

COL:750/7250

Foundations of Automatic Verification

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Course Webpage



Bounded vs Unbounded Model Checking

Bounded:

We unroll the transition system up to a fixed depth k .

Is there a counterexample of length $\leq k$?

If no counterexample is found, we increase k and repeat.

It only checks for violations up to length k

Output— counterexample

Tools: CBMC, NuSMV

Unbounded:

We still unroll transitions, but with a different purpose: to construct an inductive invariant (proof that holds for all k).

We generalize beyond specific length and reason about all reachable states.

The property is proven inductively.

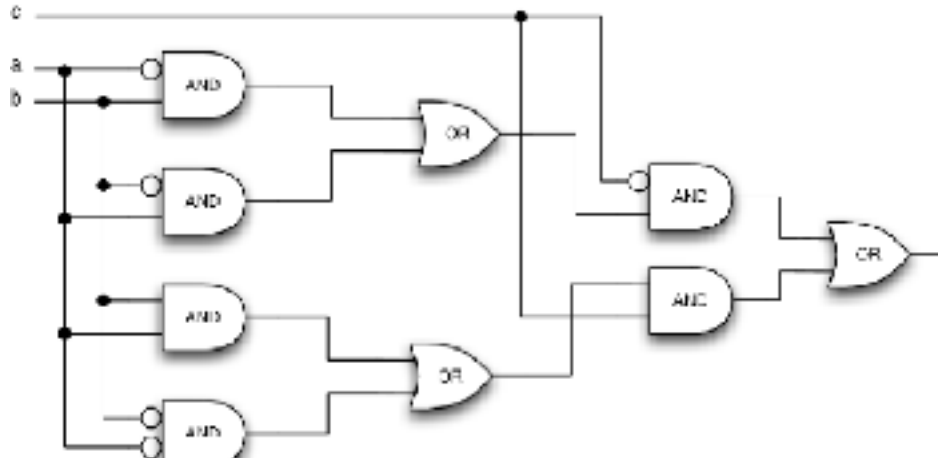
Output— proof/ counterexample

Tools: NuSMV, IC₃, PDR

Formal Verification



```
PC1 (char [] SP, char [] UI) {  
  for (int i=0; i<UI.length(); i++) {  
    if (SP[i] != UI[i]) return No;  
  }  
  return Yes;  
}
```



System

Satisfies



Properties

$$S(I,O) \models P(I,O)$$

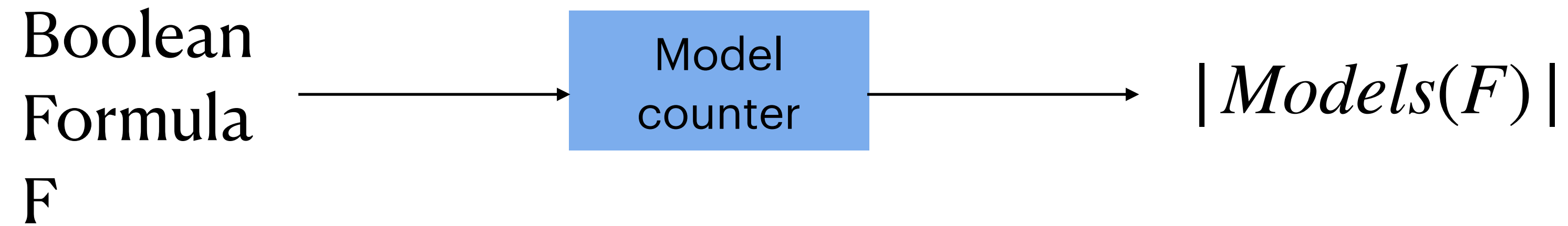
Is it always the case that S satisfies Property P?

How often S satisfies P?

Why S doesn't satisfy P?

How often System satisfies Property? Model Counting!

Finding out how many solutions are there for a given set of constraints.



How often System satisfies Property? Model Counting!

Finding out how many solutions are there for a given set of constraints.

```
ModelCounter(F, count){  
    Result, σ = CheckSAT(F)  
    if (Result == SAT){  
        count ++ }  
    else Return count  
    ModelCounter(F ∧ ¬σ, count)}
```

Assuming access to a NP oracle !

How often System satisfies Property? Model Counting!

Finding out how many solutions are there for a given set of constraints.

ModelCounter(F){

If F is 0 then Return 0

If F is 1 then Return 1

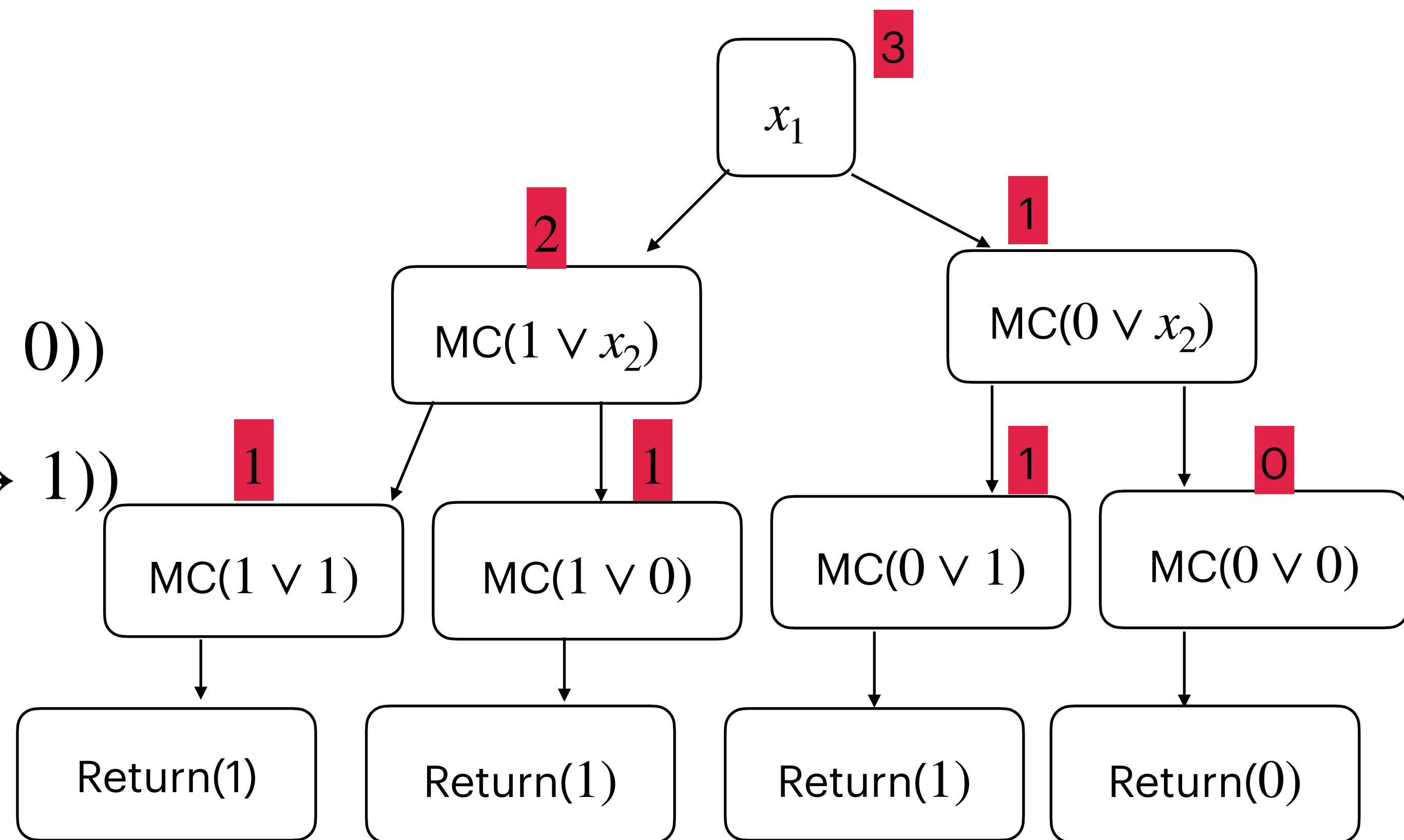
pick x ← VARs(F)

