

Automated Synthesis: Towards the Holy Grail of AI

Kuldeep S. Meel¹, Supratik Chakraborty², S Akshay², Priyanka Golia^{1,3}, Subhajit Roy³

¹National University of Singapore

²Indian Institute of Technology Bombay

³Indian Institute of Technology Kanpur

IJCAI-2022

The Life of Computer Engineers since middle ages

middle ages:= aka second half of 20th century

Wish I had a **system**
that could work like
this ...



The Life of Computer Engineers since middle ages

middle ages:= aka second half of 20th century

Wish I had a **system**
that could work like
this ...



Specification by examples

X_1	X_2	Y
20	3	20
2	9	10
5	30	30
\vdots	\vdots	\vdots



The Life of Computer Engineers since middle ages

middle ages:= aka second half of 20th century

Wish I had a **system**
that could work like
this ...



Specification by examples

X_1	X_2	Y
20	3	20
2	9	10
5	30	30
\vdots	\vdots	\vdots



Specification by logical relation

$$\begin{aligned} & (Y \geq X_1) \wedge (Y \geq X_2) \wedge (Y \geq 10) \wedge \\ & ((Y \leq X_1) \vee (Y \leq X_2) \vee (Y \leq 10)) \end{aligned}$$

The Life of Computer Engineers since middle ages

middle ages:= aka second half of 20th century

Wish I had a **system**
that could work like
this ...



Specification by examples

X_1	X_2	Y
20	3	20
2	9	10
5	30	30
\vdots	\vdots	\vdots



Specification by logical relation

$$\begin{aligned} & (Y \geq X_1) \wedge (Y \geq X_2) \wedge (Y \geq 10) \wedge \\ & ((Y \leq X_1) \vee (Y \leq X_2) \vee (Y \leq 10)) \end{aligned}$$

Specification in natural language

Output Y as max of X_1 and X_2 , but if both are
less than 10, then output Y as 10

The Life of Computer Engineers since Middle Ages

middle ages:= aka second half of 20th century

After some effort ...



Specification by logical relation

$$\begin{aligned} & (Y \geq X_1) \wedge (Y \geq X_2) \wedge (Y \geq 10) \wedge \\ & ((Y \leq X_1) \vee (Y \leq X_2) \vee (Y \leq 10)) \end{aligned}$$

The Life of Computer Engineers since Middle Ages

middle ages:= aka second half of 20th century

After some effort ...



```
input X1, X2;  
temp := max(X1, X2);  
if (temp < 10) Y := 10;  
else Y := temp;  
output Y;
```

Specification by logical relation

$$\begin{aligned} & (Y \geq X_1) \wedge (Y \geq X_2) \wedge (Y \geq 10) \wedge \\ & ((Y \leq X_1) \vee (Y \leq X_2) \vee (Y \leq 10)) \end{aligned}$$

The Life of Computer Engineers since Middle Ages

middle ages:= aka second half of 20th century

After some effort ...



```
input X1, X2;  
temp := max(X1, X2);  
if (temp < 10) Y := 10;  
else Y := temp;  
output Y;
```

How do you know
this is correct?



Specification by logical relation

$$(\mathbf{Y} \geq \mathbf{X}_1) \wedge (\mathbf{Y} \geq \mathbf{X}_2) \wedge (\mathbf{Y} \geq 10) \wedge$$
$$((\mathbf{Y} \leq \mathbf{X}_1) \vee (\mathbf{Y} \leq \mathbf{X}_2) \vee (\mathbf{Y} \leq 10))$$

A Vision for the New Age

Wish I had an **algorithm**
that could help me ...



Specification by examples

X_1	X_2	Y
20	3	20
2	9	10
5	30	30
\vdots	\vdots	\vdots

Specification by logical relation

$$\begin{aligned} & (Y \geq X_1) \wedge (Y \geq X_2) \wedge (Y \geq 10) \wedge \\ & ((Y \leq X_1) \vee (Y \leq X_2) \vee (Y \leq 10)) \end{aligned}$$

Specification in natural language

Output Y as max of X_1 and X_2 , but if both are less than 10, then output Y as 10

A Vision for the New Age

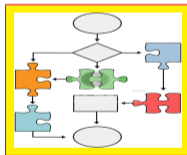
Wish I had an **algorithm**
that could help me ...



Specification by examples

X_1	X_2	Y
20	3	20
2	9	10
5	30	30
\vdots	\vdots	\vdots

Synthesis Algorithm



Specification by logical relation

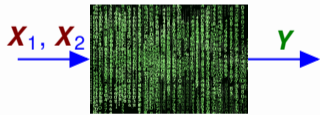
$$(\mathbf{Y} \geq \mathbf{X}_1) \wedge (\mathbf{Y} \geq \mathbf{X}_2) \wedge (\mathbf{Y} \geq 10) \wedge \\ ((\mathbf{Y} \leq \mathbf{X}_1) \vee (\mathbf{Y} \leq \mathbf{X}_2) \vee (\mathbf{Y} \leq 10))$$

Specification in natural language

*Output Y as max of X_1 and X_2 , but if both are
less than 10, then output Y as 10*

A Vision for the New Age

Wish I had an **algorithm**
that could help me ...

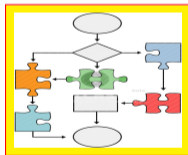


Provably correct system

Specification by examples

X_1	X_2	Y
20	3	20
2	9	10
5	30	30
⋮	⋮	⋮

Synthesis Algorithm



Specification by logical relation

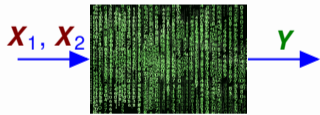
$$(Y \geq X_1) \wedge (Y \geq X_2) \wedge (Y \geq 10) \wedge ((Y \leq X_1) \vee (Y \leq X_2) \vee (Y \leq 10))$$

Specification in natural language

Output Y as max of X_1 and X_2 , but if both are less than 10, then output Y as 10

A Vision for the New Age

Wish I had an **algorithm**
that could help me ...

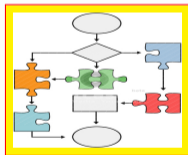


Provably correct system **again!**

Specification by examples

X_1	X_2	Y
20	3	30
2	9	12
5	30	30
⋮	⋮	⋮

Synthesis Algorithm



Specification by logical relation

$$(Y \geq X_1 + 10) \wedge (Y \geq X_2) \wedge \\ ((Y \leq X_1 + 10) \vee (Y \leq X_2))$$

Specification in natural language

*Output Y as X_2 if it is at least 10 more than X_1 ,
otherwise output $X_1 + 10$*

Focus of this talk

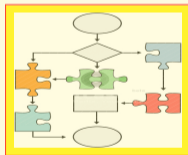
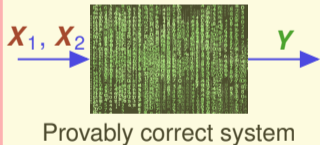
Wish I had an **algorithm**
that could help me ...



Specification by examples

X_1	X_2	Y
20	3	20
2	9	10
5	30	30
\vdots	\vdots	\vdots

Synthesis Algorithm



Specification by logical relation

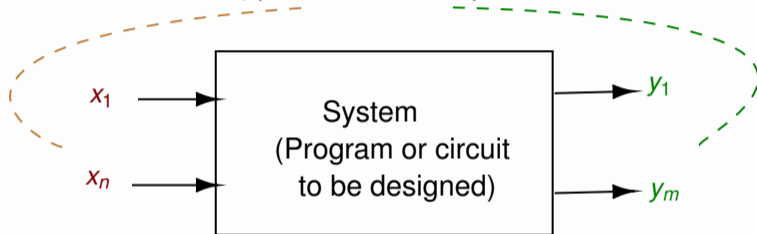
$$(Y \geq X_1) \wedge (Y \geq X_2) \wedge (Y \geq 0) \wedge \\ ((Y \leq X_1) \vee (Y \leq X_2) \vee (Y \leq 0))$$

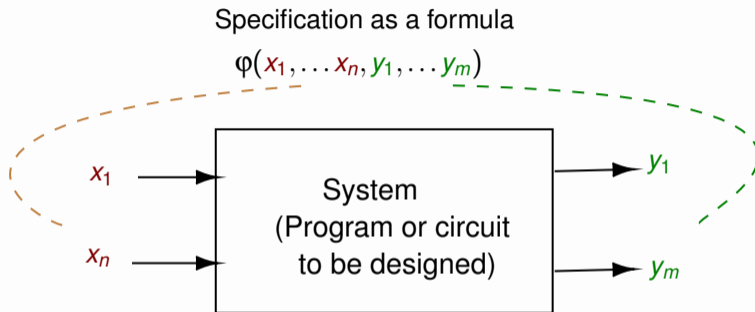
Specification in natural language

Output Y as max of X_1 and X_2 , but if both are
less than 10, then output Y as 10

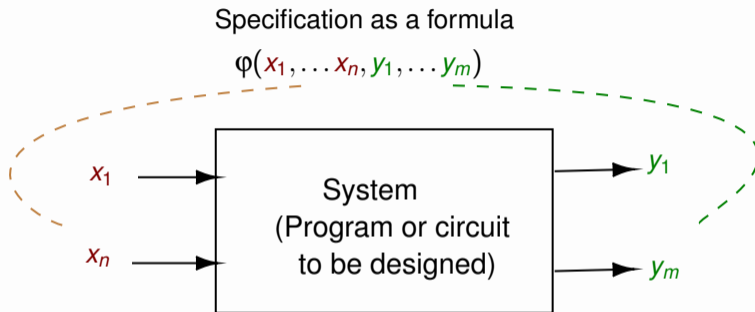
Specification as a formula

$$\varphi(x_1, \dots, x_n, y_1, \dots, y_m)$$





- Goal: Automatically synthesize system s.t. it satisfies $\varphi(x_1, \dots, x_n, y_1, \dots, y_m)$ whenever possible
 - x_i input variables (vector \mathbf{X})
 - y_j output variables (vector \mathbf{Y})

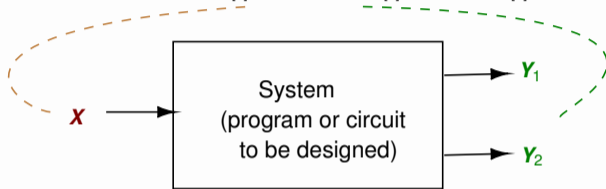


- Goal: Automatically synthesize system s.t. it satisfies $\varphi(x_1, \dots, x_n, y_1, \dots, y_m)$ whenever possible
 - x_i input variables (vector \mathbf{X})
 - y_j output variables (vector \mathbf{Y})
- Need \mathbf{Y} as functions \mathbf{F} of \mathbf{X} such that $\varphi(\mathbf{X}, \mathbf{F})$ is satisfied.

Example: Cryptanalysis

Specification as bit-vector formula

$$(X = Y_1 \times_{[n]} Y_2) \wedge \neg(Y_1 = 1_{[n]}) \wedge \neg(Y_2 = 1_{[n]})$$

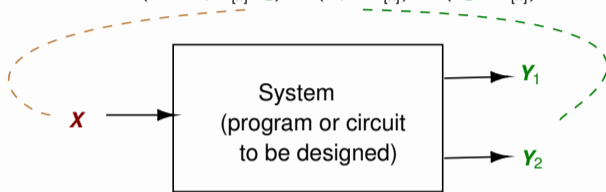


- Synthesize Y_1, Y_2 as functions of X

Example: Cryptanalysis

Specification as bit-vector formula

$$(X = Y_1 \times_{[n]} Y_2) \wedge \neg(Y_1 = 1_{[n]}) \wedge \neg(Y_2 = 1_{[n]})$$

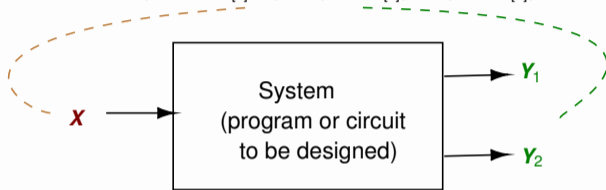


- Synthesize Y_1, Y_2 as functions of X
 - Factorization: Y_1, Y_2 must be non-trivial factors of X

Example: Cryptanalysis

Specification as bit-vector formula

$$(X = Y_1 \times_{[n]} Y_2) \wedge \neg(Y_1 = 1_{[n]}) \wedge \neg(Y_2 = 1_{[n]})$$

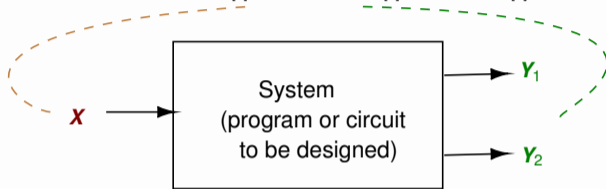


- Synthesize Y_1, Y_2 as functions of X
 - **Factorization:** Y_1, Y_2 must be non-trivial factors of X
 - Efficient solution would break crypto systems

Example: Cryptanalysis

Specification as bit-vector formula

$$(X = Y_1 \times_{[n]} Y_2) \wedge \neg(Y_1 = 1_{[n]}) \wedge \neg(Y_2 = 1_{[n]})$$

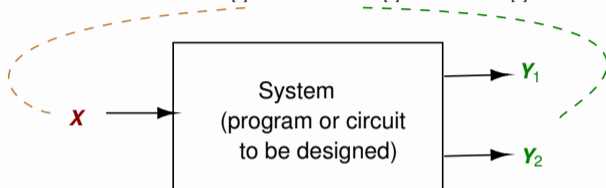


- Synthesize Y_1, Y_2 as functions of X
 - Factorization: Y_1, Y_2 must be non-trivial factors of X
 - Efficient solution would break crypto systems
- Is this spec always satisfiable?

Example: Cryptanalysis

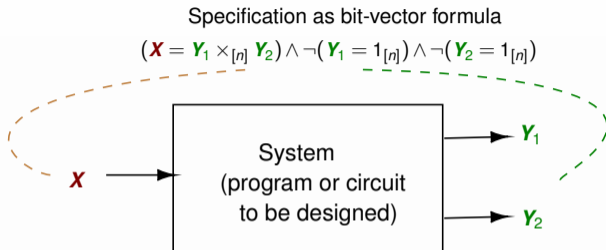
Specification as bit-vector formula

$$(X = Y_1 \times_{[n]} Y_2) \wedge \neg(Y_1 = 1_{[n]}) \wedge \neg(Y_2 = 1_{[n]})$$



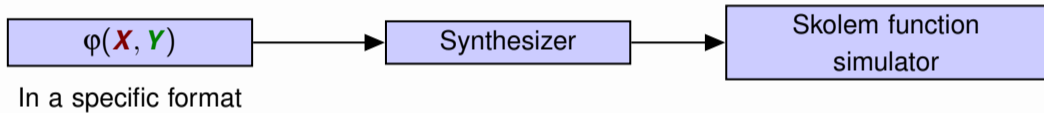
- Synthesize Y_1, Y_2 as functions of X
 - Factorization: Y_1, Y_2 must be non-trivial factors of X
 - Efficient solution would break crypto systems
- Is this spec always satisfiable? (No, X can be prime.)

Example: Cryptanalysis



- Synthesize Y_1, Y_2 as functions of X
 - **Factorization:** Y_1, Y_2 must be non-trivial factors of X
 - Efficient solution would break crypto systems
- Is this spec always satisfiable? (No, X can be prime.)
 - Synthesis still makes sense even if spec is NOT valid!
 - If X is prime, we don't care what we output
- Goal: Automatically synthesize system s.t. it satisfies $\varphi(x_1, \dots, x_n, y_1, \dots, y_m)$ **whenever possible.**

Functional Synthesis: Not Just an Abstract Dream



- Goal: Automatically synthesize system s.t. it satisfies $\varphi(x_1, \dots, x_n, y_1, \dots, y_m)$ **whenever possible**.

Formal definition

Given Boolean relation $\varphi(x_1, \dots, x_n, y_1, \dots, y_m)$

- x_i *input* variables (vector \mathbf{X})
- y_j *output* variables (vector \mathbf{Y})

- Goal: Automatically synthesize system s.t. it satisfies $\varphi(x_1, \dots, x_n, y_1, \dots, y_m)$ **whenever possible**.

Formal definition

Given Boolean relation $\varphi(x_1, \dots, x_n, y_1, \dots, y_m)$

- x_i *input* variables (vector \mathbf{X})
- y_j *output* variables (vector \mathbf{Y})

Synthesize Boolean functions $F_j(\mathbf{X})$ for each y_j s.t.

$$\forall \mathbf{X} \left(\exists y_1 \dots y_m \varphi(\mathbf{X}, y_1 \dots y_m) \Leftrightarrow \varphi(\mathbf{X}, F_1(\mathbf{X}), \dots, F_m(\mathbf{X})) \right)$$

- Goal: Automatically synthesize system s.t. it satisfies $\varphi(x_1, \dots, x_n, y_1, \dots, y_m)$ **whenever possible**.

