q_1 \land r_1)] \lor [(\neg p_o \land q_o \land q_o \land q_o \land r_o) \land (p_1 \land q_1 \land r_1)] \lor [(\neg p_o \land q_o \land q_$ 

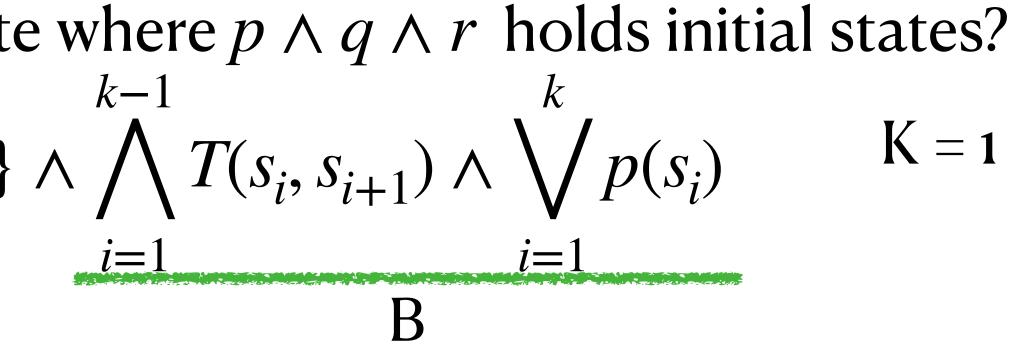
 $A \wedge B$  is SAT.  $B = (p_1 \land q_1 \land r_1)$ 



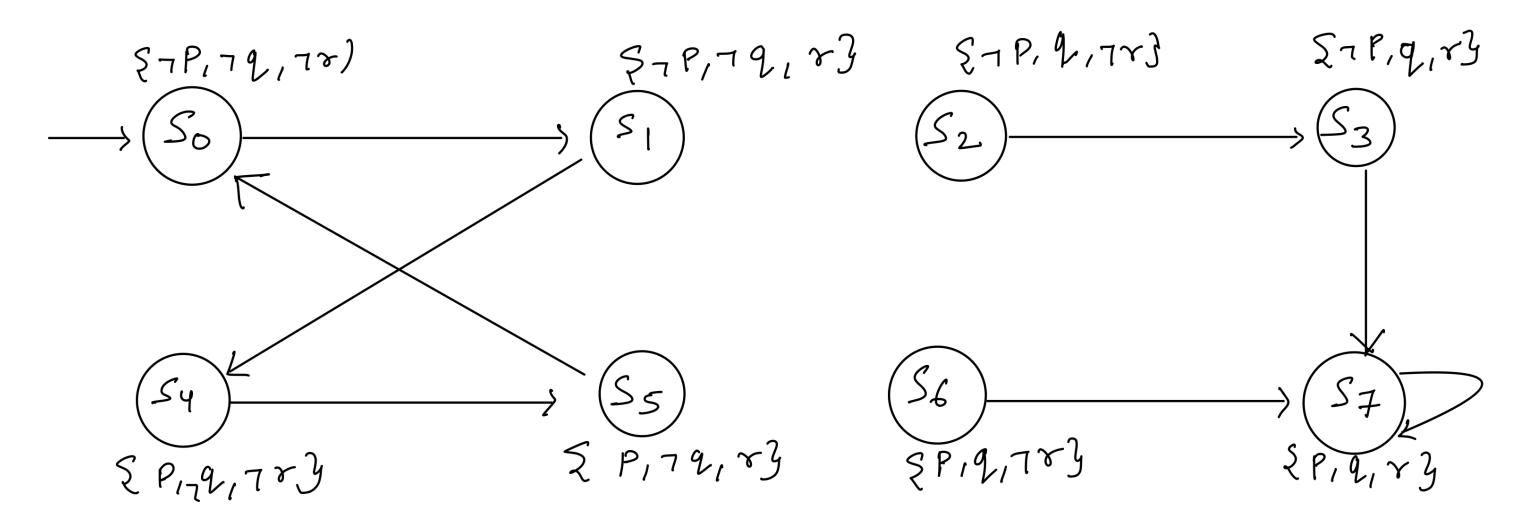


Reachability analysis — can we reach to state where  $p \land q \land r$  holds initial states?  $Q = \{s_o, s_1, s_2, s_3\} \quad \bigvee \{Q(s_o) \land T(s_o, s_1)\} \land \bigwedge^{k-1} T(s_i, s_{i+1}) \land \bigvee^k p(s_i)$  $\forall s \in O$ A

If  $A \wedge B$  is SAT, check if Q = I



Q = I, then Return counter-example. Else, increase k to build trust!