$C_0 = \text{ModelCounter}(F(x \mapsto 0))$

$C_1 = \text{ModelCounter}(F(x \mapsto 1))$

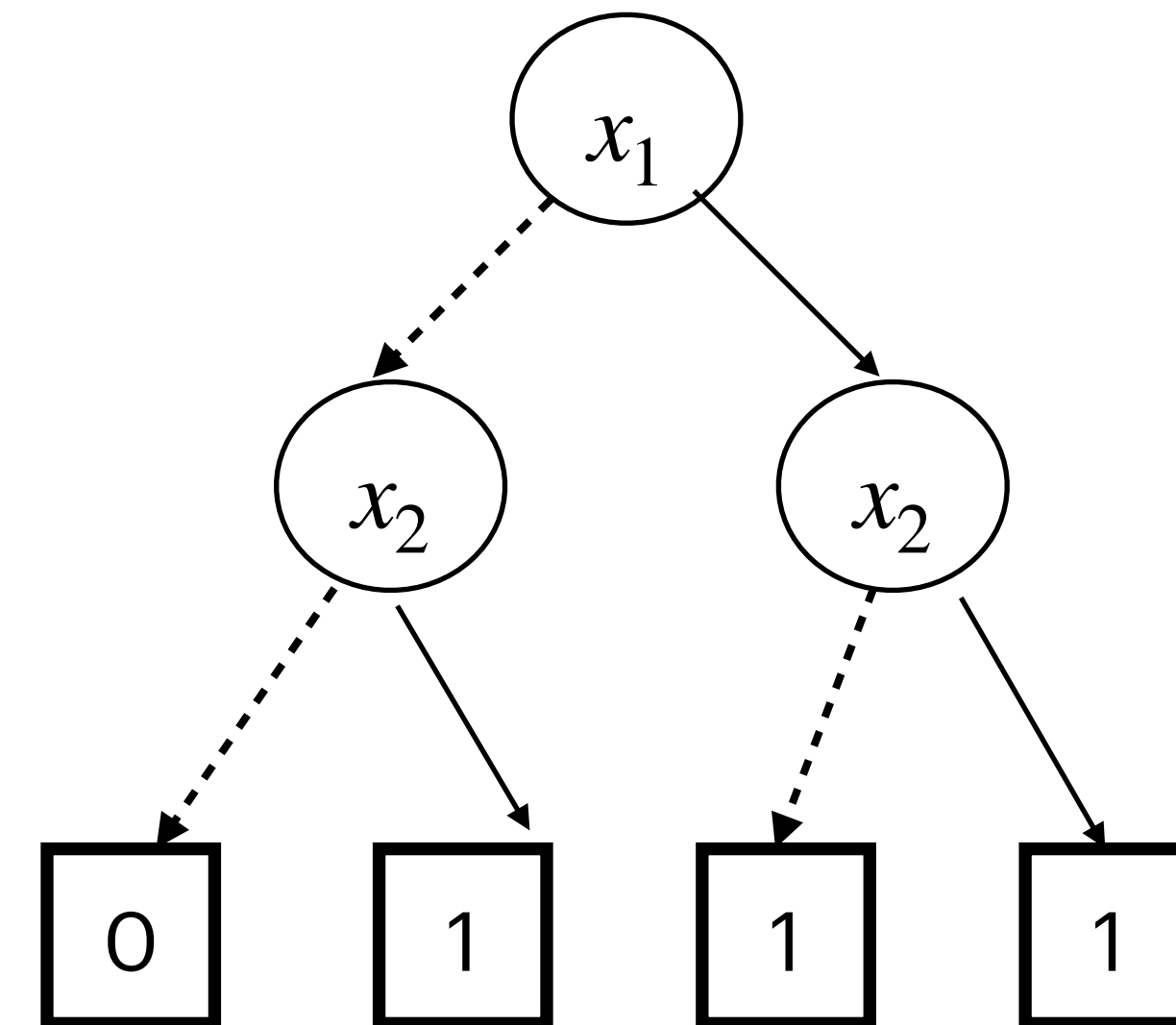
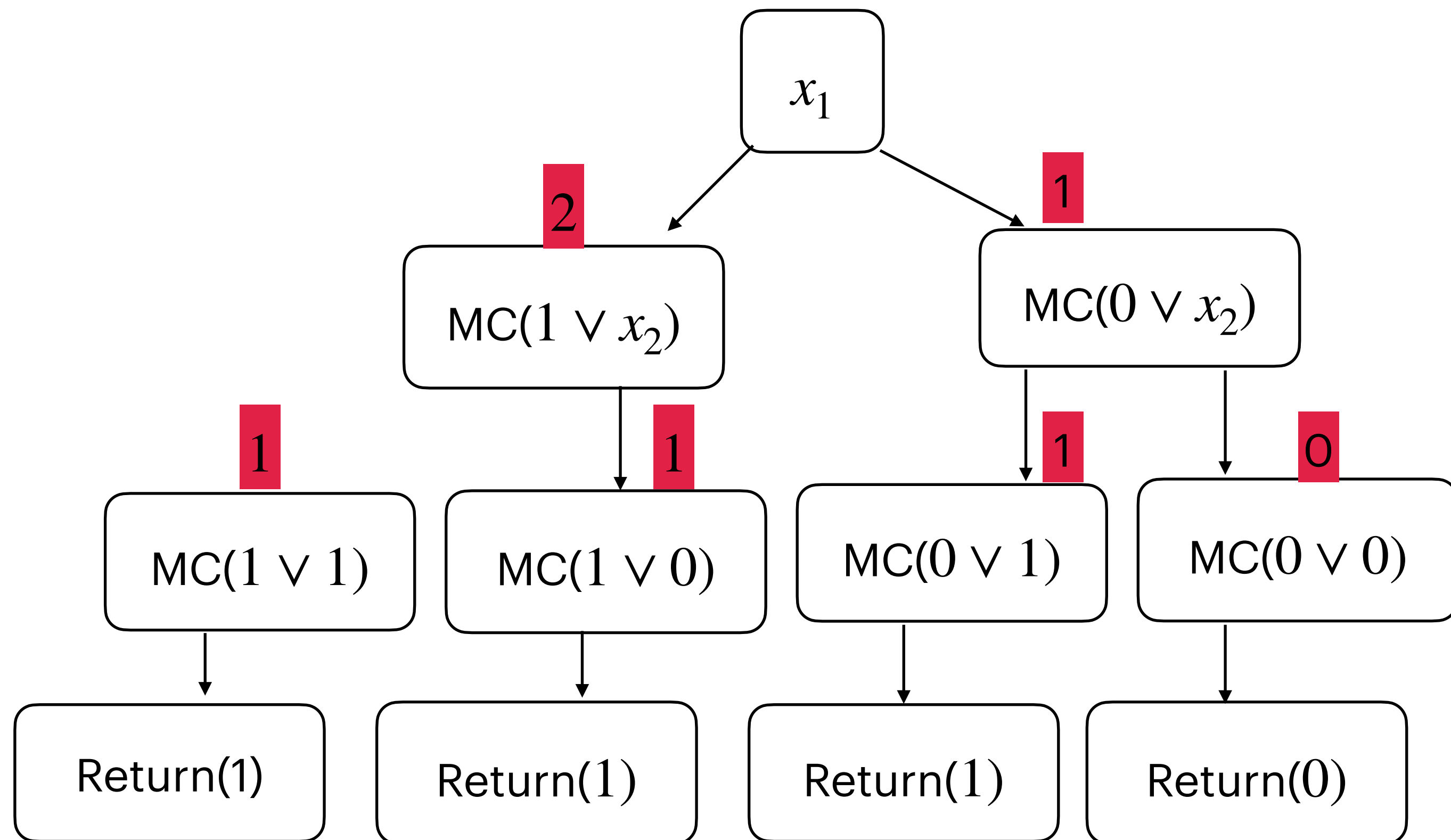
return $C_0 + C_1$ }