Formal definition

Given Boolean relation $\varphi(x_1, \dots, x_n, y_1, \dots, y_m)$

- x_i input variables (vector \mathbf{X})
- y_j output variables (vector \mathbf{Y})

Synthesize Boolean functions $F_j(\mathbf{X})$ for each y_j s.t.

$$\forall \mathbf{X} \left(\exists y_1 \dots y_m \varphi(\mathbf{X}, y_1 \dots y_m) \Leftrightarrow \varphi(\mathbf{X}, F_1(\mathbf{X}), \dots, F_m(\mathbf{X})) \right)$$

$F_j(\mathbf{X})$ is also called a *Skolem function* for y_j in φ .

Example

Let $\mathbf{X} = \{x_1, x_2\}$, $\mathbf{Y} = \{y_1\}$ and $\varphi(\mathbf{X}, \mathbf{Y}) = x_1 \vee x_2 \vee y_1$

Possible Skolem function: $F_1(x_1, x_2) := \neg(x_1 \vee x_2)$

Example

Let $\mathbf{X} = \{x_1, x_2\}$, $\mathbf{Y} = \{y_1\}$ and $\varphi(\mathbf{X}, \mathbf{Y}) = x_1 \vee x_2 \vee y_1$

Possible Skolem function: $F_1(x_1, x_2) := \neg(x_1 \vee x_2)$

$$\varphi(\mathbf{X}, F_1(\mathbf{X})) = x_1 \vee x_2 \vee (\neg(x_1 \vee x_2))$$

\mathbf{X}	$\exists \mathbf{Y} \varphi(\mathbf{X}, \mathbf{Y})$	$\varphi(\mathbf{X}, F_1(\mathbf{X}))$	} $\forall \mathbf{X} (\exists \mathbf{Y} \varphi(\mathbf{X}, \mathbf{Y}) \equiv \varphi(\mathbf{X}, F_1(\mathbf{X})))$	
$x_1 = 0, x_2 = 0$	$y_1 = 1$	True		True
$x_1 = 0, x_2 = 1$	$y_1 = 1$	True		True
$x_1 = 1, x_2 = 0$	$y_1 = 1$	True		True
$x_1 = 1, x_2 = 1$	$y_1 = 1$	True		True

Example

Let $\mathbf{X} = \{x_1, x_2\}$, $\mathbf{Y} = \{y_1\}$ and $\varphi(\mathbf{X}, \mathbf{Y}) = x_1 \vee x_2 \vee y_1$

Possible Skolem function: $F_1(x_1, x_2) := \neg(x_1 \vee x_2)$

$$\varphi(\mathbf{X}, F_1(\mathbf{X})) = x_1 \vee x_2 \vee (\neg(x_1 \vee x_2))$$

\mathbf{X}	$\exists \mathbf{Y} \varphi(\mathbf{X}, \mathbf{Y})$	$\varphi(\mathbf{X}, F_1(\mathbf{X}))$
$x_1 = 0, x_2 = 0$	$y_1 = 1$ True	True
$x_1 = 0, x_2 = 1$	$y_1 = 1$ True	True
$x_1 = 1, x_2 = 0$	$y_1 = 1$ True	True
$x_1 = 1, x_2 = 1$	$y_1 = 1$ True	True

} $\forall \mathbf{X} (\exists \mathbf{Y} \varphi(\mathbf{X}, \mathbf{Y}) \equiv \varphi(\mathbf{X}, F_1(\mathbf{X})))$

Many possible Skolem functions:

$$F_1(x_1, x_2) = \neg x_1 \quad F_1(x_1, x_2) = \neg x_2 \quad F_1(x_1, x_2) = 1$$



Skolem functions play an important role in first order logic

- Getting rid of existential quantifiers
- Seminal work by Thoralf Skolem 1920s and Jacques Herbrand 1930s.
- Skolemization and “Skolem-Normal form”
- Focus on existence of form, NOT computability.



Skolem functions play an important role in first order logic

- Getting rid of existential quantifiers
- Seminal work by Thoralf Skolem 1920s and Jacques Herbrand 1930s.
- Skolemization and “Skolem-Normal form”
- Focus on existence of form, NOT computability.

We can trace this history even further back



Skolem functions play an important role in first order logic

- Getting rid of existential quantifiers
- Seminal work by Thoralf Skolem 1920s and Jacques Herbrand 1930s.
- Skolemization and “Skolem-Normal form”
- Focus on existence of form, NOT computability.

We can trace this history even further back

- Existence and construction of Boolean unifiers
- Boole'1847, Lowenheim'1908.



First part: Applications and Overview

- 1 Application Domains
- 2 Theoretical hardness and a high level survey of algorithms

First part: Applications and Overview

- 1 Application Domains
- 2 Theoretical hardness and a high level survey of algorithms

Short break (5 minutes): Stretch yourselves!

Second part: Deep Dive into Recent Advances

- 3 Two Approaches
 - The Guess-check-and-Repair algorithmic paradigm
 - ▶ Counter-example guided and Data-driven approaches

Coffee break

- Knowledge representations for efficient synthesis
- 4 Tool demo
- 5 Conclusion and the Way Forward

- 1 Application Domains
- 2 Theoretical Hardness and Practical Algorithms
- 3 Deep Dives
- 4 Tool Demo
- 5 Conclusion and the Way Forward

Given a specification φ , automatically synthesize a program \mathcal{P} such that $\mathcal{P} \models \varphi$.

Given a specification φ , automatically synthesize a program \mathcal{P} such that $\mathcal{P} \models \varphi$.

Specifications

- Logical specifications
- Test cases (examples)
- Natural Language
- Demonstrations/Traces
- Programs

Given a specification φ , automatically synthesize a program \mathcal{P} such that $\mathcal{P} \models \varphi$.

Specifications

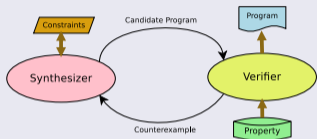
- Logical specifications
- Test cases (examples)
- Natural Language
- Demonstrations/Traces
- Programs

A popular approach: Syntax-Guided Synthesis (SyGuS)*

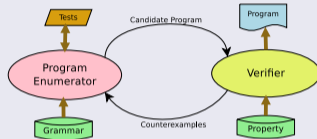
- a background theory (eg. theory of bit-vectors)
- a semantic correctness specification (in the background theory)
- a language to represent the synthesized program (as a context-free grammar)

* Alur et al., FMCAD'13

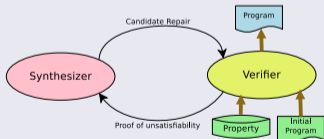
CEGIS (Symbolic)



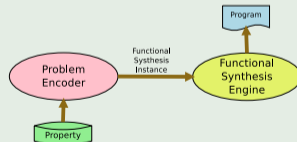
CEGIS (Enumerative)



SyPR: Proof-Guided Repairs



Reduction to Functional Synthesis



* CEGIS(Sym): Solar-Lezama, STTT'12. CEGIS(Enum): Alur et al.,

† FMCAD'13; Alur et al., TACAS'17; SyPR: Verma and Roy, ESEC/FSE'17;

$g(x_1, x_2) \geq x_1$ and
 $g(x_1, x_2) \geq x_2$ and
 $(g(x_1, x_2) == x_1$ or
 $g(x_1, x_2) == x_2)$

- Synthesize program representing function g that satisfies the specification.

$$\begin{aligned} &g(x_1, x_2) \geq x_1 \text{ and} \\ &g(x_1, x_2) \geq x_2 \text{ and} \\ &(g(x_1, x_2) == x_1 \text{ or} \\ &g(x_1, x_2) == x_2) \end{aligned}$$
$$\begin{aligned} &y_1 \geq x_1 \text{ and} \\ &y_1 \geq x_2 \text{ and} \\ &(y_1 == x_1 \text{ or} \\ &y_1 == x_2) \end{aligned}$$

- Synthesize program representing function g that satisfies the specification.
- Replace every call of functions g by a new variable y_1 in the specification.

$$\forall x_1, x_2 \exists y_1 \varphi(x_1, x_2, y_1)$$

$$\begin{aligned} &g(x_1, x_2) \geq x_1 \text{ and} \\ &g(x_1, x_2) \geq x_2 \text{ and} \\ &(g(x_1, x_2) == x_1 \text{ or} \\ &g(x_1, x_2) == x_2) \end{aligned}$$
$$\begin{aligned} &y_1 \geq x_1 \text{ and} \\ &y_1 \geq x_2 \text{ and} \\ &(y_1 == x_1 \text{ or} \\ &y_1 == x_2) \end{aligned}$$

- Synthesize program representing function g that satisfies the specification.
- Replace every call of functions g by a new variable y_1 in the specification.
- Works with appropriate caveats, e.g., outputs depend on all inputs.

$$\forall x_1, x_2 \exists y_1 \varphi(x_1, x_2, y_1)$$

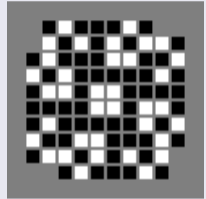
The synthesized skolem function is an implementation of the function $g(x_1, x_2)$.

Conway's Game of Life

- Infinite 2D grid of cells, each alive or dead in each gen:
 - 1 (Under-pop) live cell with < 2 live neighbors dies;
 - 2 (Status-quo) live cell with 2 or 3 live neighbors lives;
 - 3 (Over-pop) live cell > 3 live neighbors dies;
 - 4 (Re-birth) dead cell with 3 live neighbors comes alive

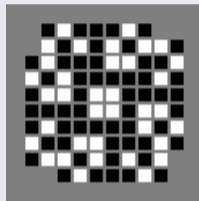
Conway's Game of Life

- Infinite 2D grid of cells, each alive or dead in each gen:
 - 1 (Under-pop) live cell with < 2 live neighbors dies;
 - 2 (Status-quo) live cell with 2 or 3 live neighbors lives;
 - 3 (Over-pop) live cell > 3 live neighbors dies;
 - 4 (Re-birth) dead cell with 3 live neighbors comes alive



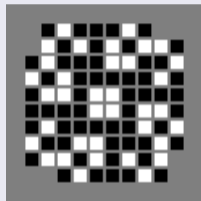
Conway's Game of Life

- Infinite 2D grid of cells, each alive or dead in each gen:
 - 1 (Under-pop) live cell with < 2 live neighbors dies;
 - 2 (Status-quo) live cell with 2 or 3 live neighbors lives;
 - 3 (Over-pop) live cell > 3 live neighbors dies;
 - 4 (Re-birth) dead cell with 3 live neighbors comes alive
- **Objective:** Is there a **Garden of Eden (GoE)**, a configuration with no predecessor?
 - If it does not exist, give a witnessing function that defines the predecessor!



Conway's Game of Life

- Infinite 2D grid of cells, each alive or dead in each gen:
 - 1 (Under-pop) live cell with < 2 live neighbors dies;
 - 2 (Status-quo) live cell with 2 or 3 live neighbors lives;
 - 3 (Over-pop) live cell > 3 live neighbors dies;
 - 4 (Re-birth) dead cell with 3 live neighbors comes alive
- **Objective:** Is there a **Garden of Eden (GoE)**, a configuration with no predecessor?
 - If it does not exist, give a witnessing function that defines the predecessor!
 - History from 1971 onwards...
https://conwaylife.com/wiki/Garden_of_Eden



Encoded as Skolem function existence and synthesis problem

- Let \mathbf{X} be current position, \mathbf{Y} be previous position and $T(\mathbf{X}, \mathbf{Y})$ be transition function
- Then GoE does not exist iff $\forall \mathbf{X} \exists \mathbf{Y} T(\mathbf{X}, \mathbf{Y})$ is satisfiable!

Encoded as Skolem function existence and synthesis problem

- Let \mathbf{X} be current position, \mathbf{Y} be previous position and $T(\mathbf{X}, \mathbf{Y})$ be transition function
- Then GoE does not exist iff $\forall \mathbf{X} \exists \mathbf{Y} T(\mathbf{X}, \mathbf{Y})$ is satisfiable!
- A witness that GoE does not exist is a Skolem function for \mathbf{Y} .

Encoded as Skolem function existence and synthesis problem

- Let \mathbf{X} be current position, \mathbf{Y} be previous position and $T(\mathbf{X}, \mathbf{Y})$ be transition function
 - Then GoE does not exist iff $\forall \mathbf{X} \exists \mathbf{Y} T(\mathbf{X}, \mathbf{Y})$ is satisfiable!
 - A witness that GoE does not exist is a Skolem function for \mathbf{Y} .
-
- $\forall \mathbf{X} \exists \mathbf{Y} T(\mathbf{X}, \mathbf{Y})$ has two alternating blocks of quantifiers: 2-QBF. In general, can have many!

Encoded as Skolem function existence and synthesis problem

- Let \mathbf{X} be current position, \mathbf{Y} be previous position and $T(\mathbf{X}, \mathbf{Y})$ be transition function
 - Then GoE does not exist iff $\forall \mathbf{X} \exists \mathbf{Y} T(\mathbf{X}, \mathbf{Y})$ is satisfiable!
 - A witness that GoE does not exist is a Skolem function for \mathbf{Y} .
-
- $\forall \mathbf{X} \exists \mathbf{Y} T(\mathbf{X}, \mathbf{Y})$ has **two** alternating blocks of quantifiers: **2-QBF**. In general, can have many!

Quantified Boolean Formula (QBF) or QSAT: **Essentially SAT + chunks of quantifiers**

$$\forall \mathbf{X}_1 \exists \mathbf{Y}_1 \forall \mathbf{X}_2 \exists \mathbf{Y}_2 \dots \forall \mathbf{X}_k \exists \mathbf{Y}_k \varphi$$

where φ is a Quantifier-free Boolean Formula, $\mathbf{X}_i, \mathbf{Y}_i$ are sequences of variables.

Encoded as Skolem function existence and synthesis problem

- Let \mathbf{X} be current position, \mathbf{Y} be previous position and $T(\mathbf{X}, \mathbf{Y})$ be transition function
 - Then GoE does not exist iff $\forall \mathbf{X} \exists \mathbf{Y} T(\mathbf{X}, \mathbf{Y})$ is satisfiable!
 - A witness that GoE does not exist is a Skolem function for \mathbf{Y} .
-
- $\forall \mathbf{X} \exists \mathbf{Y} T(\mathbf{X}, \mathbf{Y})$ has two alternating blocks of quantifiers: 2-QBF. In general, can have many!

Quantified Boolean Formula (QBF) or QSAT: Essentially SAT + chunks of quantifiers

$$\forall \mathbf{X}_1 \exists \mathbf{Y}_1 \forall \mathbf{X}_2 \exists \mathbf{Y}_2 \dots \forall \mathbf{X}_k \exists \mathbf{Y}_k \varphi$$

where φ is a Quantifier-free Boolean Formula, $\mathbf{X}_i, \mathbf{Y}_i$ are sequences of variables.

Any 2-player game can be coded as QBF—Skolem functions are winning strategies of Player 2 (\exists -player)!

- Quantifier elimination (Of course!)
 - $\exists \mathbf{Y} \varphi(\mathbf{X}, \mathbf{Y}) \equiv \varphi(\mathbf{X}, \mathbf{F}(\mathbf{X}))$ used in fundamental operations like image computation, interpolant generation, computing predicate abstractions etc.

- Quantifier elimination (Of course!)
 - $\exists \mathbf{Y} \varphi(\mathbf{X}, \mathbf{Y}) \equiv \varphi(\mathbf{X}, \mathbf{F}(\mathbf{X}))$ used in fundamental operations like image computation, interpolant generation, computing predicate abstractions etc.
- Synthesizing arithmetic functions from specifications of arithmetic relations [Fried et al.'16](#)
 - **Example**: subtract, min, max, floor of avg, sort.

- Quantifier elimination (Of course!)
 - $\exists \mathbf{Y} \varphi(\mathbf{X}, \mathbf{Y}) \equiv \varphi(\mathbf{X}, \mathbf{F}(\mathbf{X}))$ used in fundamental operations like image computation, interpolant generation, computing predicate abstractions etc.
- Synthesizing arithmetic functions from specifications of arithmetic relations [Fried et al.'16](#)
 - **Example**: subtract, min, max, floor of avg, sort.
- Disjunctive decomposition of transition relations [Trivedi'03](#)

- Quantifier elimination (Of course!)
 - $\exists \mathbf{Y} \varphi(\mathbf{X}, \mathbf{Y}) \equiv \varphi(\mathbf{X}, \mathbf{F}(\mathbf{X}))$ used in fundamental operations like image computation, interpolant generation, computing predicate abstractions etc.
- Synthesizing arithmetic functions from specifications of arithmetic relations [Fried et al.'16](#)
 - **Example**: subtract, min, max, floor of avg, sort.
- Disjunctive decomposition of transition relations [Trivedi'03](#)
- Circuit repair [Gitina et al.'13](#), [Jiang et al.'20](#), [Fujita et al.'20](#)
 - Complete the implementation of a circuit such that it is functionally equivalent to the specification.
- Reactive synthesis
 - Synthesizing winning strategy within the winning region.