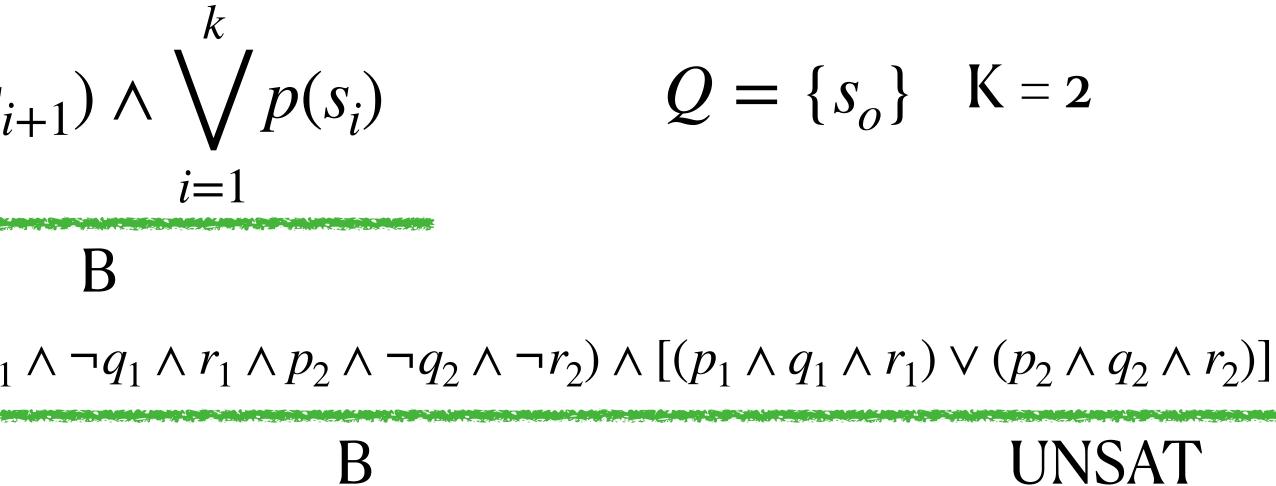
Reachability analysis — can we reach to state where  $p \land q \land r$  holds initial states?

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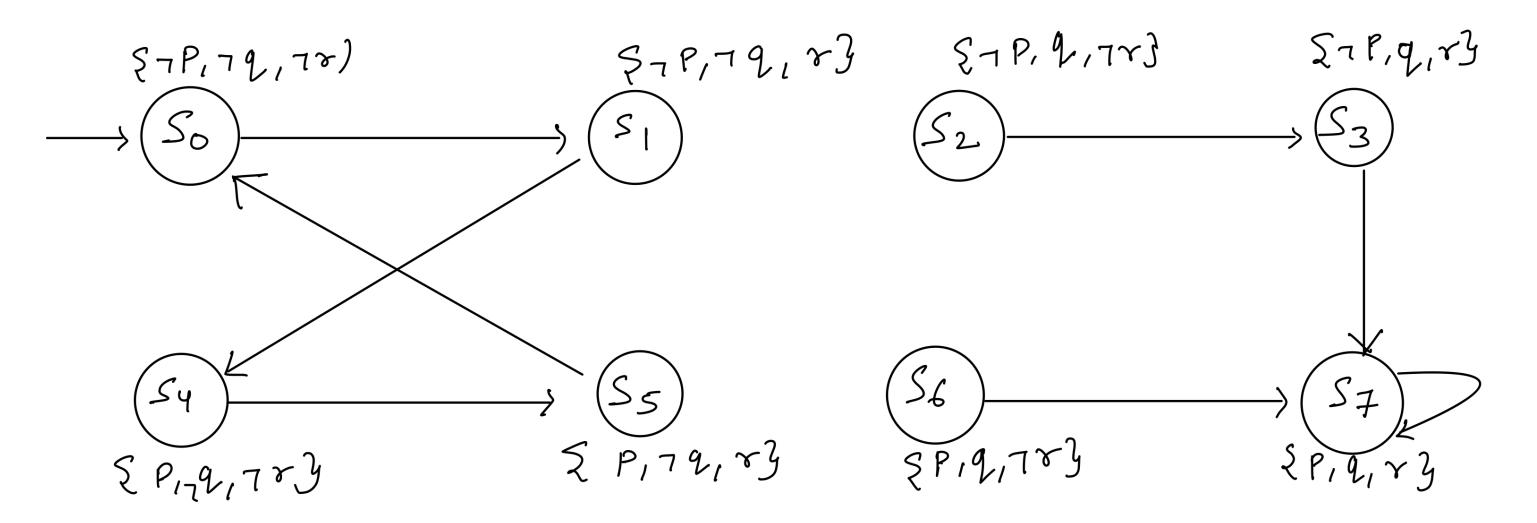
$$A$$

$$\neg p_o \wedge \neg q_o \wedge \neg r_o) \wedge (\neg p_1 \wedge \neg q_1 \wedge r_1) \wedge (\neg p_1)$$