$$F = x_1 \vee x_2$$



How often System satisfies Property?

$$F = x_1 \vee x_2$$

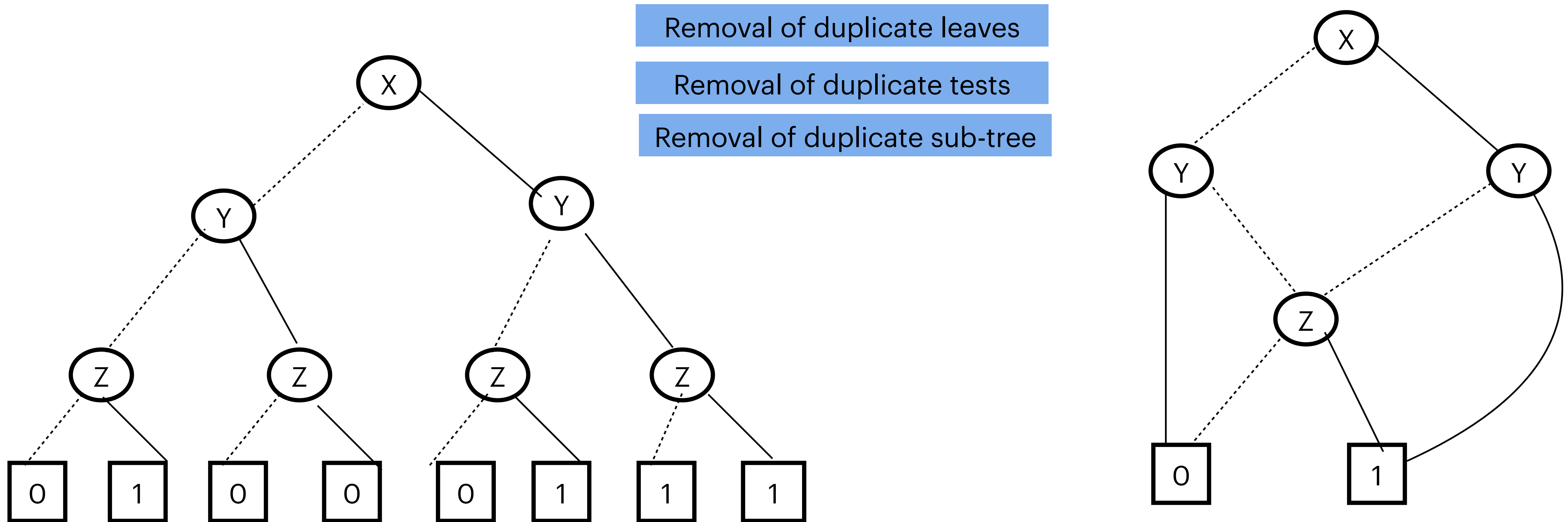


In OBDD, Model count is Sum of leaf nodes.

Model Counting

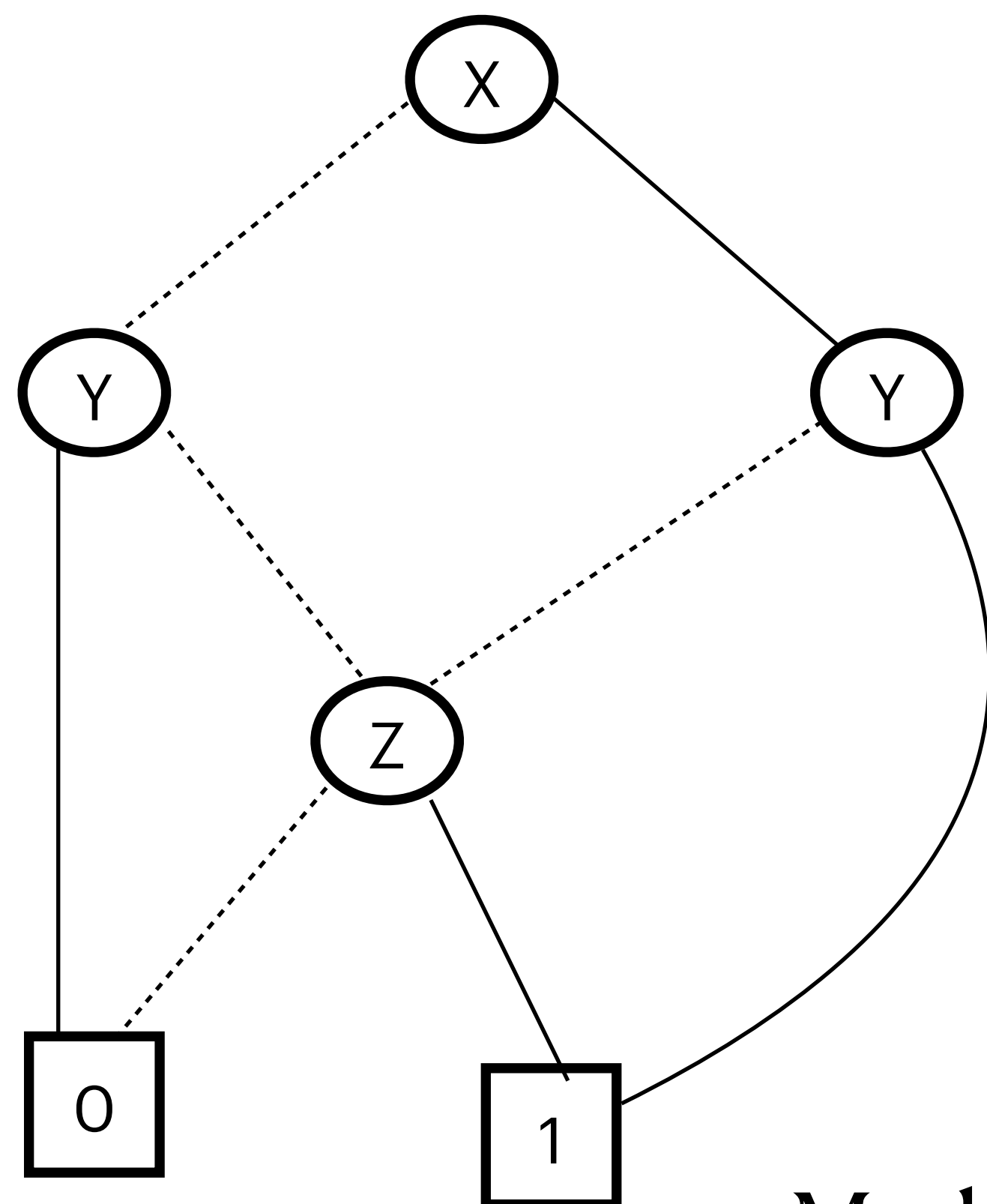
ROBDD — **Reduced** Ordered Binary Decision Diagrams