First part: Applications and Overview

- 1 Application Domains
- 2 Theoretical hardness and a high level survey of algorithms

First part: Applications and Overview

- 1 Application Domains
- 2 Theoretical hardness and a high level survey of algorithms

Short break (5 minutes): Stretch yourselves!

Second part: Deep Dive into Recent Advances

- 3 Two Approaches
 - The Guess-check-and-Repair algorithmic paradigm
 - ▶ Counter-example guided and Data-driven approaches
 - Coffee break
 - Knowledge representations for efficient synthesis
- 4 Tool demo
- 5 Conclusion and the Way Forward

- 1 Application Domains
- 2 Theoretical Hardness and Practical Algorithms**
- 3 Deep Dives
- 4 Tool Demo
- 5 Conclusion and the Way Forward

How Hard is Boolean Functional Synthesis?

Representation: Specification & Skolem functions as Boolean circuits in NNF.

How Hard is Boolean Functional Synthesis?

Representation: Specification & Skolem functions as Boolean circuits in NNF.

Time complexity

Boolean functional synthesis is *NP*-hard

How Hard is Boolean Functional Synthesis?

Representation: Specification & Skolem functions as Boolean circuits in NNF.

Time complexity

Boolean functional synthesis is *NP*-hard (not surprising!).

How Hard is Boolean Functional Synthesis?

Representation: Specification & Skolem functions as Boolean circuits in NNF.

Time complexity

Boolean functional synthesis is *NP-hard* (not surprising!).

Space complexity *

* S. Akshay, Supratik Chakraborty, Shubham Goel, Sumith Kulal, Shetal Shah, CAV'18, FMSD'20

How Hard is Boolean Functional Synthesis?

Representation: Specification & Skolem functions as Boolean circuits in NNF.

Time complexity

Boolean functional synthesis is *NP-hard* (not surprising!).

Space complexity *

- Unless some well-regarded complexity-theoretic conjectures fail, there exist specifications φ for which Skolem function sizes must be *super-polynomial* or even *exponential* in $|\varphi|$.

How Hard is Boolean Functional Synthesis?

Representation: Specification & Skolem functions as Boolean circuits in NNF.

Time complexity

Boolean functional synthesis is *NP-hard* (not surprising!).

Space complexity *

- Unless some well-regarded complexity-theoretic conjectures fail, there exist specifications φ for which Skolem function sizes must be *super-polynomial* or even *exponential* in $|\varphi|$.

Bottomline: Efficient algorithms for Boolean functional synthesis unlikely

How Hard is Boolean Functional Synthesis?

Representation: Specification & Skolem functions as Boolean circuits in NNF.

Time complexity

Boolean functional synthesis is *NP-hard* (not surprising!).

Space complexity *

- Unless some well-regarded complexity-theoretic conjectures fail, there exist specifications φ for which Skolem function sizes must be *super-polynomial* or even *exponential* in $|\varphi|$.

Bottomline: Efficient algorithms for Boolean functional synthesis unlikely

Also note: use of SAT-solvers inevitable or unavoidable!

* S. Akshay, Supratik Chakraborty, Shubham Goel, Sumith Kulal, Shetal Shah, CAV'18, FMSD'20

Phase I

1. Extract Skolem functions from proof of validity of $\forall \mathbf{X} \exists \mathbf{Y} \varphi(\mathbf{X}, \mathbf{Y})$
Bendetti'05, Jussilla et al.'07, Balabanov et al.'12, Heule et al.'14
 - Efficient if a short proof of validity is found.
2. Using templates
Solar-Lezama et al.'06, Srivastava et al.'13
 - Effective when small set of candidate Skolem functions known.
3. Self-substitution + function composition
Jiang'09, Trivedi'03
 - Craig Interpolation-based approach.

Phase II

4. Incremental determinization

Rabe et al.'17,'18

- Incrementally adds new constraints to the formula to generate a unique Skolem function.

5. Quantifier instantiation techniques in SMT solvers

Barrett et al.'15, Bierre et al.'17

- Works even for bit-vector and other theories.

6. Input/output component separation

Chakraborty et al.'18

- View specification as made of input and output components.
- Alternate analysis of each component to generate decision lists.

7. Synthesis from and as ROBDDs

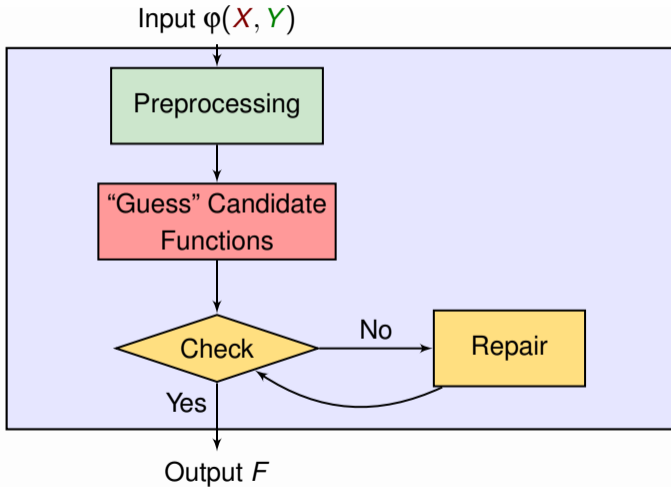
- Kukula et al.'00, Kuncak et al.'10, Fried et al.'16, Tabajara et al.'17

Phase III: The Modern Age!

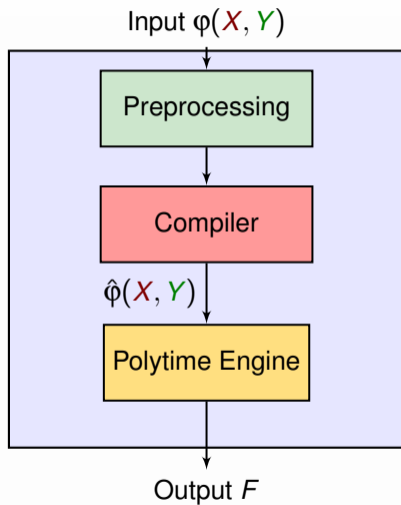
8. Counter-example guided Skolem function generation (**Guess + check + repair**)
 - Over-approximate initial guess of Skolem functions + refine
John et al.'15, Akshay et al.'17,'18,'20
 - Machine-learn initial Skolem function + MaxSat-based iterative repair
Golia et al.'20, '21
9. Knowledge Compilation for Boolean Functional Synthesis (**Special normal forms**)
 - Synthesis negation normal forms (SynNNF)
Akshay et al.'19
 - Subset-And-Unsatisfiable Normal Form (SAUNF)
Shah et al.'21

Our focus in the deep-dive: These last approaches!

Counter-example guided Skolem function generation

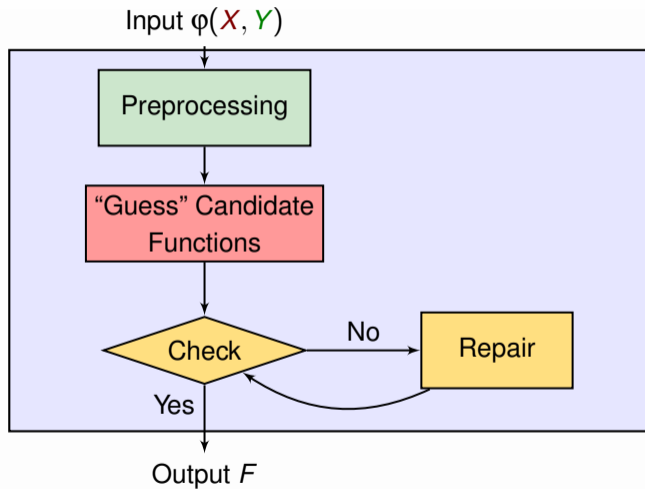


} Machine-learning based
or
Function-approx based

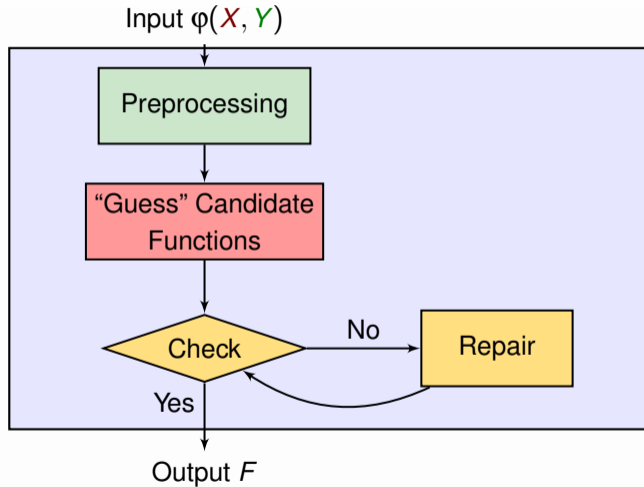


- 1 Application Domains
- 2 Theoretical Hardness and Practical Algorithms
- 3 Deep Dives**
- 4 Tool Demo
- 5 Conclusion and the Way Forward

Deep Dive 1: Counter-example guided Skolem function generation

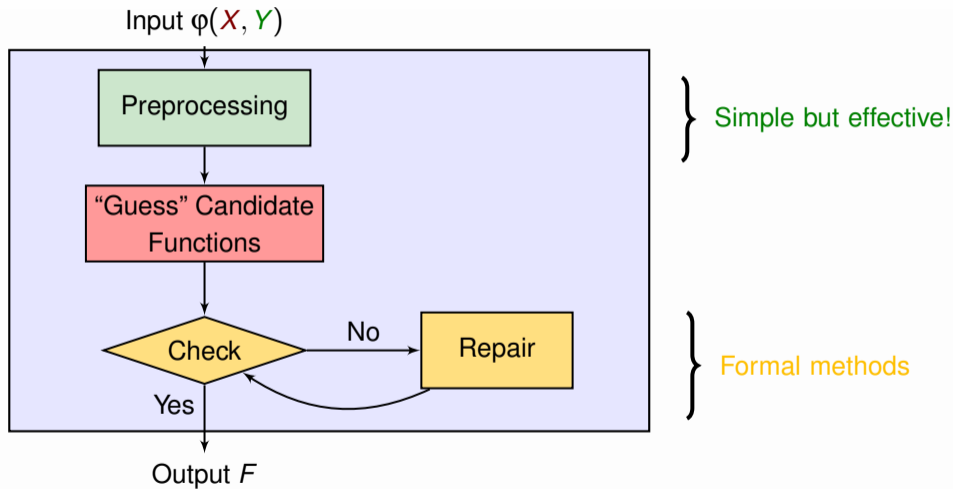


Deep Dive 1: Counter-example guided Skolem function generation

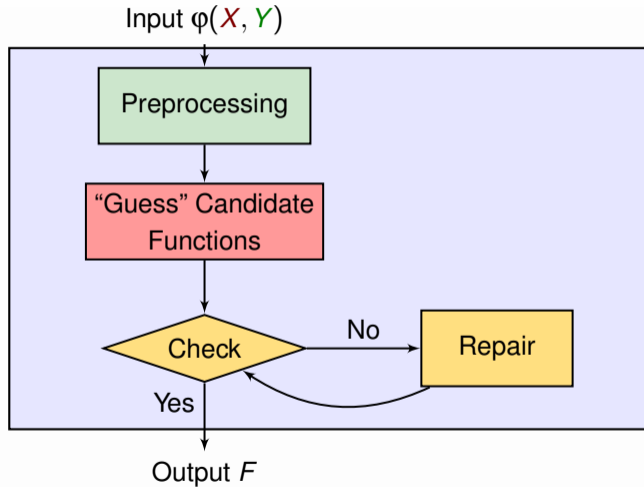


} Simple but effective!

Deep Dive 1: Counter-example guided Skolem function generation



Deep Dive 1: Counter-example guided Skolem function generation



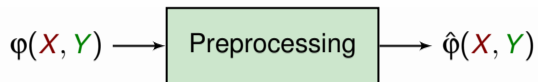
} Simple but effective!

} Machine-learning (Manthan)

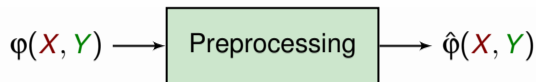
} or

} Function-approx (BFSS)

} Formal methods



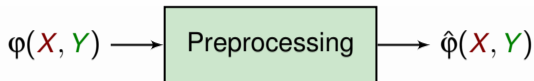
- Skolem functions of $\hat{\varphi}(X, Y)$
 - are (or can be extended to) Skolem functions for $\varphi(X, Y)$.
 - are easier to synthesise at least for some variables.



- Skolem functions of $\hat{\varphi}(X, Y)$
 - are (or can be extended to) Skolem functions for $\varphi(X, Y)$.
 - are easier to synthesise at least for some variables.

Pre-process your input

- For unate variables, constant functions suffice. e.g., if $\varphi|_{y=0} \implies \varphi|_{y=1}$ then $F_1 = 1$.

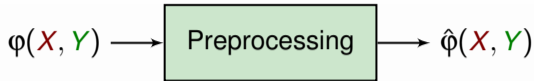


- Skolem functions of $\hat{\varphi}(X, Y)$
 - are (or can be extended to) Skolem functions for $\varphi(X, Y)$.
 - are easier to synthesise at least for some variables.

Pre-process your input

- For unate variables, constant functions suffice. e.g., if $\varphi|_{y=0} \implies \varphi|_{y=1}$ then $F_1 = 1$.
- Uniquely defined variables are easy, e.g., Tseitin variables. y_1 is uniquely defined in

$$\varphi(X, Y) := \dots \wedge (y_1 \leftrightarrow (x_1 \vee x_2)) \wedge \dots$$



- Skolem functions of $\hat{\varphi}(X, Y)$
 - are (or can be extended to) Skolem functions for $\varphi(X, Y)$.
 - are easier to synthesise at least for some variables.

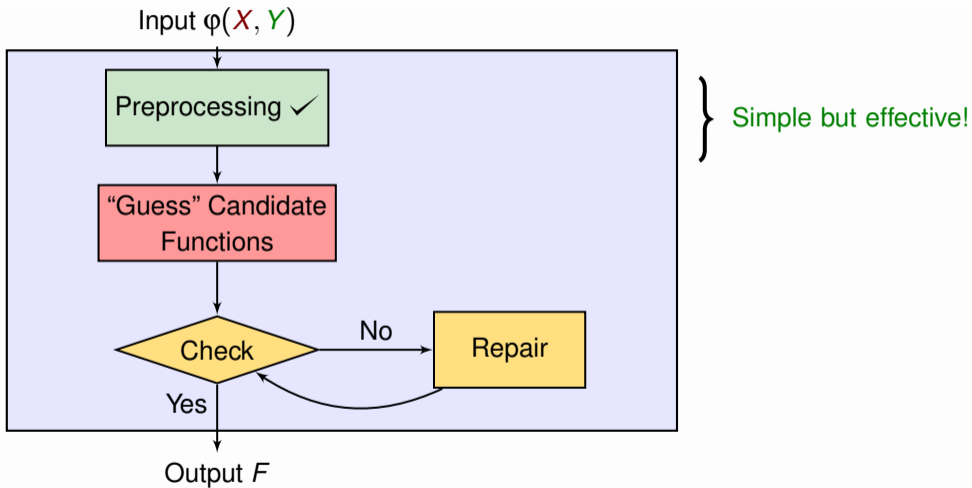
Pre-process your input

- For unate variables, constant functions suffice. e.g., if $\varphi|_{y=0} \implies \varphi|_{y=1}$ then $F_1 = 1$.
- Uniquely defined variables are easy, e.g., Tseitin variables. y_1 is uniquely defined in

$$\varphi(X, Y) := \dots \wedge (y_1 \leftrightarrow (x_1 \vee x_2)) \wedge \dots$$

These simple checks are **surprisingly effective**; handle many variables.

Deep Dive 1: Counter-example guided Skolem function generation



How do we check if a given function is a correct Skolem function?

Given functions F_1, \dots, F_m , is $\forall \mathbf{X} (\exists \mathbf{Y} \varphi(\mathbf{X}, \mathbf{Y}) \Leftrightarrow \varphi(\mathbf{X}, \mathbf{F}(\mathbf{X})))$?

How do we check if a given function is a correct Skolem function?

Given functions F_1, \dots, F_m , is $\forall \mathbf{X} (\exists \mathbf{Y} \varphi(\mathbf{X}, \mathbf{Y}) \Leftrightarrow \varphi(\mathbf{X}, \mathbf{F}(\mathbf{X})))$?