A







Reachability analysis — can we reach to state where  $p \land q \land r$  holds initial states?

$$Q(s_o) \wedge T(s_o, s_1) \wedge \bigwedge_{i=1}^{k-1} T(s_i, s_{i+1}) \wedge \bigvee_{i=1}^{k} p(s_i) \qquad Q = \{s_o\} \quad K = 2$$

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$$UNSAT$$

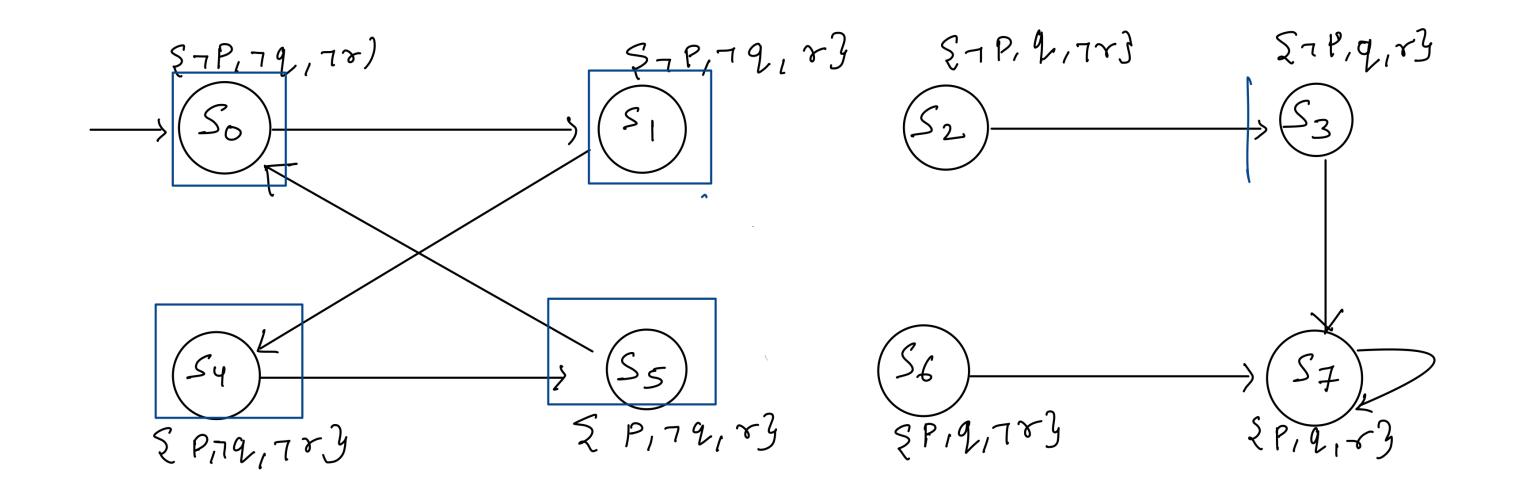
$$B$$

$$I_s : \{s \mid I \in L(s)\} \qquad Q = Q \cup I_s$$

$$Check the reachability with Over-approximate set$$

Interpola

$$I_S = \{s_o, s_1, s_4, s_5\}$$



Reachability analysis — can we reach to state where  $p \land q \land r$  holds initial states?

$$Q(s_o) \wedge T(s_o, s_1) \wedge \bigwedge_{i=1}^{k-1} T(s_i, s_{i+1}) \wedge \bigvee_{i=1}^k p(s_i) \qquad \qquad Q = \{s_o\} \quad K = 2$$

$$UNSAT$$

 $Q = Q \cup I_s$ 

Interpolant :=  $\neg q_1$ 

$$I_S = \{s_o, s_1, s_4, s_5\}$$

 $I_s: \{s \mid I \in L(s)\}$ 

B

Q is inductive invariant!!!  $M \models F$ 

General idea:

1. Perform BMC

2. If BMC is UNSAT:

Iteratively compute and refine an overapproximation of states reachable in K steps.

> Compute Interpolant as over-approximation. If interpolant is inductive Return True.

else

use interpolant to over-approximate.

If BMC is SAT: 3.

Check if over-approximation is same as initial states

otherwise increase K.

**procedure** CraigReachability(model  $M, p \in AP$ ) if  $S_0 \wedge \neg p$  is SAT return " $M \not\models AG p$ "; k := 1; $Q := S_0;$ while *true* do  $A := Q(s_0) \wedge R(s_0, s_1);$  $B := \bigwedge_{i=1}^{k-1} R(s_i, s_{i+1}) \land \bigvee_{i=1}^k \neg p(s_i);$ if  $A \wedge B$  is SAT then if  $Q = S_0$  then return " $M \not\models AG p$ "; Increase *k*  $Q := S_0$ else compute interpolant *I* for *A* and *B* if  $I \subseteq Q$  then return " $M \models AG p$ ";  $Q := Q \cup I$ end if end while end procedure