$$F = (x \wedge y) \vee (\neg y \wedge z)$$



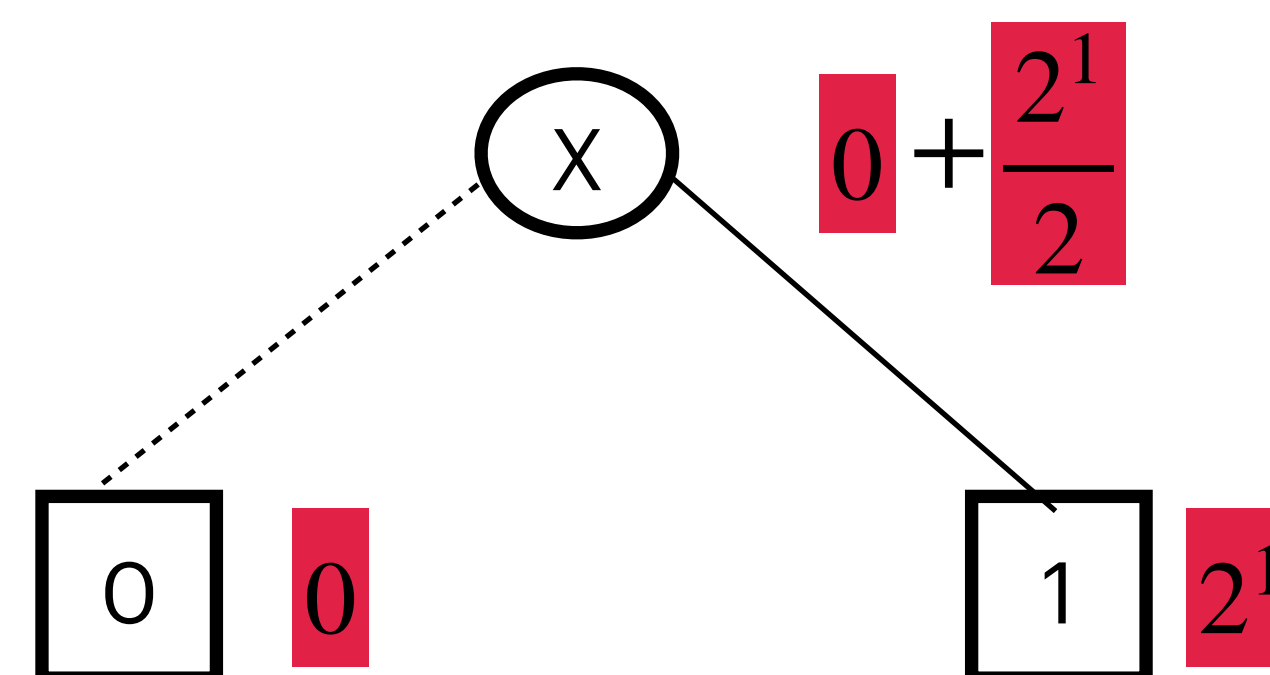
Model Counting

$$F = (x \wedge y) \vee (\neg y \wedge z)$$



Model Counting in ROBDD?

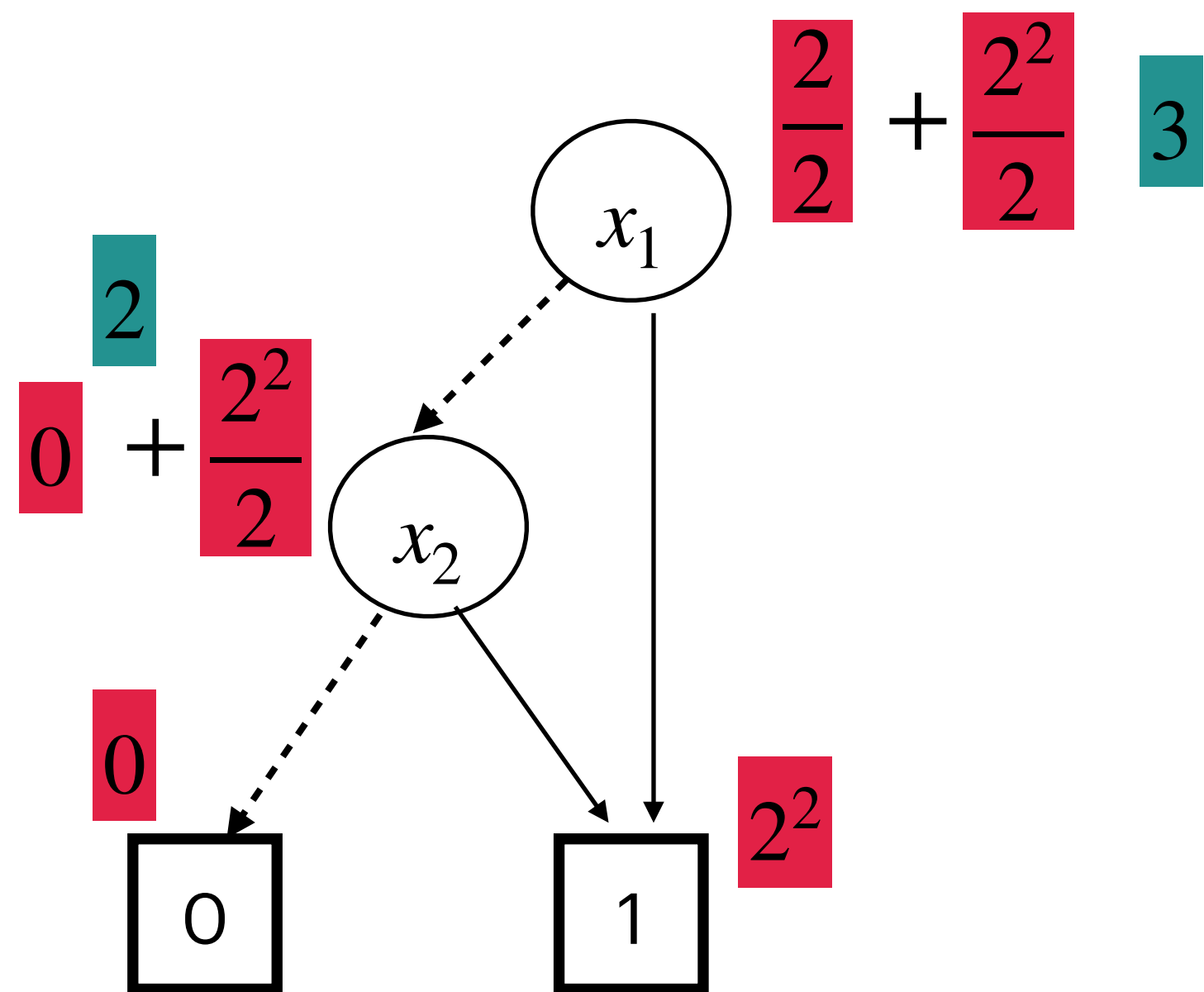
Key Observation: We are fixing a variable as we move from the child to the parent node.