Can we avoid using a 2-QBF solver and stick to faster SAT-solvers?

How do we check if a given function is a correct Skolem function?

Given functions F_1, \dots, F_m , is $\forall \mathbf{X} (\exists \mathbf{Y} \varphi(\mathbf{X}, \mathbf{Y}) \Leftrightarrow \varphi(\mathbf{X}, \mathbf{F}(\mathbf{X})))$?

Can we avoid using a 2-QBF solver and stick to faster SAT-solvers?

Yes, we can! [John et al.'15]

- Propositional error formula:

$$E(\mathbf{X}, \mathbf{Y}, \mathbf{Y}') := \varphi(\mathbf{X}, \mathbf{Y}) \wedge \neg \varphi(\mathbf{X}, \mathbf{Y}') \wedge (\mathbf{Y}' \leftrightarrow \mathbf{F}(\mathbf{X}))$$

How do we check if a given function is a correct Skolem function?

Given functions F_1, \dots, F_m , is $\forall \mathbf{X} (\exists \mathbf{Y} \varphi(\mathbf{X}, \mathbf{Y}) \Leftrightarrow \varphi(\mathbf{X}, \mathbf{F}(\mathbf{X})))$?

Can we avoid using a 2-QBF solver and stick to faster SAT-solvers?

Yes, we can! [John et al.'15]

- Propositional error formula:

$$E(\mathbf{X}, \mathbf{Y}, \mathbf{Y}') := \varphi(\mathbf{X}, \mathbf{Y}) \wedge \neg \varphi(\mathbf{X}, \mathbf{Y}') \wedge (\mathbf{Y}' \leftrightarrow \mathbf{F}(\mathbf{X}))$$

- Suppose σ : satisfying assignment of E

How do we check if a given function is a correct Skolem function?

Given functions F_1, \dots, F_m , is $\forall \mathbf{X} (\exists \mathbf{Y} \varphi(\mathbf{X}, \mathbf{Y}) \Leftrightarrow \varphi(\mathbf{X}, \mathbf{F}(\mathbf{X})))$?

Can we avoid using a 2-QBF solver and stick to faster SAT-solvers?

Yes, we can! [John et al.'15]

- Propositional error formula:

$$E(\mathbf{X}, \mathbf{Y}, \mathbf{Y}') := \varphi(\mathbf{X}, \mathbf{Y}) \wedge \neg \varphi(\mathbf{X}, \mathbf{Y}') \wedge (\mathbf{Y}' \leftrightarrow \mathbf{F}(\mathbf{X}))$$

- Suppose σ : satisfying assignment of E
 - $\varphi(\sigma[\mathbf{X}], \sigma[\mathbf{Y}]) = 1$, $\sigma[\mathbf{Y}'] = \mathbf{F}(\sigma[\mathbf{X}])$, $\varphi(\sigma[\mathbf{X}], \sigma[(\mathbf{Y}')]) = 0$

How do we check if a given function is a correct Skolem function?

Given functions F_1, \dots, F_m , is $\forall \mathbf{X} (\exists \mathbf{Y} \varphi(\mathbf{X}, \mathbf{Y}) \Leftrightarrow \varphi(\mathbf{X}, \mathbf{F}(\mathbf{X})))$?

Can we avoid using a 2-QBF solver and stick to faster SAT-solvers?

Yes, we can! [John et al.'15]

- Propositional error formula:

$$E(\mathbf{X}, \mathbf{Y}, \mathbf{Y}') := \varphi(\mathbf{X}, \mathbf{Y}) \wedge \neg \varphi(\mathbf{X}, \mathbf{Y}') \wedge (\mathbf{Y}' \leftrightarrow \mathbf{F}(\mathbf{X}))$$

- Suppose σ : satisfying assignment of E
 - $\varphi(\sigma[\mathbf{X}], \sigma[\mathbf{Y}]) = 1$, $\sigma[\mathbf{Y}'] = \mathbf{F}(\sigma[\mathbf{X}])$, $\varphi(\sigma[\mathbf{X}], \sigma[(\mathbf{Y}')]) = 0$
 - σ is **counterexample** to the claim that F_1, \dots, F_m are all correct Skolem functions.

How do we check if a given function is a correct Skolem function?

Given functions F_1, \dots, F_m , is $\forall \mathbf{X} (\exists \mathbf{Y} \varphi(\mathbf{X}, \mathbf{Y}) \Leftrightarrow \varphi(\mathbf{X}, \mathbf{F}(\mathbf{X})))$?

Can we avoid using a 2-QBF solver and stick to faster SAT-solvers?

Yes, we can! [John et al.'15]

- Propositional error formula:

$$E(\mathbf{X}, \mathbf{Y}, \mathbf{Y}') := \varphi(\mathbf{X}, \mathbf{Y}) \wedge \neg \varphi(\mathbf{X}, \mathbf{Y}') \wedge (\mathbf{Y}' \leftrightarrow \mathbf{F}(\mathbf{X}))$$

- Suppose σ : satisfying assignment of E
 - $\varphi(\sigma[\mathbf{X}], \sigma[\mathbf{Y}]) = 1$, $\sigma[\mathbf{Y}'] = \mathbf{F}(\sigma[\mathbf{X}])$, $\varphi(\sigma[\mathbf{X}], \sigma[\mathbf{Y}']) = 0$
 - σ is **counterexample** to the claim that F_1, \dots, F_m are all correct Skolem functions.
- E unsatisfiable iff F_1, \dots, F_m are all correct Skolem functions.

$$E(X, Y, Y') := \varphi(X, Y) \wedge \neg\varphi(X, Y') \wedge (Y' \leftrightarrow F(X))$$

- Let $\sigma := \{x_1 \mapsto 1, x_2 \mapsto 1, y_1 \mapsto 1, y_2 \mapsto 1, y'_1 \mapsto 0, y'_2 \mapsto 0\}$ be a counter-example.

What to Repair?

- Idea: Repair all F_i where $\sigma[y_i] \neq \sigma[y'_i]$.

$$E(X, Y, Y') := \varphi(X, Y) \wedge \neg\varphi(X, Y') \wedge (Y' \leftrightarrow F(X))$$

- Let $\sigma := \{x_1 \mapsto 1, x_2 \mapsto 1, y_1 \mapsto 1, y_2 \mapsto 1, y'_1 \mapsto 0, y'_2 \mapsto 0\}$ be a counter-example.

What to Repair?

- Idea: Repair all F_i where $\sigma[y_i] \neq \sigma[y'_i]$.
- But $\varphi(X, Y)$ is Boolean Relation, say $\hat{\sigma} = \{x_1 \mapsto 1, x_2 \mapsto 1, y_1 \mapsto 0, y_2 \mapsto 1, y'_1 \mapsto 0, y'_2 \mapsto 0\}$
 - In this case, we don't need to repair F_1 .

$$E(X, Y, Y') := \varphi(X, Y) \wedge \neg\varphi(X, Y') \wedge (Y' \leftrightarrow F(X))$$

- Let $\sigma := \{x_1 \mapsto 1, x_2 \mapsto 1, y_1 \mapsto 1, y_2 \mapsto 1, y'_1 \mapsto 0, y'_2 \mapsto 0\}$ be a counter-example.

What to Repair?

- Idea: Repair all F_i where $\sigma[y_i] \neq \sigma[y'_i]$.
- But $\varphi(X, Y)$ is Boolean Relation, say $\hat{\sigma} = \{x_1 \mapsto 1, x_2 \mapsto 1, y_1 \mapsto 0, y_2 \mapsto 1, y'_1 \mapsto 0, y'_2 \mapsto 0\}$
 - In this case, we don't need to repair F_1 .
- **Improvement: MaxSAT-based Identification of nice counterexamples**
 - Hard Clauses $\varphi(X, Y) \wedge (X \leftrightarrow \sigma[X])$; Soft Clauses $(Y \leftrightarrow \sigma[Y'])$.

$$E(X, Y, Y') := \varphi(X, Y) \wedge \neg\varphi(X, Y') \wedge (Y' \leftrightarrow F(X))$$

- Let $\sigma := \{x_1 \mapsto 1, x_2 \mapsto 1, y_1 \mapsto 1, y_2 \mapsto 1, y'_1 \mapsto 0, y'_2 \mapsto 0\}$ be a counter-example.

What to Repair?

- Idea: Repair all F_i where $\sigma[y_i] \neq \sigma[y'_i]$.
- But $\varphi(X, Y)$ is Boolean Relation, say $\hat{\sigma} = \{x_1 \mapsto 1, x_2 \mapsto 1, y_1 \mapsto 0, y_2 \mapsto 1, y'_1 \mapsto 0, y'_2 \mapsto 0\}$
 - In this case, we don't need to repair F_1 .
- **Improvement: MaxSAT-based Identification of nice counterexamples**
 - Hard Clauses $\varphi(X, Y) \wedge (X \leftrightarrow \sigma[X])$; Soft Clauses $(Y \leftrightarrow \sigma[Y'])$.

How to Repair?

- For improved cex $\hat{\sigma}$, we want to repair F_2 .

$$E(X, Y, Y') := \varphi(X, Y) \wedge \neg\varphi(X, Y') \wedge (Y' \leftrightarrow F(X))$$

- Let $\sigma := \{x_1 \mapsto 1, x_2 \mapsto 1, y_1 \mapsto 1, y_2 \mapsto 1, y'_1 \mapsto 0, y'_2 \mapsto 0\}$ be a counter-example.

What to Repair?

- Idea: Repair all F_i where $\sigma[y_i] \neq \sigma[y'_i]$.
- But $\varphi(X, Y)$ is Boolean Relation, say $\hat{\sigma} = \{x_1 \mapsto 1, x_2 \mapsto 1, y_1 \mapsto 0, y_2 \mapsto 1, y'_1 \mapsto 0, y'_2 \mapsto 0\}$
 - In this case, we don't need to repair F_1 .
- **Improvement: MaxSAT-based Identification of nice counterexamples**
 - Hard Clauses $\varphi(X, Y) \wedge (X \leftrightarrow \sigma[X])$; Soft Clauses $(Y \leftrightarrow \sigma[Y'])$.

How to Repair?

- For improved cex $\hat{\sigma}$, we want to repair F_2 . Idea: From $\hat{\sigma}$: if $x_1 \wedge x_2 \wedge \neg y_1$, then set $y_2 = 1$.

$$E(X, Y, Y') := \varphi(X, Y) \wedge \neg\varphi(X, Y') \wedge (Y' \leftrightarrow F(X))$$

- Let $\sigma := \{x_1 \mapsto 1, x_2 \mapsto 1, y_1 \mapsto 1, y_2 \mapsto 1, y'_1 \mapsto 0, y'_2 \mapsto 0\}$ be a counter-example.

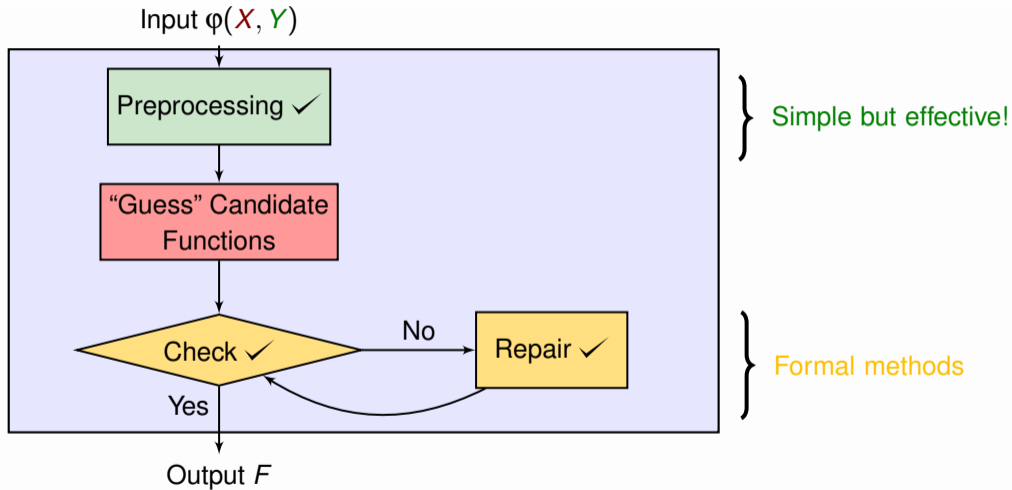
What to Repair?

- Idea: Repair all F_i where $\sigma[y_i] \neq \sigma[y'_i]$.
- But $\varphi(X, Y)$ is Boolean Relation, say $\hat{\sigma} = \{x_1 \mapsto 1, x_2 \mapsto 1, y_1 \mapsto 0, y_2 \mapsto 1, y'_1 \mapsto 0, y'_2 \mapsto 0\}$
 - In this case, we don't need to repair F_1 .
- **Improvement: MaxSAT-based Identification of nice counterexamples**
 - Hard Clauses $\varphi(X, Y) \wedge (X \leftrightarrow \sigma[X])$; Soft Clauses $(Y \leftrightarrow \sigma[Y'])$.

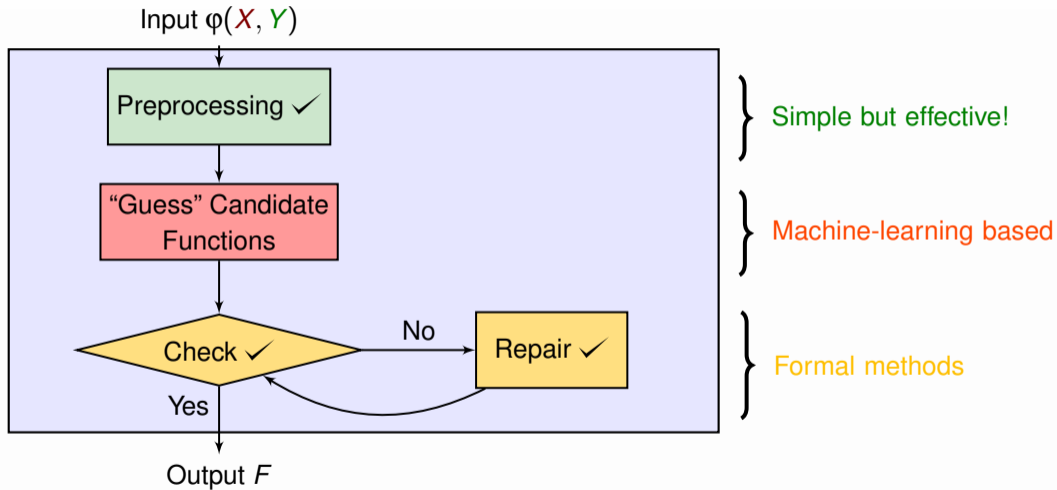
How to Repair?

- For improved cex $\hat{\sigma}$, we want to repair F_2 . Idea: From $\hat{\sigma}$: if $x_1 \wedge x_2 \wedge \neg y_1$, then set $y_2 = 1$.
- **Improvement: Use UNSAT Core of $\varphi(X, Y) \wedge x_1 \wedge x_2 \wedge \neg y_1 \wedge \neg y_2$.**

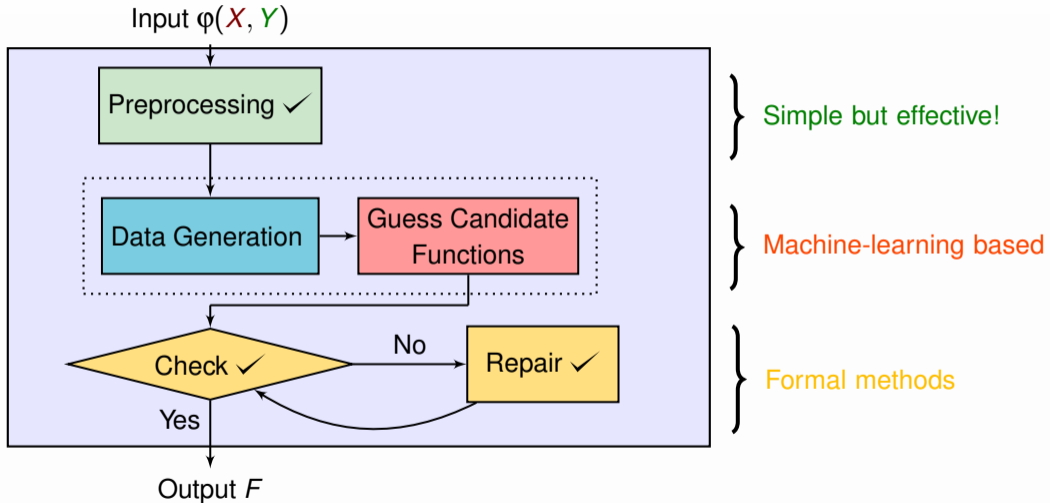
Deep Dive 1: Counter-example guided Skolem function generation



Deep Dive 1: Counter-example guided Skolem function generation



Machine-learning based guessing of candidate Skolem functions (Manthan)



Data Generation

Standing on the Shoulders of Constrained Samplers

$\varphi(x_1, x_2, y_1, y_2)$

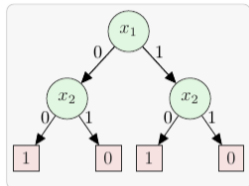


x_1	x_2	y_1	y_2
0	0	1	0
0	1	0	1
1	0	1	1
1	1	0	0

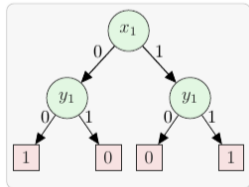
Learn Candidate Functions

Taming the Curse of Abstractions via Learning with Errors

x_1	x_2	y_1	y_2
0	0	1	0
0	1	0	1
1	0	1	1
1	1	0	0



$p_1 := (\neg x_1 \wedge \neg x_2)$,
 $p_2 := (x_1 \wedge \neg x_2)$
 $f_1 =$ if p_1 then 1
 elif p_2 then 1
 else 0



$p_1 := (\neg x_1 \wedge \neg y_1)$,
 $p_2 := (x_1 \wedge y_1)$
 $f_2 =$ if p_1 then 1
 elif p_2 then 1
 else 0

Potential Strategy: Randomly sample satisfying assignment of $\varphi(X, Y)$.

Challenge: Multiple valuations of y_1, y_2 for same valuation of x_1, x_2 .

Potential Strategy: Randomly sample satisfying assignment of $\varphi(X, Y)$.


Challenge: Multiple valuations of y_1, y_2 for same valuation of x_1, x_2 .

$$\varphi(x_1, x_2, y_1, y_2) : (x_1 \vee x_2 \vee y_1) \wedge (\neg x_1 \vee \neg x_2 \vee \neg y_2)$$

x_1	x_2	y_1	y_2
0	0	1	0/1
0	1	0/1	0/1
1	0	0/1	0/1
1	1	0/1	0

$$\varphi(x_1, x_2, y_1, y_2) : (x_1 \vee x_2 \vee y_1) \wedge (\neg x_1 \vee \neg x_2 \vee \neg y_2)$$

x_1	x_2	y_1	y_2
0	0	1	0/1
0	1	0/1	0/1
1	0	0/1	0/1
1	1	0/1	0

Uniform Sampler 

x_1	x_2	y_1	y_2
0	0	1	1
0	1	0	1
1	0	0	1
1	1	0	0

$$\varphi(x_1, x_2, y_1, y_2) : (x_1 \vee x_2 \vee y_1) \wedge (\neg x_1 \vee \neg x_2 \vee \neg y_2)$$

x_1	x_2	y_1	y_2
0	0	1	0/1
0	1	0/1	0/1
1	0	0/1	0/1
1	1	0/1	0

Uniform Sampler 

x_1	x_2	y_1	y_2
0	0	1	1
0	1	0	1
1	0	0	1
1	1	0	0

- Possible Skolem functions:

- $F_1(x_1, x_2) = \neg(x_1 \vee x_2)$
- $F_2(x_1, x_2) = \neg(x_1 \wedge x_2)$

$$\varphi(x_1, x_2, y_1, y_2) : (x_1 \vee x_2 \vee y_1) \wedge (\neg x_1 \vee \neg x_2 \vee \neg y_2)$$

x_1	x_2	y_1	y_2		x_1	x_2	y_1	y_2
0	0	1	0/1	<div style="display: flex; align-items: center; justify-content: center;"> <div style="margin-right: 10px;">Uniform Sampler</div> <div style="font-size: 2em;">→</div> </div>	0	0	1	1
0	1	0/1	0/1		0	1	0	1
1	0	0/1	0/1		1	0	0	1
1	1	0/1	0		1	1	0	0

- Possible Skolem functions:

- $F_1(x_1, x_2) = \neg(x_1 \vee x_2)$ $F_1(x_1, x_2) = \neg x_1$ $F_1(x_1, x_2) = \neg x_2$ $F_1(x_1, x_2) = 1$
- $F_2(x_1, x_2) = \neg(x_1 \wedge x_2)$ $F_2(x_1, x_2) = \neg x_1$ $F_2(x_1, x_2) = \neg x_2$ $F_2(x_1, x_2) = 0$

$$\varphi(x_1, x_2, y_1, y_2) : (x_1 \vee x_2 \vee y_1) \wedge (\neg x_1 \vee \neg x_2 \vee \neg y_2)$$

x_1	x_2	y_1	y_2		x_1	x_2	y_1	y_2
0	0	1	0/1	<div style="display: flex; align-items: center; justify-content: center;"> <div style="margin-right: 10px;">Magical Sampler</div> <div style="font-size: 2em;">→</div> </div>	0	0	1	0
0	1	0/1	0/1		0	1	1	0
1	0	0/1	0/1		1	0	1	0
1	1	0/1	0		1	1	1	0

- Possible Skolem functions:

- $F_1(x_1, x_2) = \neg(x_1 \vee x_2)$ $F_1(x_1, x_2) = \neg x_1$ $F_1(x_1, x_2) = \neg x_2$ $F_1(x_1, x_2) = 1$
- $F_2(x_1, x_2) = \neg(x_1 \wedge x_2)$ $F_2(x_1, x_2) = \neg x_1$ $F_2(x_1, x_2) = \neg x_2$ $F_2(x_1, x_2) = 0$

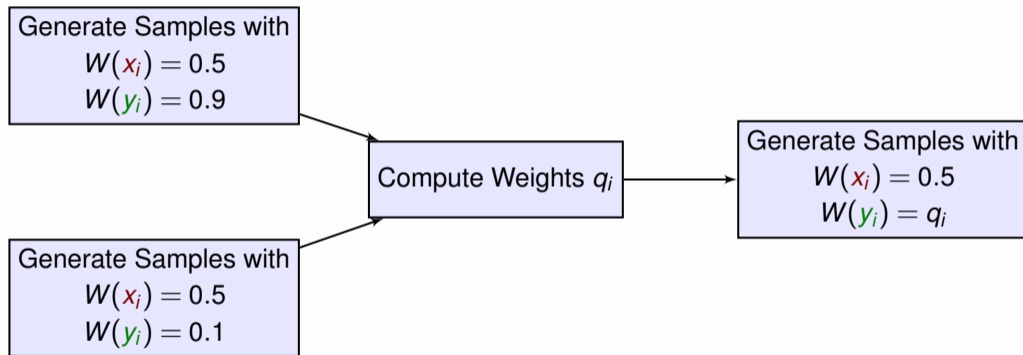
- $W : X \cup Y \mapsto [0, 1]$
- The probability of generation of an assignment is proportional to its weight.

$$W(\sigma) = \prod_{\sigma(z_i)=1} W(z_i) \prod_{\sigma(z_i)=0} (1 - W(z_i))$$

- Example: $W(x_1) = 0.5$ $W(x_2) = 0.5$ $W(y_1) = 0.9$ $W(y_2) = 0.1$
 $\sigma_1 = \{x_1 \mapsto 1, x_2 \mapsto 0, y_1 \mapsto 0, y_2 \mapsto 1\}$

$$W(\sigma_1) = 0.5 \times (1 - 0.5) \times (1 - 0.9) \times 0.1 = 0.0025$$

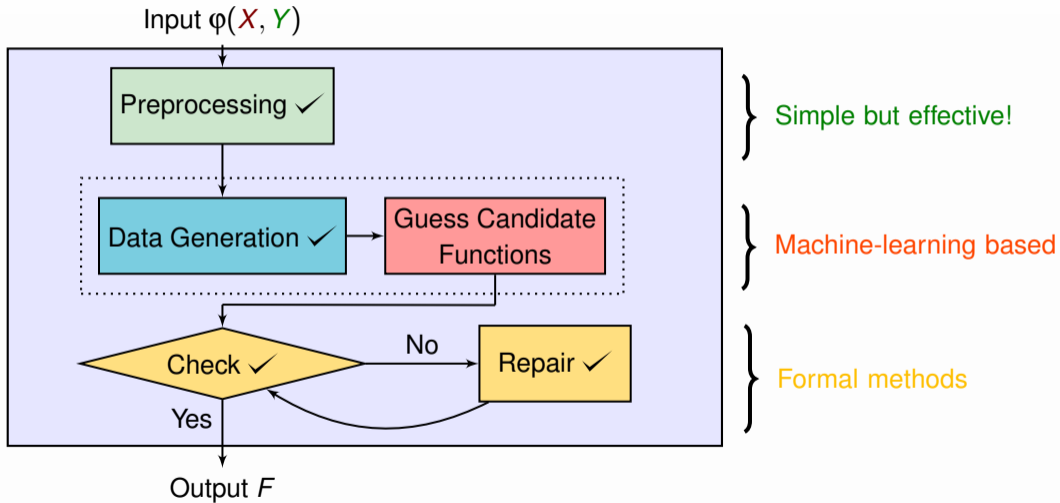
- Uniform sampling is a special case where all variables are assigned weight of 0.5.



Different Sampling Strategies

- Knowledge representation based techniques
 - (Yuan,Shultz, Pixley,Miller,Aziz 1999)
 - (Yuan,Aziz, Pixley,Albin, 2004)
 - (Kukula and Shiple, 2000)
 - (Sharma, Gupta, Meel, Roy, 2018)
 - (Gupta, Sharma, Meel, Roy, 2019)
- Hashing based techniques
 - (Chakraborty, Meel, and Vardi 2013, 2014,2015)
 - (Soos, Meel, and Gocht 2020)
- Mutation based techniques
 - (Dutra, Laeuffer, Bachrach, Sen, 2018)
- Markov Chain Monte Carlo based techniques
 - (Wei and Selman,2005)
 - (Kitchen,2010)
- Constraint solver based techniques
 - (Ermon, Gomes, Sabharwal, Selman,2012)
- Belief networks based techniques
 - (Dechter, Kask, Bin, Emek,2002)
 - (Gogate and Dechter,2006)

Machine-learning based guessing of candidate Skolem functions (Manthan)



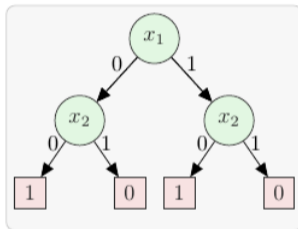
$$\varphi(x_1, x_2, y_1, y_2) : (x_1 \vee x_2 \vee y_1) \wedge (\neg x_1 \vee \neg x_2 \vee \neg y_2)$$

- To learn y_2
 - Feature set: valuation of x_1, x_2, y_1
 - Label: valuation of y_2
 - Learn decision tree to represent y_2 in terms of x_1, x_2, y_1
- To learn y_1
 - Feature set: valuation of x_1, x_2
 - Label: valuation of y_1
 - Learn decision tree to represent y_1 in terms of x_1, x_2

x_1	x_2	y_1	y_2
0	0	1	0
0	1	0	1
1	0	1	1
1	1	0	0

Learning Candidate Functions

x_1	x_2	y_1	y_2
0	0	1	0
0	1	0	1
1	0	1	1
1	1	0	0



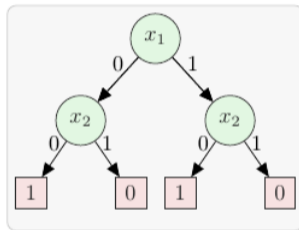
$$p_1 := (\neg x_1 \wedge \neg x_2),$$

$$p_2 := (x_1 \wedge \neg x_2)$$

$f_1 =$ if p_1 then 1
 elif p_2 then 1
 else 0

Learning Candidate Functions

x_1	x_2	y_1	y_2
0	0	1	0
0	1	0	1
1	0	1	1
1	1	0	0

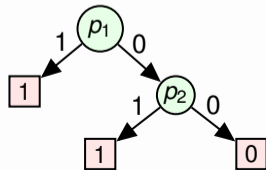


$$p_1 := (\neg x_1 \wedge \neg x_2),$$

$$p_2 := (x_1 \wedge \neg x_2)$$

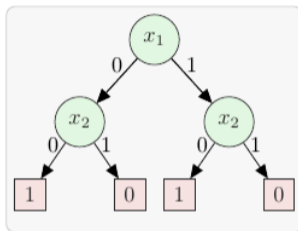
$f_1 =$ if p_1 then 1
 elif p_2 then 1
 else 0

Can reorder p_1, p_2
Learning one level decision list



What Kind of Learning

x_1	x_2	y_1	y_2
0	0	1	0
0	1	0	1
1	0	1	1
1	1	0	0



$$p_1 := (\neg x_1 \wedge \neg x_2),$$

$$p_2 := (x_1 \wedge \neg x_2)$$

$f_1 =$ if p_1 then 1
 elif p_2 then 1
 else 0

Learning without Error

Every row is a solution of $\varphi(X, Y)$

Learning with Errors

The data is only a subset of solutions.

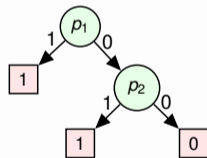
$$E(X, Y, Y') := \varphi(X, Y) \wedge \neg\varphi(X, Y') \wedge (Y' \leftrightarrow F(X))$$

- $\sigma \models E(X, Y, Y')$ be a counterexample to fix.
- Use MaxSAT to find a *nicer* counterexample σ'
- Repair patches: If $\underbrace{x_1 \wedge x_2 \wedge \neg y_1}_{\beta = \{x_1, x_2, \neg y_1\}}$ then $y_2 = 1$

Repair: Adding Level to Decision List

- Candidates are from one level decision list:
 - Learned decision tree: If p_1 then 1, elif p_2 then 1, else 0.
 - p_1, p_2 can be reordered.

Can reorder p_1, p_2 }

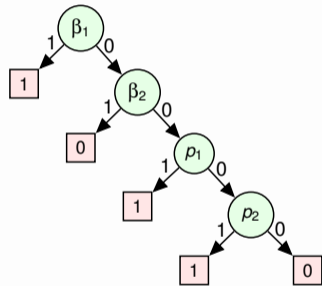


Repair: Adding Level to Decision List

- Candidates are from one level decision list:
 - Learned decision tree: If p_1 then 1, elif p_2 then 1, else 0.
 - p_1, p_2 can be reordered.
- Suppose in repair iterations, we have learned: If β_1 then 1, ... β_2 then 0
.....
- β_1 and β_2 can be reordered.
- From one-level decision list to two-level decision list.

Can reorder β_1, β_2

Can reorder p_1, p_2



$$\varphi(X, Y)$$

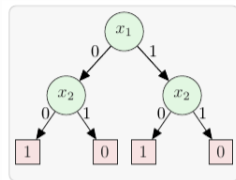
$$X = \{x_1, x_2\}$$

$$Y = \{y_1, y_2\}$$

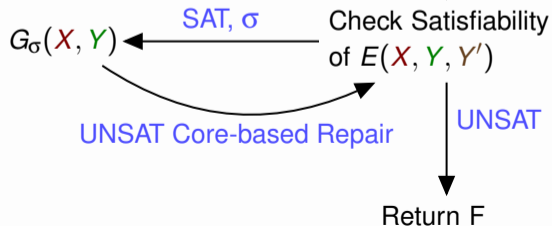
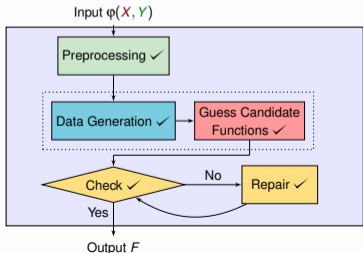
Data Generation

x_1	x_2	y_1	y_2
0	0	1	0
0	1	0	1
1	0	1	0
1	1	0	1

Learn Candidates



Verify Candidates



Deep Dive 2

Knowledge Compilation for Boolean Functional Synthesis

- The Guess-check-repair approach was **input-agnostic**.
- Suffers from worst-case exponential blowup (unavoidable due to hardness results).

- The Guess-check-repair approach was **input-agnostic**.
- Suffers from worst-case exponential blowup (unavoidable due to hardness results).

This leads us to ask

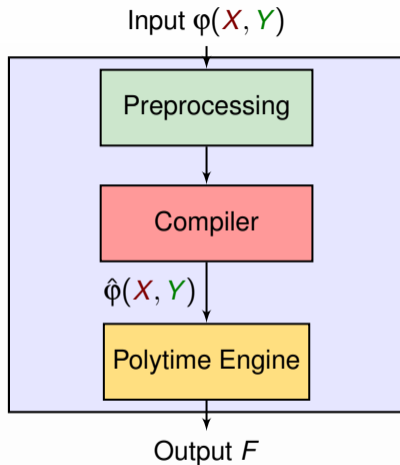
- Are there special properties of input specification which guarantee provably fast/small solutions?
- Can we develop new algorithms exploiting these properties?