Bottom-up approach.

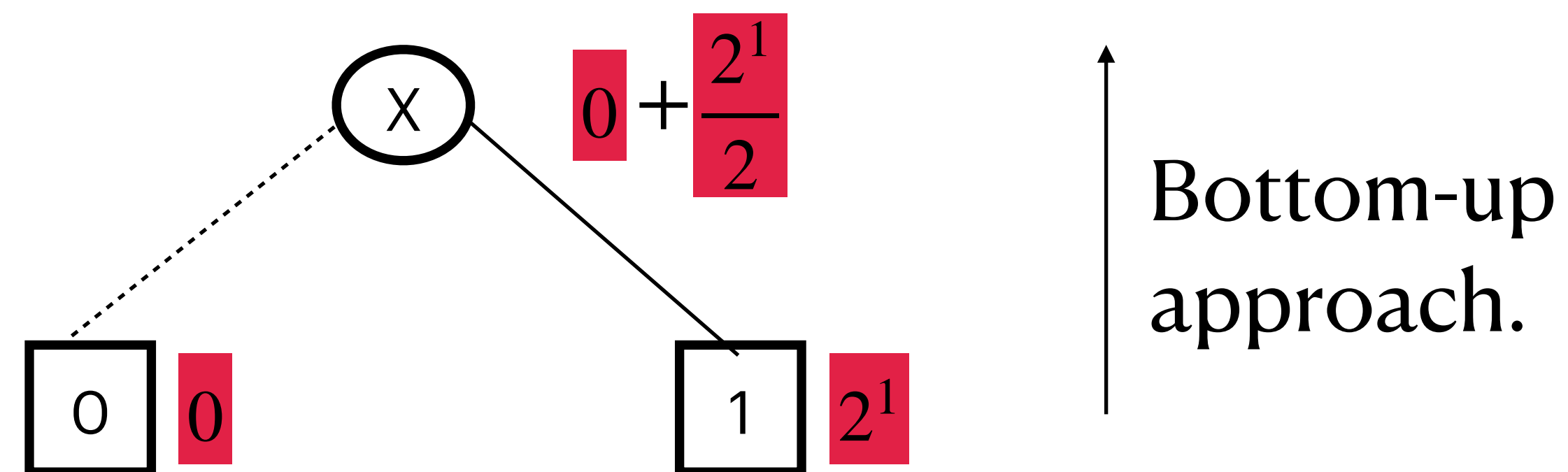
Model Counting

$$F = x_1 \vee x_2$$



Model Counting in ROBDD?

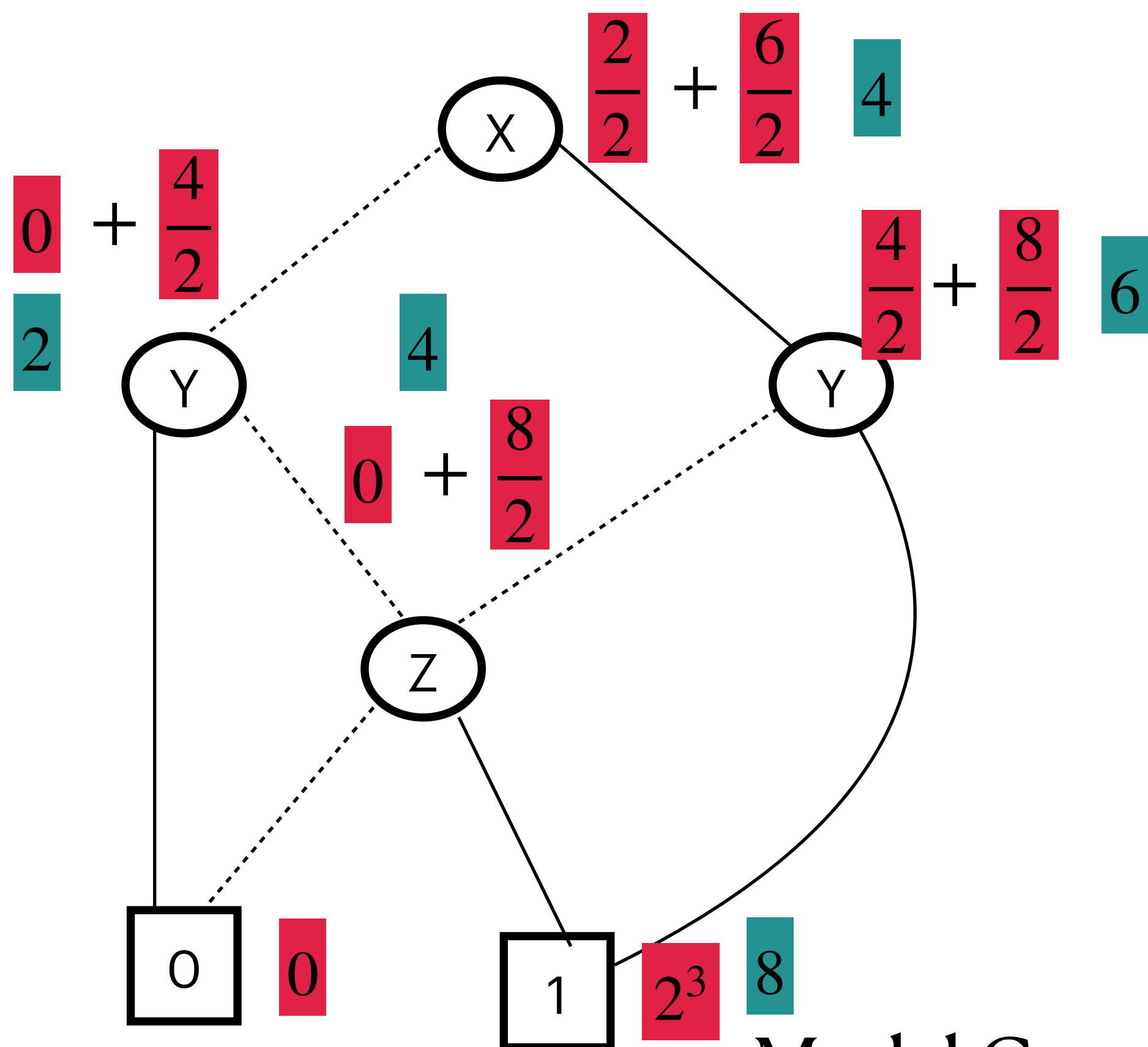
Key Observation: We are fixing a variable as we move from the child to the parent node.



Bottom-up approach.

Model Counting

$$F = (x \wedge y) \vee (\neg y \wedge z)$$



$$|\text{Models}(F)| = 4$$

Model Counting in ROBDD?

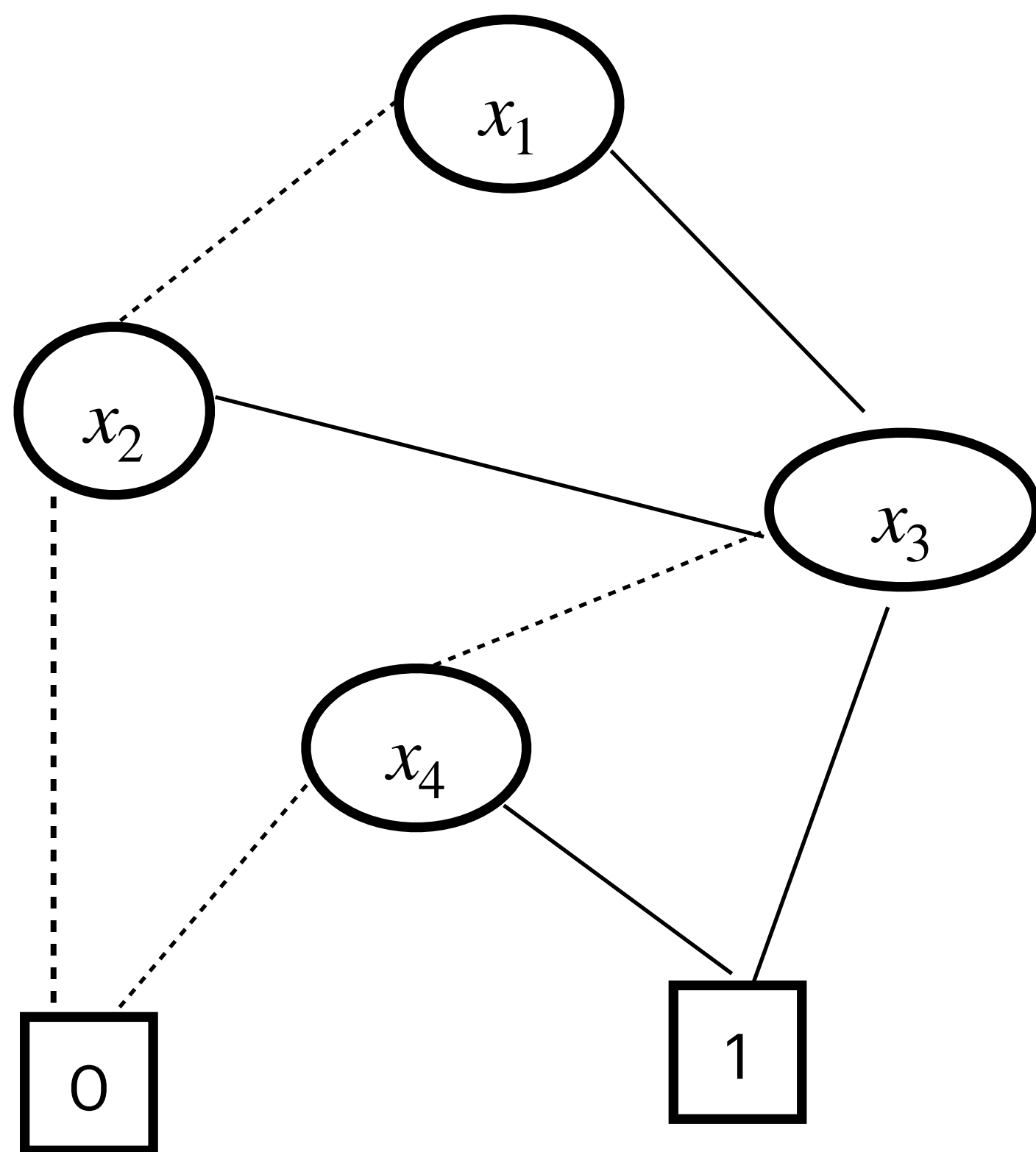
Model Counting

$$F = (x_1 \vee x_2) \wedge (x_3 \vee x_4) \quad x_1 > x_2 > x_3 > x_4$$

Model Counting

$$F = (x_1 \vee x_2) \wedge (x_3 \vee x_4)$$

$$x_1 > x_2 > x_3 > x_4$$



ROBDD vs CNF

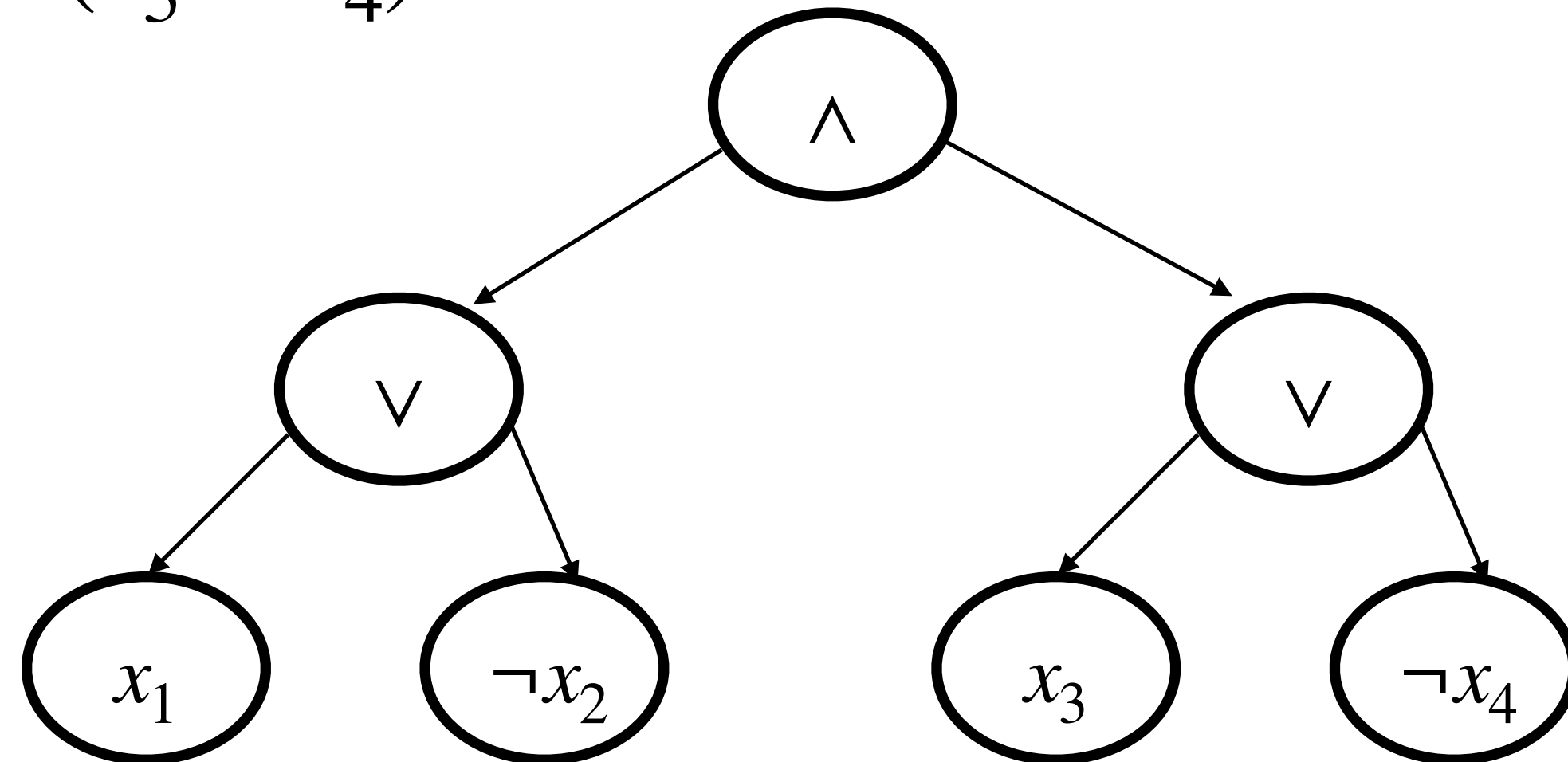
	CNF	ROBDD
SAT	NP-Hard	$O(F_{ROBDD})$
Model Count	#P	$O(F_{ROBDD})$
UNSAT	Co-NP	$O(1)$