- The Guess-check-repair approach was **input-agnostic**.
- Suffers from worst-case exponential blowup (unavoidable due to hardness results).

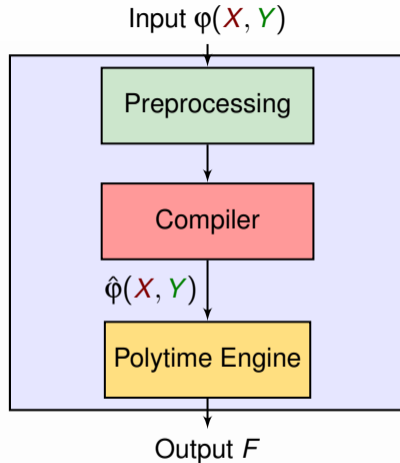
This leads us to ask

- Are there special properties of input specification which guarantee provably fast/small solutions?
- Can we develop new algorithms exploiting these properties?

Leads us to the rich area of Knowledge representations and Knowledge compilation.



Deep Dive 2: Knowledge Representations and Compilation for Synthesis



The question we will address in this deep dive...

What is $\hat{\phi}(X, Y)$, i.e., representation of input s.t., Polytime Engine suffices for synthesis?

Let's start with a simple case

What if there is only one output, i.e., $|\mathbf{Y}| = 1$.

Let's start with a simple case

What if there is only one output, i.e., $|\mathbf{Y}| = 1$.

1-output synthesis is easy: We don't even need to change the Spec!

Spec $\varphi(\mathbf{X}, y_1)$:

Let's start with a simple case

What if there is only one output, i.e., $|\mathbf{Y}| = 1$.

1-output synthesis is easy: We don't even need to change the Spec!

Spec $\varphi(\mathbf{X}, y_1)$: $\varphi(\mathbf{X}, 1)$ is a Skolem function for y_1 in $\varphi(\mathbf{X}, y_1)$

Let's start with a simple case

What if there is only one output, i.e., $|\mathbf{Y}| = 1$.

1-output synthesis is easy: We don't even need to change the Spec!

Spec $\varphi(\mathbf{X}, y_1)$: $\varphi(\mathbf{X}, 1)$ is a Skolem function for y_1 in $\varphi(\mathbf{X}, y_1)$

For any \mathbf{X} , we have $\exists y_1 \varphi(\mathbf{X}, y_1) \Leftrightarrow \varphi(\mathbf{X}, 1) \vee \varphi(\mathbf{X}, 0) \Leftrightarrow \varphi(\mathbf{X}, \varphi(\mathbf{X}, 1))$.

Let's start with a simple case

What if there is only one output, i.e., $|\mathbf{Y}| = 1$.

1-output synthesis is easy: We don't even need to change the Spec!

Spec $\varphi(\mathbf{X}, y_1)$: $\varphi(\mathbf{X}, 1)$ is a Skolem function for y_1 in $\varphi(\mathbf{X}, y_1)$

For any \mathbf{X} , we have $\exists y_1 \varphi(\mathbf{X}, y_1) \Leftrightarrow \varphi(\mathbf{X}, 1) \vee \varphi(\mathbf{X}, 0) \Leftrightarrow \varphi(\mathbf{X}, \varphi(\mathbf{X}, 1))$.

Corollary

- $\neg\varphi(\mathbf{X}, 0)$ is also a correct Skolem function.

Let's start with a simple case

What if there is only one output, i.e., $|\mathbf{Y}| = 1$.

1-output synthesis is easy: We don't even need to change the Spec!

Spec $\varphi(\mathbf{X}, y_1)$: $\varphi(\mathbf{X}, 1)$ is a Skolem function for y_1 in $\varphi(\mathbf{X}, y_1)$

For any \mathbf{X} , we have $\exists y_1 \varphi(\mathbf{X}, y_1) \Leftrightarrow \varphi(\mathbf{X}, 1) \vee \varphi(\mathbf{X}, 0) \Leftrightarrow \varphi(\mathbf{X}, \varphi(\mathbf{X}, 1))$.

Corollary

- $\neg\varphi(\mathbf{X}, 0)$ is also a correct Skolem function.
- Any interpolant between these two is also a correct Skolem function. Jiang '09, Trivedi '03.

Multi-output synthesis

Spec $\varphi(\mathbf{X}, y_1, \dots, y_m)$: Transform to 1-output synthesis

Multi-output synthesis

Spec $\varphi(\mathbf{X}, y_1, \dots, y_m)$: Transform to 1-output synthesis

- Construct *new spec* $\varphi'(\mathbf{X}, y_m) \equiv \exists y_1 \dots y_{m-1} \varphi$
 - Inputs \mathbf{X} , output y_m

Multi-output synthesis

Spec $\varphi(\mathbf{X}, y_1, \dots, y_m)$: Transform to 1-output synthesis

- Construct *new spec* $\varphi'(\mathbf{X}, y_m) \equiv \exists y_1 \dots y_{m-1} \varphi$
 - Inputs \mathbf{X} , output y_m
- Synthesize $F_m(\mathbf{X})$ for y_m from φ'

Multi-output synthesis

Spec $\varphi(\mathbf{X}, y_1, \dots, y_m)$: Transform to 1-output synthesis

- Construct *new spec* $\varphi'(\mathbf{X}, y_m) \equiv \exists y_1 \dots y_{m-1} \varphi$
 - Inputs \mathbf{X} , output y_m
- Synthesize $F_m(\mathbf{X})$ for y_m from φ'
- Construct *new spec* $\varphi''(\mathbf{X}, y_{m-1}, y_m) \equiv \exists y_1 \dots y_{m-2} \varphi$
 - Inputs \mathbf{X}, y_m ; output y_{m-1}

Multi-output synthesis

Spec $\varphi(\mathbf{X}, y_1, \dots, y_m)$: Transform to 1-output synthesis

- Construct *new spec* $\varphi'(\mathbf{X}, y_m) \equiv \exists y_1 \dots y_{m-1} \varphi$
 - Inputs \mathbf{X} , output y_m
- Synthesize $F_m(\mathbf{X})$ for y_m from φ'
- Construct *new spec* $\varphi''(\mathbf{X}, y_{m-1}, y_m) \equiv \exists y_1 \dots y_{m-2} \varphi$
 - Inputs \mathbf{X}, y_m ; output y_{m-1}
- Synthesize $F_{m-1}(\mathbf{X}, y_m)$ for y_{m-1} ; substitute $F_m(\mathbf{X})$ for y_m

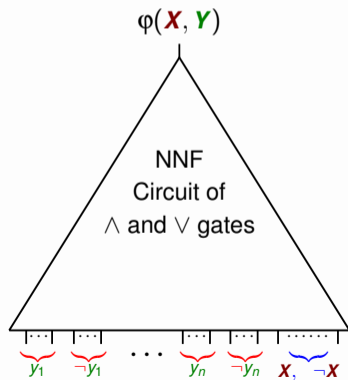
Multi-output synthesis

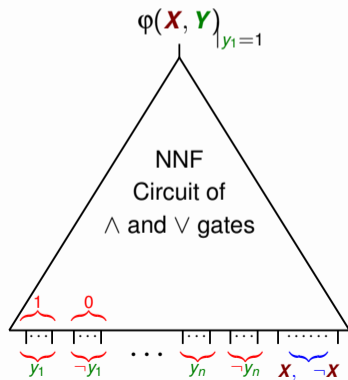
Spec $\varphi(\mathbf{X}, y_1, \dots, y_m)$: Transform to 1-output synthesis

- Construct *new spec* $\varphi'(\mathbf{X}, y_m) \equiv \exists y_1 \dots y_{m-1} \varphi$
 - Inputs \mathbf{X} , output y_m
- Synthesize $F_m(\mathbf{X})$ for y_m from φ'
- Construct *new spec* $\varphi''(\mathbf{X}, y_{m-1}, y_m) \equiv \exists y_1 \dots y_{m-2} \varphi$
 - Inputs \mathbf{X}, y_m ; output y_{m-1}
- Synthesize $F_{m-1}(\mathbf{X}, y_m)$ for y_{m-1} ; substitute $F_m(\mathbf{X})$ for y_m
- Repeat ...

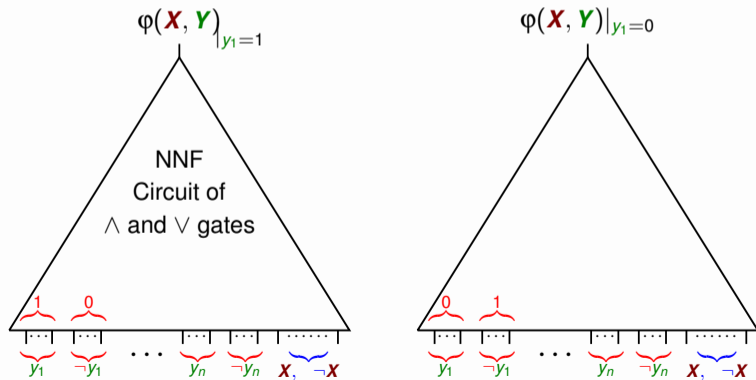
So, to compute Skolem functions, just need to efficiently compute

$$\exists y_1 \dots y_i \varphi(\mathbf{X}, y_1, \dots, y_m) \quad \forall i \in \{1, \dots, m\}$$

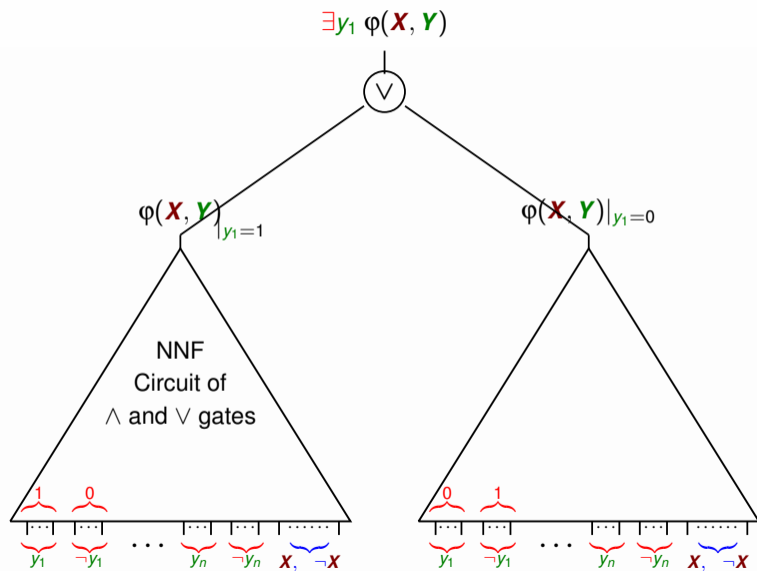




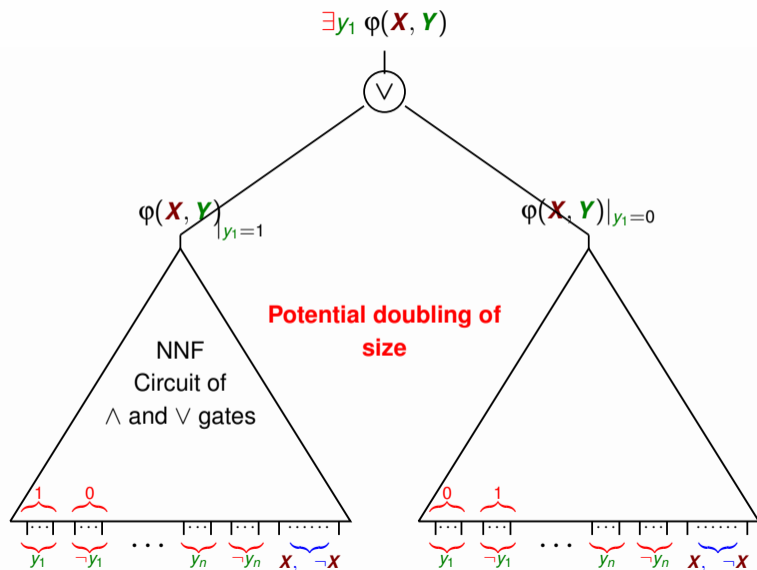
Existential Quantification with NNF circuits



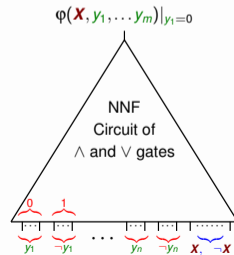
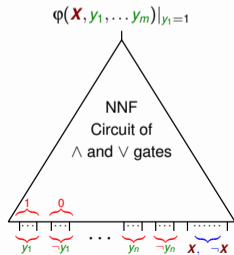
Existential Quantification with NNF circuits



Existential Quantification with NNF circuits

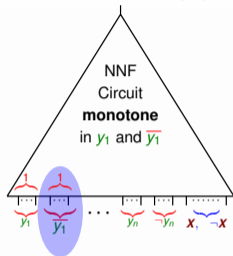


Over-approximating $\exists y_1 \varphi(X, Y)$ Sans Doubling

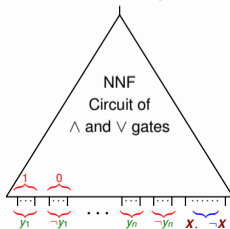


Over-approximating $\exists y_1 \varphi(X, Y)$ Sans Doubling

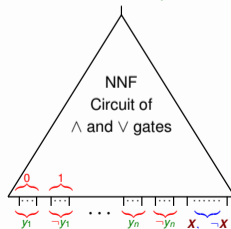
$$\widehat{\varphi}(X, y_1, \overline{y_1}, y_2, y_3, \dots, y_m) |_{y_1 = \overline{y_1} = 1}$$



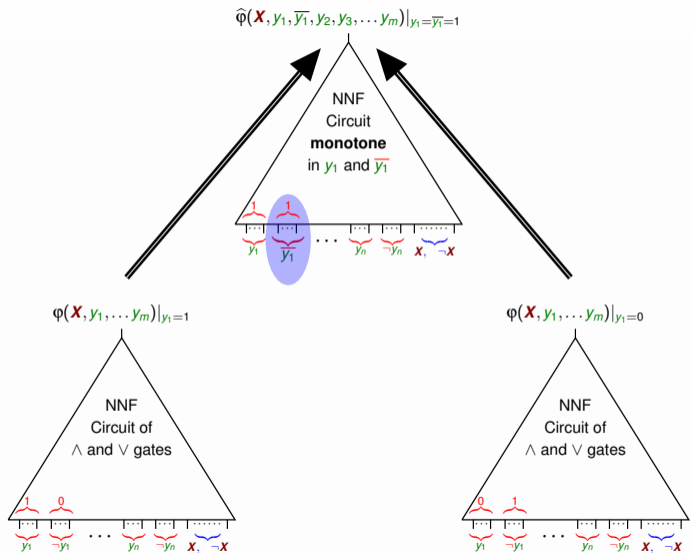
$$\varphi(X, y_1, \dots, y_m) |_{y_1 = 1}$$



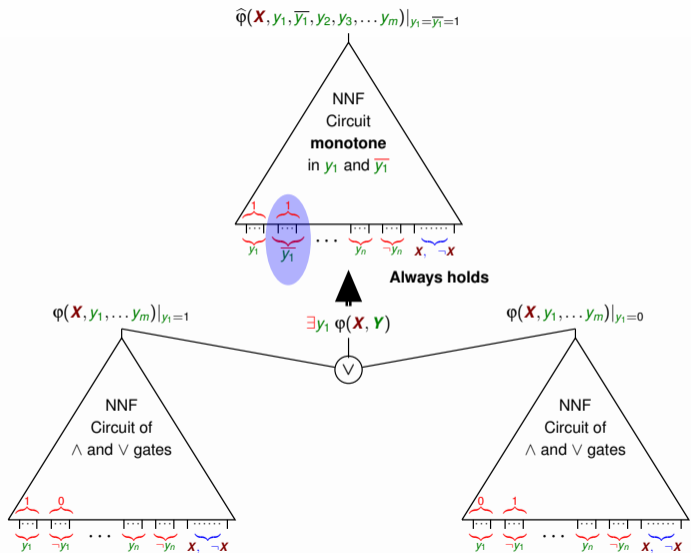
$$\varphi(X, y_1, \dots, y_m) |_{y_1 = 0}$$



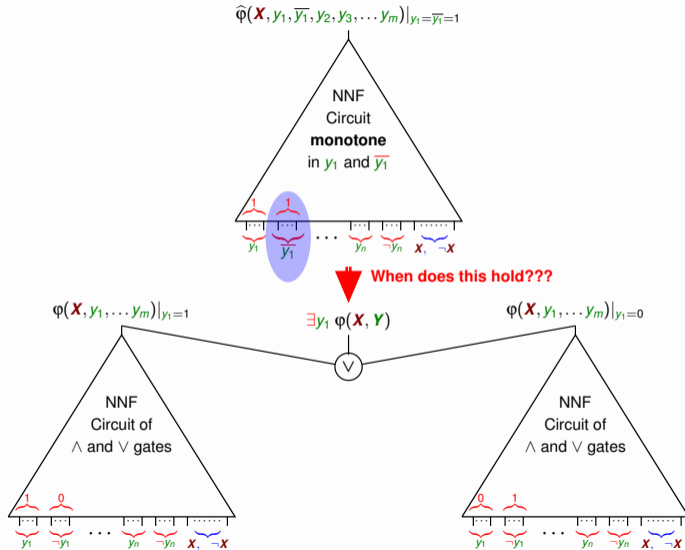
Over-approximating $\exists y_1 \varphi(X, Y)$ Sans Doubling



Over-approximating $\exists y_1 \varphi(X, Y)$ Sans Doubling



Can We Represent Quantification **Exactly** sans Blow-up?



Take first output: $\exists y_1 \varphi(\mathbf{X}, \mathbf{Y}) \Rightarrow \hat{\varphi} |_{y_1=1, \bar{y}_1=1}$.

Take first output: $\exists y_1 \varphi(\mathbf{X}, \mathbf{Y}) \Rightarrow \hat{\varphi} |_{y_1=1, \bar{y}_1=1}$. When does the reverse implication hold?

Take first output: $\exists y_1 \varphi(\mathbf{X}, \mathbf{Y}) \Rightarrow \hat{\varphi} |_{y_1=1, \bar{y}_1=1}$. When does the reverse implication hold?
Let's ask the opposite.

Take first output: $\exists y_1 \varphi(\mathbf{X}, \mathbf{Y}) \Rightarrow \hat{\varphi} |_{y_1=1, \bar{y}_1=1}$. When does the reverse implication hold?
Let's ask the opposite.

When do we have $\exists y_1 \varphi(\mathbf{X}, \mathbf{Y}) \not\equiv \hat{\varphi} |_{y_1=1, \bar{y}_1=1}$?

The positive form and existential quantification

Take first output: $\exists y_1 \varphi(\mathbf{X}, \mathbf{Y}) \Rightarrow \hat{\varphi} |_{y_1=1, \bar{y}_1=1}$. When does the reverse implication hold?
Let's ask the opposite.

When do we have $\exists y_1 \varphi(\mathbf{X}, \mathbf{Y}) \not\Leftarrow \hat{\varphi} |_{y_1=1, \bar{y}_1=1}$?

- Exactly when
 - $\hat{\varphi}_1 |_{y_1=1, \bar{y}_1=1} = 1$

Take first output: $\exists y_1 \varphi(\mathbf{X}, \mathbf{Y}) \Rightarrow \hat{\varphi} |_{y_1=1, \bar{y}_1=1}$. When does the reverse implication hold?
Let's ask the opposite.

When do we have $\exists y_1 \varphi(\mathbf{X}, \mathbf{Y}) \not\Leftarrow \hat{\varphi} |_{y_1=1, \bar{y}_1=1}$?

- Exactly when

- $\hat{\varphi}_1 |_{y_1=1, \bar{y}_1=1} = 1$
- $\exists y_1 \varphi(\mathbf{X}, \mathbf{Y}) \Leftrightarrow \varphi |_{y_1=1} \vee \varphi |_{y_1=0} = 0$
 - ▶ $\varphi |_{y_1=1} \Leftrightarrow \hat{\varphi} |_{y_1=1, \bar{y}_1=0} = 0$
 - ▶ $\varphi |_{y_1=0} \Leftrightarrow \hat{\varphi} |_{y_1=0, \bar{y}_1=1} = 0$

The positive form and existential quantification

Take first output: $\exists y_1 \varphi(\mathbf{X}, \mathbf{Y}) \Rightarrow \hat{\varphi} |_{y_1=1, \bar{y}_1=1}$. When does the reverse implication hold?
Let's ask the opposite.

When do we have $\exists y_1 \varphi(\mathbf{X}, \mathbf{Y}) \not\equiv \hat{\varphi} |_{y_1=1, \bar{y}_1=1}$?

- Exactly when

- $\hat{\varphi}_1 |_{y_1=1, \bar{y}_1=1} = 1$
- $\exists y_1 \varphi(\mathbf{X}, \mathbf{Y}) \Leftrightarrow \varphi |_{y_1=1} \vee \varphi |_{y_1=0} = 0$
 - ▶ $\varphi |_{y_1=1} \Leftrightarrow \hat{\varphi} |_{y_1=1, \bar{y}_1=0} = 0$
 - ▶ $\varphi |_{y_1=0} \Leftrightarrow \hat{\varphi} |_{y_1=0, \bar{y}_1=1} = 0$
 - ▶ (By monotonicity of $\hat{\varphi}$ w.r.t y_1 and \bar{y}_1) $\hat{\varphi} |_{y_1=0, \bar{y}_1=0} = 0$

y_1	\bar{y}_1	$\hat{\varphi}$
1	1	1
1	0	0
0	1	0
0	0	0

The positive form and existential quantification

Take first output: $\exists y_1 \varphi(\mathbf{X}, \mathbf{Y}) \Rightarrow \hat{\varphi} |_{y_1=1, \bar{y}_1=1}$. When does the reverse implication hold?

Let's ask the opposite.

When do we have $\exists y_1 \varphi(\mathbf{X}, \mathbf{Y}) \not\equiv \hat{\varphi} |_{y_1=1, \bar{y}_1=1}$?

- Exactly when

- $\hat{\varphi}_1 |_{y_1=1, \bar{y}_1=1} = 1$

- $\exists y_1 \varphi(\mathbf{X}, \mathbf{Y}) \Leftrightarrow \varphi |_{y_1=1} \vee \varphi |_{y_1=0} = 0$

- ▶ $\varphi |_{y_1=1} \Leftrightarrow \hat{\varphi} |_{y_1=1, \bar{y}_1=0} = 0$

- ▶ $\varphi |_{y_1=0} \Leftrightarrow \hat{\varphi} |_{y_1=0, \bar{y}_1=1} = 0$

- ▶ (By monotonicity of $\hat{\varphi}$ w.r.t y_1 and \bar{y}_1) $\hat{\varphi} |_{y_1=0, \bar{y}_1=0} = 0$

- For some values for other outputs and inputs, $\hat{\varphi} \equiv y_1 \wedge \bar{y}_1$.

y_1	\bar{y}_1	$\hat{\varphi}$
1	1	1
1	0	0
0	1	0
0	0	0

The positive form and existential quantification

Take first output: $\exists y_1 \varphi(\mathbf{X}, \mathbf{Y}) \Rightarrow \hat{\varphi} |_{y_1=1, \bar{y}_1=1}$. When does the reverse implication hold?
Let's ask the opposite.

When do we have $\exists y_1 \varphi(\mathbf{X}, \mathbf{Y}) \neq \hat{\varphi} |_{y_1=1, \bar{y}_1=1}$?

- Exactly when
 - $\hat{\varphi}_1 |_{y_1=1, \bar{y}_1=1} = 1$
 - $\exists y_1 \varphi(\mathbf{X}, \mathbf{Y}) \Leftrightarrow \varphi |_{y_1=1} \vee \varphi |_{y_1=0} = 0$
 - ▶ $\varphi |_{y_1=1} \Leftrightarrow \hat{\varphi} |_{y_1=1, \bar{y}_1=0} = 0$
 - ▶ $\varphi |_{y_1=0} \Leftrightarrow \hat{\varphi} |_{y_1=0, \bar{y}_1=1} = 0$
 - ▶ (By monotonicity of $\hat{\varphi}$ w.r.t y_1 and \bar{y}_1) $\hat{\varphi} |_{y_1=0, \bar{y}_1=0} = 0$
- For some values for other outputs and inputs, $\hat{\varphi} \equiv y_1 \wedge \bar{y}_1$.

y_1	\bar{y}_1	$\hat{\varphi}$
1	1	1
1	0	0
0	1	0
0	0	0

So, what should we avoid?

- For some values for the other variables, we have $\hat{\varphi} \Leftrightarrow y_1 \wedge \bar{y}_1$.

The positive form and existential quantification

Take first output: $\exists y_1 \varphi(\mathbf{X}, \mathbf{Y}) \Rightarrow \widehat{\varphi} |_{y_1=1, \overline{y_1}=1}$. When does the reverse implication hold?
Let's ask the opposite.

When do we have $\exists y_1 \varphi(\mathbf{X}, \mathbf{Y}) \not\equiv \widehat{\varphi} |_{y_1=1, \overline{y_1}=1}$?

- Exactly when
 - $\widehat{\varphi}_1 |_{y_1=1, \overline{y_1}=1} = 1$
 - $\exists y_1 \varphi(\mathbf{X}, \mathbf{Y}) \Leftrightarrow \varphi |_{y_1=1} \vee \varphi |_{y_1=0} = 0$
 - ▶ $\varphi |_{y_1=1} \Leftrightarrow \widehat{\varphi} |_{y_1=1, \overline{y_1}=0} = 0$
 - ▶ $\varphi |_{y_1=0} \Leftrightarrow \widehat{\varphi} |_{y_1=0, \overline{y_1}=1} = 0$
 - ▶ (By monotonicity of $\widehat{\varphi}$ w.r.t y_1 and $\overline{y_1}$) $\widehat{\varphi} |_{y_1=0, \overline{y_1}=0} = 0$
- For some values for other outputs and inputs, $\widehat{\varphi} \equiv y_1 \wedge \overline{y_1}$.

y_1	$\overline{y_1}$	$\widehat{\varphi}$
1	1	1
1	0	0
0	1	0
0	0	0

So, what should we avoid?

- For some values for the other variables, we have $\widehat{\varphi} \Leftrightarrow y_1 \wedge \overline{y_1}$.
- If we can avoid it, we get $\exists y_1 \varphi(\mathbf{X}, \mathbf{Y}) \Leftrightarrow \widehat{\varphi} |_{y_1=1, \overline{y_1}=1}$

The positive form and existential quantification

Take first output: $\exists y_1 \varphi(\mathbf{X}, \mathbf{Y}) \Rightarrow \widehat{\varphi} |_{y_1=1, \overline{y_1}=1}$. When does the reverse implication hold?
Let's ask the opposite.

When do we have $\exists y_1 \varphi(\mathbf{X}, \mathbf{Y}) \neq \widehat{\varphi} |_{y_1=1, \overline{y_1}=1}$?

- Exactly when
 - $\widehat{\varphi} |_{y_1=1, \overline{y_1}=1} = 1$
 - $\exists y_1 \varphi(\mathbf{X}, \mathbf{Y}) \Leftrightarrow \varphi |_{y_1=1} \vee \varphi |_{y_1=0} = 0$
 - ▶ $\varphi |_{y_1=1} \Leftrightarrow \widehat{\varphi} |_{y_1=1, \overline{y_1}=0} = 0$
 - ▶ $\varphi |_{y_1=0} \Leftrightarrow \widehat{\varphi} |_{y_1=0, \overline{y_1}=1} = 0$
 - ▶ (By monotonicity of $\widehat{\varphi}$ w.r.t y_1 and $\overline{y_1}$) $\widehat{\varphi} |_{y_1=0, \overline{y_1}=0} = 0$
- For some values for other outputs and inputs, $\widehat{\varphi} \equiv y_1 \wedge \overline{y_1}$.

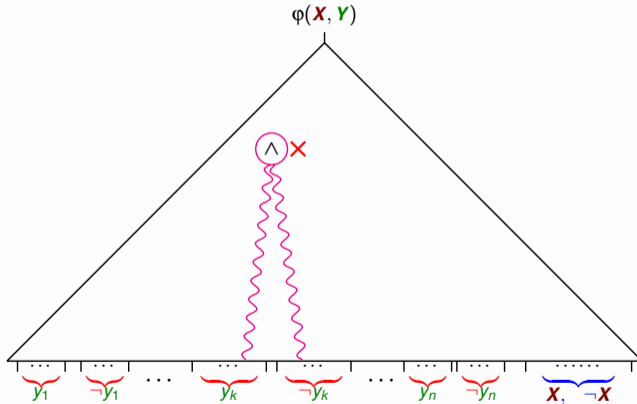
y_1	$\overline{y_1}$	$\widehat{\varphi}$
1	1	1
1	0	0
0	1	0
0	0	0

So, what should we avoid?

- For some values for the other variables, we have $\widehat{\varphi} \Leftrightarrow y_1 \wedge \overline{y_1}$.
- If we can avoid it, we get $\exists y_1 \varphi(\mathbf{X}, \mathbf{Y}) \Leftrightarrow \widehat{\varphi} |_{y_1=1, \overline{y_1}=1}$
- Can generalize this to multiple outputs...

A simple yet special Normal Form

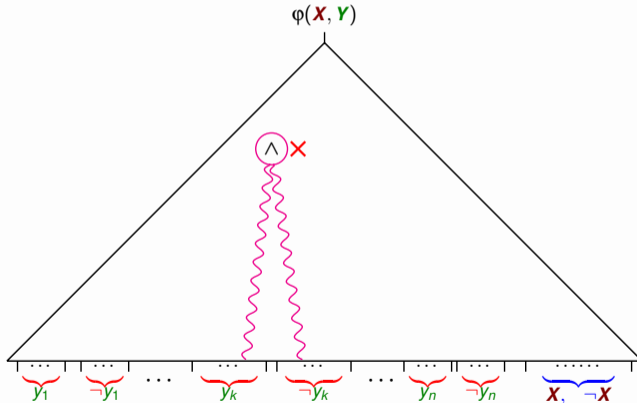
- Weak Decomposable Negation Normal Form (wDNNF)*: **Forbidden structure/syntax**



* S. Akshay, Supratik Chakraborty, Shubham Goel, Sumith Kulal, Shetal Shah, CAV'18.

A simple yet special Normal Form

- Weak Decomposable Negation Normal Form (wDNNF)*: **Forbidden structure/syntax**
- Generalizes DNNF[†], well-studied in KR community.

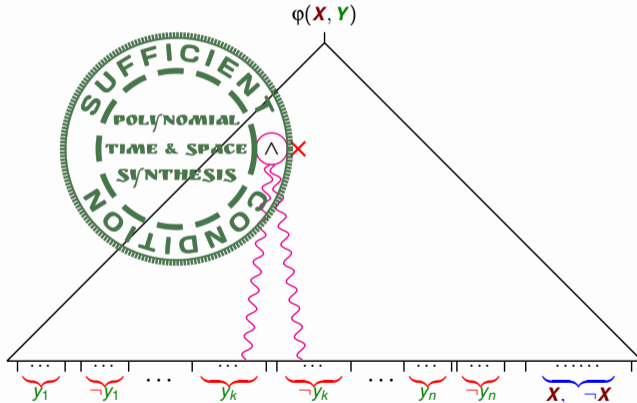


* S. Akshay, Supratik Chakraborty, Shubham Goel, Sumith Kulal, Shetal Shah, CAV'18.

† Adnan Darwiche, J. ACM '01

A simple yet special Normal Form

- Weak Decomposable Negation Normal Form (wDNNF)*: **Forbidden structure/syntax**
- Generalizes DNNF[†], well-studied in KR community.

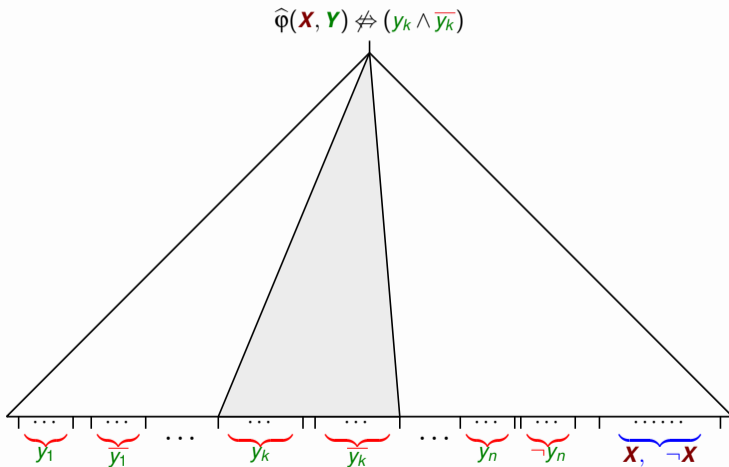


* S. Akshay, Supratik Chakraborty, Shubham Goel, Sumith Kulal, Shetal Shah, CAV'18.