Different Compilation Forms

NNF: Normal Negation Form

1. Each non-terminal node is either \wedge or \vee
2. Each terminal node is either a literal or 0 or 1

$$F = (x_1 \vee \neg x_2) \wedge (x_3 \vee x_4)$$



Different Compilation Forms

d-NNF: Deterministic Normal Negation Form (*Darwiche 1998*)

A NNF is deterministic if for every \vee (OR) node with children $\{c_1, c_2, \dots, c_k\}$ following holds:

$$\forall i \neq j \text{ Models}(c_i) \cap \text{Models}(c_j) = \emptyset$$

Any two children of \vee (OR) node don't share models

Different Compilation Forms

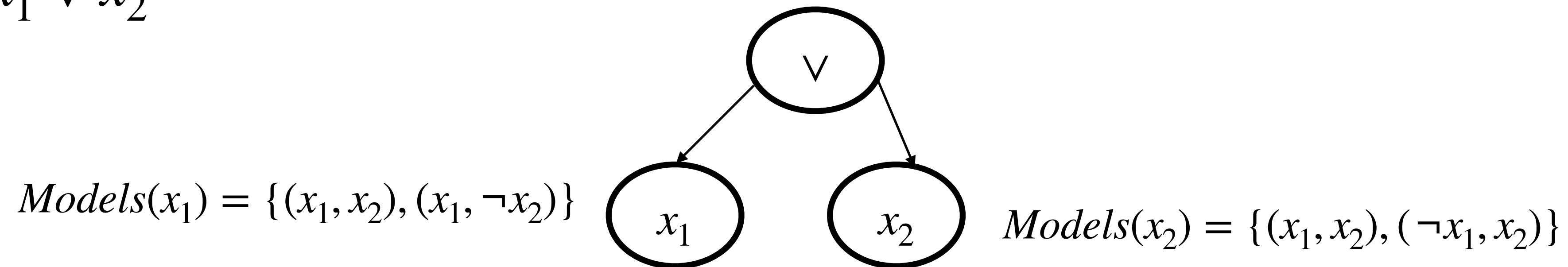
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Any two children of \vee (OR) node don't share models

$$F = x_1 \vee x_2$$



Different Compilation Forms

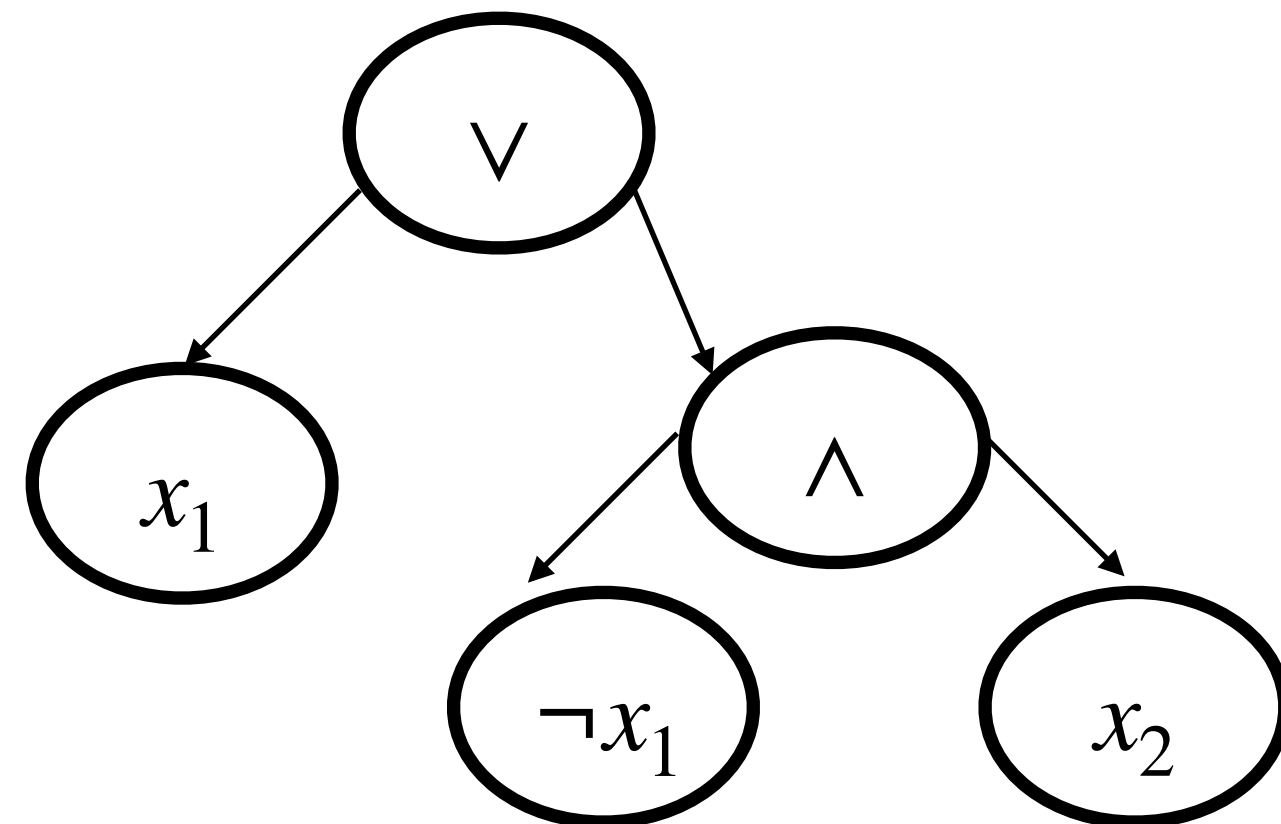
d-NNF: Deterministic Normal Negation Form (*Darwiche 1998*)

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Any two children of \vee (OR) node don't share models

$$F = x_1 \vee x_2$$



F in d-NNF

Different Compilation Forms

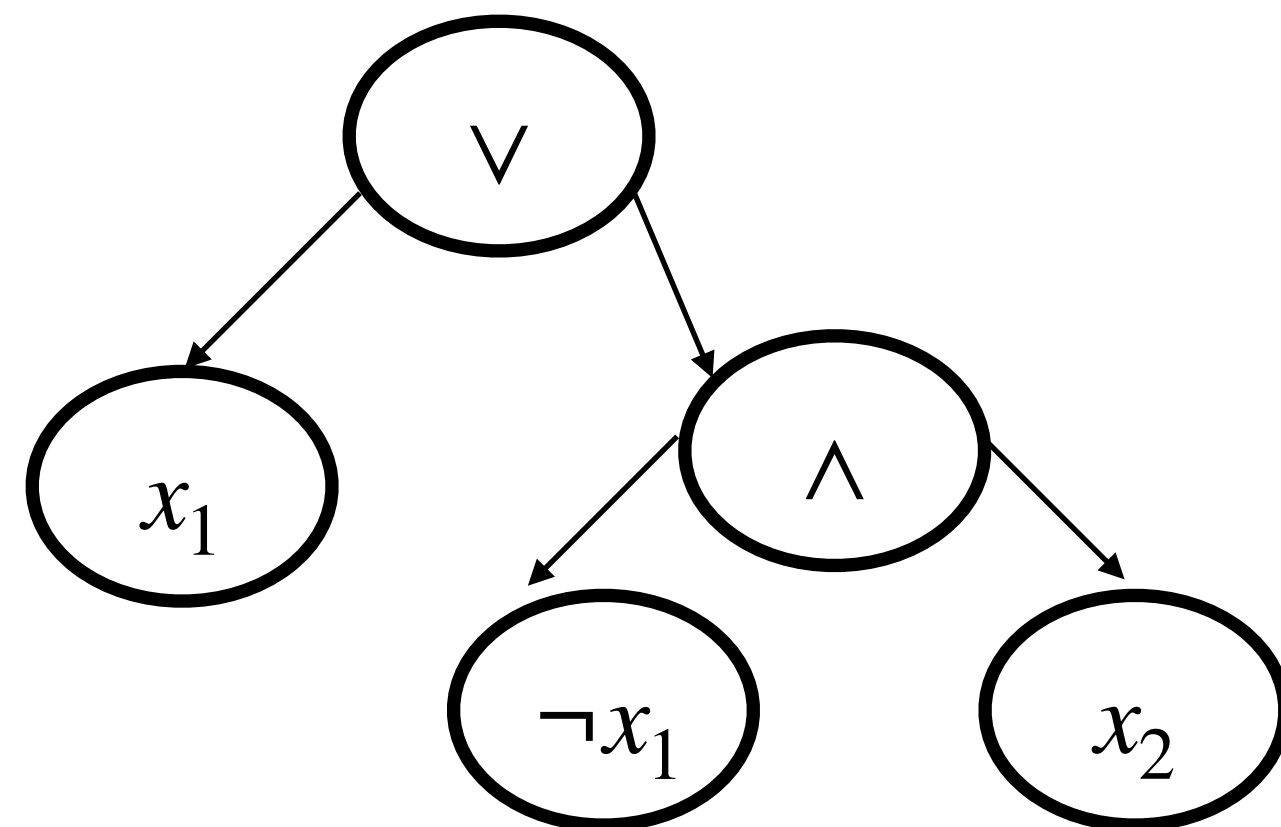
DNNF: Decomposable Normal Negation Form (*Darwiche 2011*)

A NNF is decomposable if for every \wedge (AND) node with children $\{c_1, c_2, \dots, c_k\}$ following holds:

$$\forall i \neq j \text{ Vars}(c_i) \cap \text{Vars}(c_j) = \emptyset$$

Any two children of \wedge (AND) node don't share variables/literals

$$F = x_1 \vee x_2$$



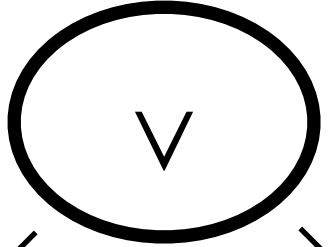
F in DNNF

Model Counting in d-DNNF

$$F = x_1 \vee x_2$$

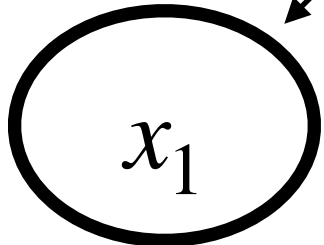
$$\text{Models}(\vee) = \{(x_1, x_2), (x_1, \neg x_2), (\neg x_1, x_2)\}$$

Union

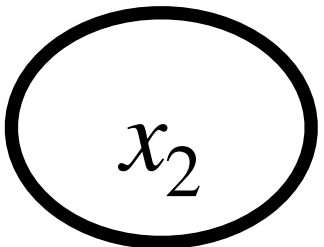
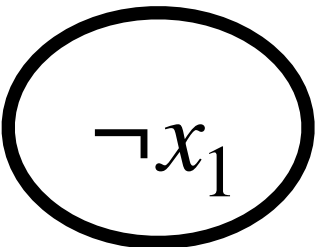
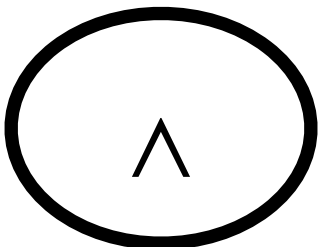


Intersection

$$\text{Models}(x_1) = \{(x_1, x_2), (x_1, \neg x_2)\}$$



$$\text{Models}(\wedge) = \{(\neg x_1, x_2)\}$$



$$\text{Models}(\neg x_1) = \{(\neg x_1, x_2), (\neg x_1, \neg x_2)\}$$

$$\text{Models}(x_2) = \{(\neg x_1, x_2), (x_1, x_2)\}$$

F in d – DNNF

We can't store models at every node! We need to store count!

Model Counting in d-DNNF

(Suggestion from the class)

Please check if is it correct!!!!

Model count of a terminal node:

1. If node is 0, then Model count is 0
2. If node is 1, then Model count is $2^{|\text{Vars}(F)|}$
3. If node is a literal, Model count is $2^{|\text{Vars}(F)-1|}$

Model count of a AND node with children $\{c_1, c_2, \dots, c_k\}$

$$\frac{\prod_{i \in [1, k]} \text{ModelCount}(c_i)}{2^{|\text{Vars}(F)| \times (k-1)}}$$

Model count of a OR node with children $\{c_1, c_2, \dots, c_k\}$

$$\sum_{i \in [1, k]} \text{ModelCount}(c_i)$$

Model Counting in d-DNNF

(Suggestion from the class)

Please check if is it correct!!!!

Model count of a terminal node:

1. If node is 0, then Model count is 0
2. If node is 1, then Model count is 1
3. If node is a literal, Model count is 1

Model count of a AND node with children $\{c_1, c_2, \dots, c_k\}$

$$\prod_{i \in [1, k]} \text{ModelCount}(c_i)$$

Model count of a OR node with children $\{c_1, c_2, \dots, c_k\}$

$$\sum_{i \in [1, k]} \left(\text{ModelCount}(c_i) \times 2^{\left| \bigcup_{j \in [1, k]} \text{Vars}(c_j) - \text{Vars}(c_i) \right|} \right)$$