† Adnan Darwiche, J. ACM '01

A semantic Normal Form

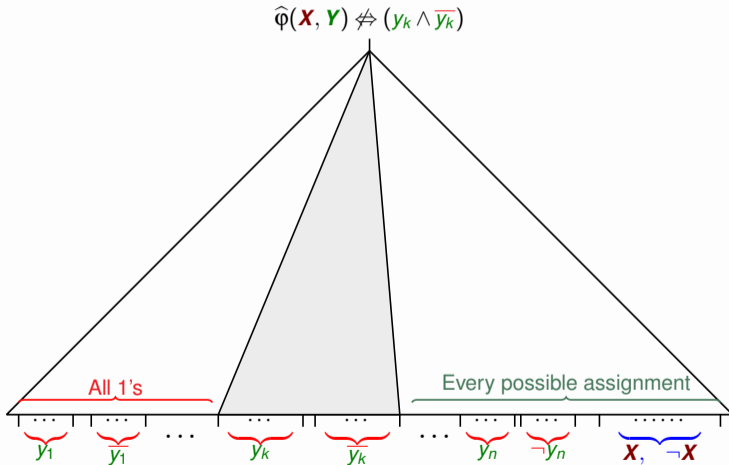
- Synthesis Negation Normal Form (SynNNF)*: **Forbidden semantics**



* S. Akshay, J. Arora, S. Chakraborty, S. Krishna, D. Raghunathan, S. Shah, FMCAD'19.

A semantic Normal Form

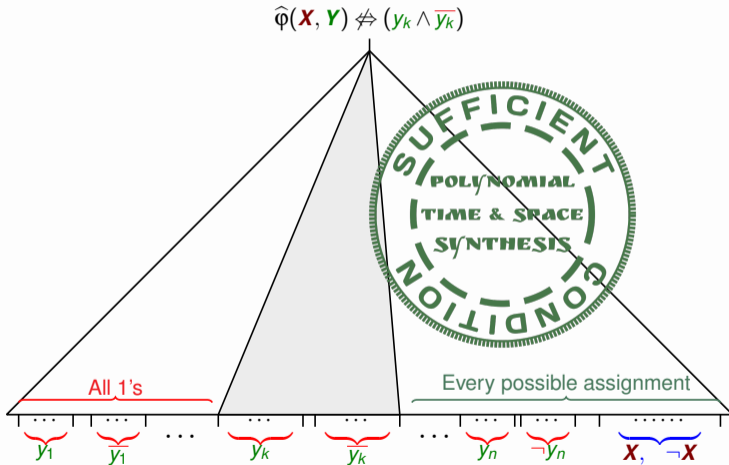
- Synthesis Negation Normal Form (SynNNF)*: **Forbidden semantics**



* S. Akshay, J. Arora, S. Chakraborty, S. Krishna, D. Raghunathan, S. Shah, FMCAD'19.

A semantic Normal Form

- Synthesis Negation Normal Form (SynNNF)*: **Forbidden semantics**



* S. Akshay, J. Arora, S. Chakraborty, S. Krishna, D. Raghunathan, S. Shah, FMCAD'19.

Skolem fn for y_i (in terms of $y_{i+1}, \dots, y_m, \mathbf{X}$)

- $\exists y_1, \dots, y_{i-1} \varphi(\mathbf{X}, y_1, \dots, y_{i-1}, 1, y_{i+1}, \dots, y_m)$

Skolem fn for y_i (in terms of $y_{i+1}, \dots, y_m, \mathbf{X}$)

- $\exists y_1, \dots, y_{i-1} \varphi(\mathbf{X}, y_1, \dots, y_{i-1}, 1, y_{i+1}, \dots, y_m)$
- Equivalently, $\hat{\varphi} \mid_{y_1=1, \bar{y}_1=1, \dots, y_{i-1}=1, \bar{y}_{i-1}=1, y_i=1, \bar{y}_i=0}$, if φ in SynNNF

Skolem fn for y_i (in terms of $y_{i+1}, \dots, y_m, \mathbf{X}$)

- $\exists y_1, \dots, y_{i-1} \varphi(\mathbf{X}, y_1, \dots, y_{i-1}, 1, y_{i+1}, \dots, y_m)$
- Equivalently, $\hat{\varphi} \mid_{y_1=1, \bar{y}_1=1, \dots, y_{i-1}=1, \bar{y}_{i-1}=1, y_i=1, \bar{y}_i=0}$, if φ in SynNNF

Poly-time/sized Skolem functions!

Skolem fn for y_i (in terms of $y_{i+1}, \dots, y_m, \mathbf{X}$)

- $\exists y_1, \dots, y_{i-1} \varphi(\mathbf{X}, y_1, \dots, y_{i-1}, 1, y_{i+1}, \dots, y_m)$
- Equivalently, $\hat{\varphi} \mid_{y_1=1, \bar{y}_1=1, \dots, y_{i-1}=1, \bar{y}_{i-1}=1, y_i=1, \bar{y}_i=0}$, if φ in SynNNF

Poly-time/sized Skolem functions!

Observations:

- Not purely structural restriction on representation of φ

Skolem fn for y_i (in terms of $y_{i+1}, \dots, y_m, \mathbf{X}$)

- $\exists y_1, \dots, y_{i-1} \varphi(\mathbf{X}, y_1, \dots, y_{i-1}, 1, y_{i+1}, \dots, y_m)$
- Equivalently, $\hat{\varphi} \mid_{y_1=1, \bar{y}_1=1, \dots, y_{i-1}=1, \bar{y}_{i-1}=1, y_i=1, \bar{y}_i=0}$, if φ in SynNNF

Poly-time/sized Skolem functions!

Observations:

- Not purely structural restriction on representation of φ
- Reminiscent of Deterministic DNNF (dDNNF)*
 - For every \vee node representing $\varphi_1 \vee \varphi_2$, require $\varphi_1 \wedge \varphi_2 = \perp$.

Comparing the Normal Forms

- Every wDNNF, DNNF circuit is also in SynNNF.
- Every FBDD, ROBDD can be compiled in linear time to SynNNF.

Comparing the Normal Forms

- Every wDNNF, DNNF circuit is also in SynNNF.
- Every FBDD, ROBDD can be compiled in linear time to SynNNF.

SynNNF is strictly weaker/more succinct than wDNNF, DNNF, FBDD, ROBDD

Comparing the Normal Forms

- Every wDNNF, DNNF circuit is also in SynNNF.
- Every FBDD, ROBDD can be compiled in linear time to SynNNF.

SynNNF is strictly weaker/more succinct than wDNNF, DNNF, FBDD, ROBDD

Punchline!

SynNNF is **exponentially more succinct** than DNNF/dDNNF

Comparing the Normal Forms

- Every wDNNF, DNNF circuit is also in SynNNF.
- Every FBDD, ROBDD can be compiled in linear time to SynNNF.

SynNNF is strictly weaker/more succinct than wDNNF, DNNF, FBDD, ROBDD

Punchline!

SynNNF is **exponentially more succinct** than DNNF/dDNNF, which are themselves **exponentially more succinct** than ROBDDs/FBDD.

Comparing the Normal Forms

- Every wDNNF, DNNF circuit is also in SynNNF.
- Every FBDD, ROBDD can be compiled in linear time to SynNNF.

SynNNF is strictly weaker/more succinct than wDNNF, DNNF, FBDD, ROBDD

Punchline!

SynNNF is **exponentially more succinct** than DNNF/dDNNF, which are themselves **exponentially more succinct** than ROBDDs/FBDD.

What more can we do?

Comparing the Normal Forms

- Every wDNNF, DNNF circuit is also in SynNNF.
- Every FBDD, ROBDD can be compiled in linear time to SynNNF.

SynNNF is strictly weaker/more succinct than wDNNF, DNNF, FBDD, ROBDD

Punchline!

SynNNF is **exponentially more succinct** than DNNF/dDNNF, which are themselves **exponentially more succinct** than ROBDDs/FBDD.

What more can we do?

- Does there exist a necessary and sufficient condition for efficient synthesis?

Comparing the Normal Forms

- Every wDNNF, DNNF circuit is also in SynNNF.
- Every FBDD, ROBDD can be compiled in linear time to SynNNF.

SynNNF is strictly weaker/more succinct than wDNNF, DNNF, FBDD, ROBDD

Punchline!

SynNNF is **exponentially more succinct** than DNNF/dDNNF, which are themselves **exponentially more succinct** than ROBDDs/FBDD.

What more can we do?

- Does there exist a necessary and sufficient condition for efficient synthesis?
- **Subset-And-Unrealizable Normal Form (SAUNF)** P. Shah, A. Bansal, S. Akshay, S. Chakraborty, LICS'21.

- What about general classes of specs?
 - CNF specs: NNF circuits don't always admit efficient synthesis

- What about general classes of specs?
 - CNF specs: NNF circuits don't always admit efficient synthesis

Compiling CNF to SynNNF [Akshay et al. FMCAD'19.]

- Algorithm for compilation: uses ideas from dDNNF-compilation and more
- Prototype implementation C2Syn
- Worst-case exponential-time and space
 - Unavoidable due to hardness results

- What about general classes of specs?
 - CNF specs: NNF circuits don't always admit efficient synthesis

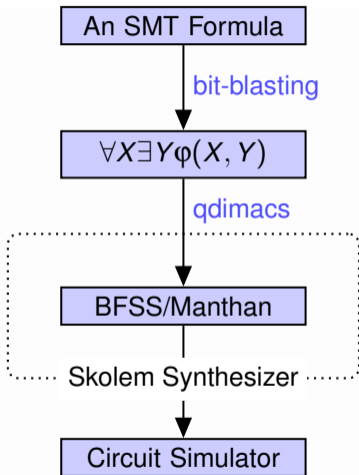
Compiling CNF to SynNNF [Akshay et al. FMCAD'19.]

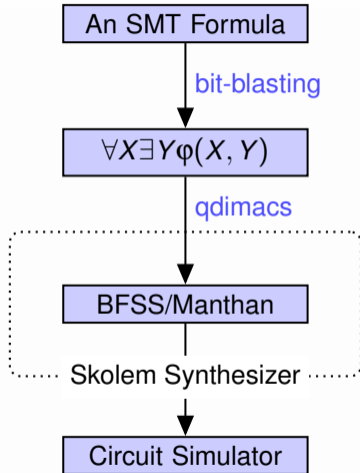
- Algorithm for compilation: uses ideas from dDNNF-compilation and more
- Prototype implementation C2Syn
- Worst-case exponential-time and space
 - Unavoidable due to hardness results

Compiling CNF to SAUNF [Shah et al. LICS'21.]

- Algorithm for compilation
- Future work: Implementation and comparisons!

- 1 Application Domains
- 2 Theoretical Hardness and Practical Algorithms
- 3 Deep Dives
- 4 Tool Demo**
- 5 Conclusion and the Way Forward

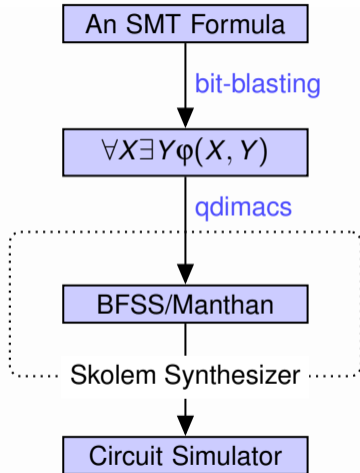




```
1 (set-logic BV)
2 ;; out function with two 2 bit arguments
3 (declare-fun out ( (_ BitVec 2) (_ BitVec 2)) (_ BitVec 2))
4 ;; declaring the constant
5 (declare-const inp1 (_ BitVec 2))
6 (declare-const inp2 (_ BitVec 2))
7 ;; output of out function should be greater than or equal to first input
8 (assert (bvuge (out inp1 inp2) inp1))
9 ;; output of out function should be greater than or equal to second input
10 (assert (bvuge (out inp1 inp2) inp2))
11 ;; output of out function should be either be equal to first input
12 ;; or to the second input
13 (assert (or (= inp1 (out inp1 inp2)) (= inp2 (out inp1 inp2))))
14 (check-sat)
```

An SMT formula

Tool Demo: Pipeline

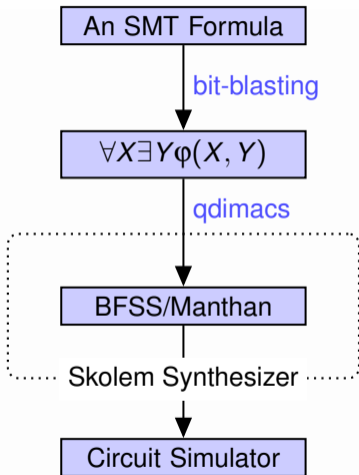


```
1 (set-logic BV)
2 ;; out function with two 2 bit arguments
3 (declare-fun out ( (_ BitVec 2) (_ BitVec 2)) (_ BitVec 2))
4 ;; declaring the constant
5 (declare-const inp1 (_ BitVec 2))
6 (declare-const inp2 (_ BitVec 2))
7 ;; output of out function should be greater than or equal to first input
8 (assert (bvuge (out inp1 inp2) inp1))
9 ;; output of out function should be greater than or equal to second input
10 (assert (bvuge (out inp1 inp2) inp2))
11 ;; output of out function should be either be equal to first input
12 ;; or to the second input
13 (assert (or (= inp1 (out inp1 inp2)) (= inp2 (out inp1 inp2))))
14 (check-sat)
```

An SMT formula

```
1 p cnf 12 32
2 a 3 5 7 8 0
3 e 1 2 4 6 9 10 11 12 0
4 1 -2 0
5 3 1 0
6 2 -3 -1 0
7 4 -5 0
8 1 -5 0
9 4 1 0
10 -2 6 0
11 6 0
12 2 -7 -6 0
13 4 -8 0
14 -8 6 0
15 4 6 0
16 -4 -8 -9 0
```

Qdimacs formula

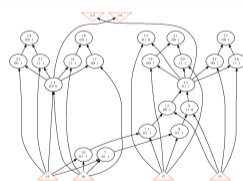


```
1 (set-logic BV)
2 ;; out function with two 2 bit arguments
3 (declare-fun out ( (_ BitVec 2) (_ BitVec 2)) (_ BitVec 2))
4 ;; declaring the constant
5 (declare-const inp1 (_ BitVec 2))
6 (declare-const inp2 (_ BitVec 2))
7 ;; output of out function should be greater than or equal to first input
8 (assert (bvuge (out inp1 inp2) inp1))
9 ;; output of out function should be greater than or equal to second input
10 (assert (bvuge (out inp1 inp2) inp2))
11 ;; output of out function should be either be equal to first input
12 ;; or to the second input
13 (assert (or (= inp1 (out inp1 inp2)) (= inp2 (out inp1 inp2))))
14 (check-sat)
```

An SMT formula

```
1 p cnf 12 32
2 a 3 5 7 8 0
3 e 1 2 4 6 9 10 11 12 0
4 1 -2 0
5 3 1 0
6 2 -3 -1 0
7 4 -5 0
8 1 -5 0
9 4 1 0
10 -2 6 0
11 7 6 0
12 2 -7 -6 0
13 4 -8 0
14 -8 6 0
15 4 6 0
16 -4 -8 -9 0
```

Qdimacs formula



Synthesized Skolem function

- 1 Application Domains
- 2 Theoretical Hardness and Practical Algorithms
- 3 Deep Dives
- 4 Tool Demo
- 5 Conclusion and the Way Forward**

- Functional Synthesis is a fundamental problem with wide variety of applications
 - program synthesis, games and planning, circuit repair
- Long history of work that has sought to push the scalability envelope
- An exciting and diverse set of approaches
 - Guess, check, and repair
 - Knowledge representation
- Promise of scalability: Out of 609 benchmarks
 - 2018 247 solved
 - 2019 280 solved
 - 2020 356 solved
 - 2021 509 solved

Where do we go from here?

1. Benchmarks
2. Notion of Quality
3. Beyond Single Functions
4. Beyond Propositional Logic

Promise of scalability: Out of 609 benchmarks

2018 SOTA 247 solved

2019 SOTA 280 solved

2020 SOTA 356 solved

2021 SOTA 509 solved

B. Cook, 2022: Virtuous cycle in Automated Reasoning: ...application areas drives more investment in foundational tools, while improvements in the foundational tools drive further applications. Around and around.

- The current formulation allows the solver to find an arbitrary functions
- Opportunity to formalize the notion of quality
- Smaller size?
- Uses gates of particular type?
- Readable?

- Enumeration of functions: Knowledge compilation
- Uniform sampling of functions: randomized strategies
- Counting of functions

- Past twenty years: Development of solvers with satisfiability modulo theory solvers
 - Capable of handling theories such as string, bitvectors, linear real arithmetic
- Lifting synthesis techniques to SMT
 - Knowledge compilation
 - Machine Learning techniques for SMT learning
 - Repair techniques

Promise of scalability: Out of 609 benchmarks

2018 SOTA 247 solved

2019 SOTA 280 solved

2020 SOTA 356 solved

2021 SOTA 509 solved

The Future:

1. Benchmarks
2. Notion of Quality
3. Beyond Single Functions
4. Beyond Propositional Logic