

# Boolean Functional Synthesis and its Applications

Priyanka Golia <sup>1,2</sup>

Joint work with: Kuldeep S. Meel <sup>1</sup> and Subhajit Roy <sup>1</sup>



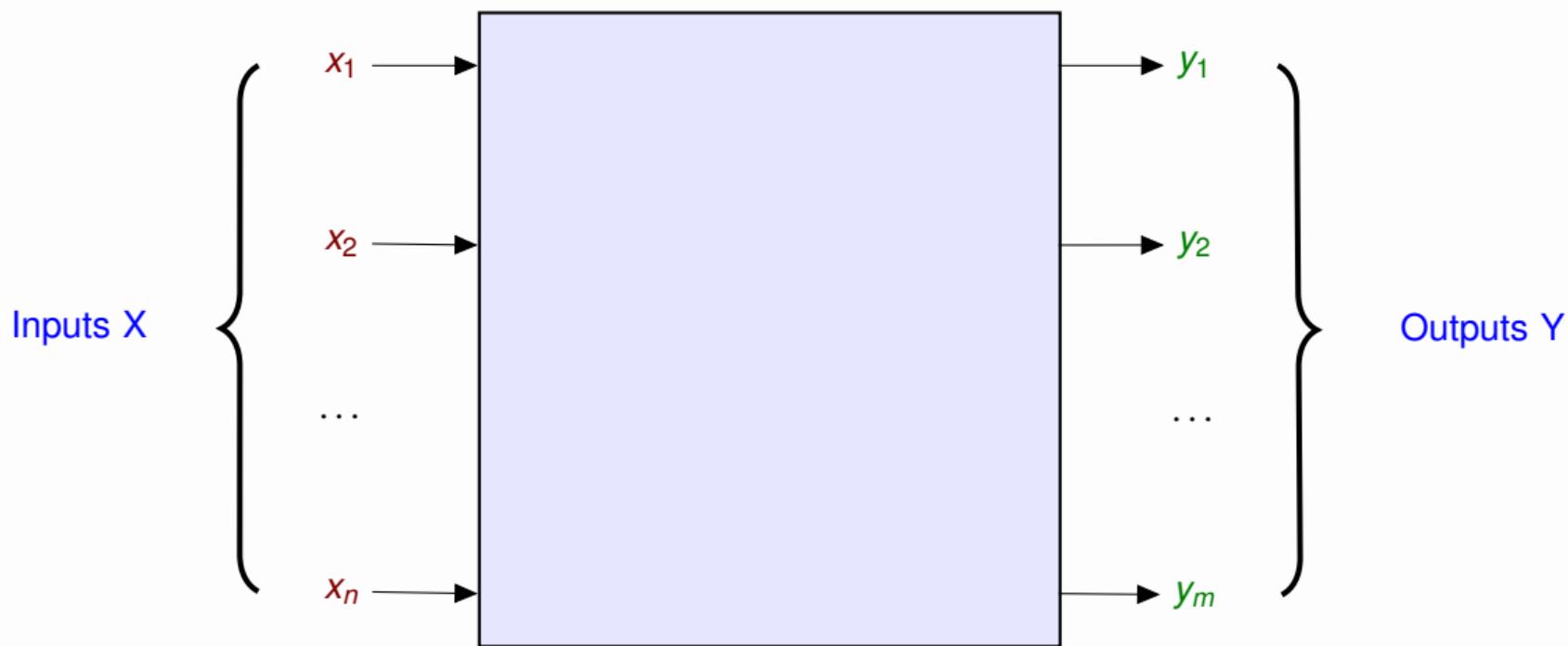
<sup>1</sup>National University of Singapore

<sup>2</sup>Indian Institute of Technology Kanpur

Corresponding Papers: CAV 2020, IJCAI 2021, ICCAD 2021 (Best Paper Award Nomination)

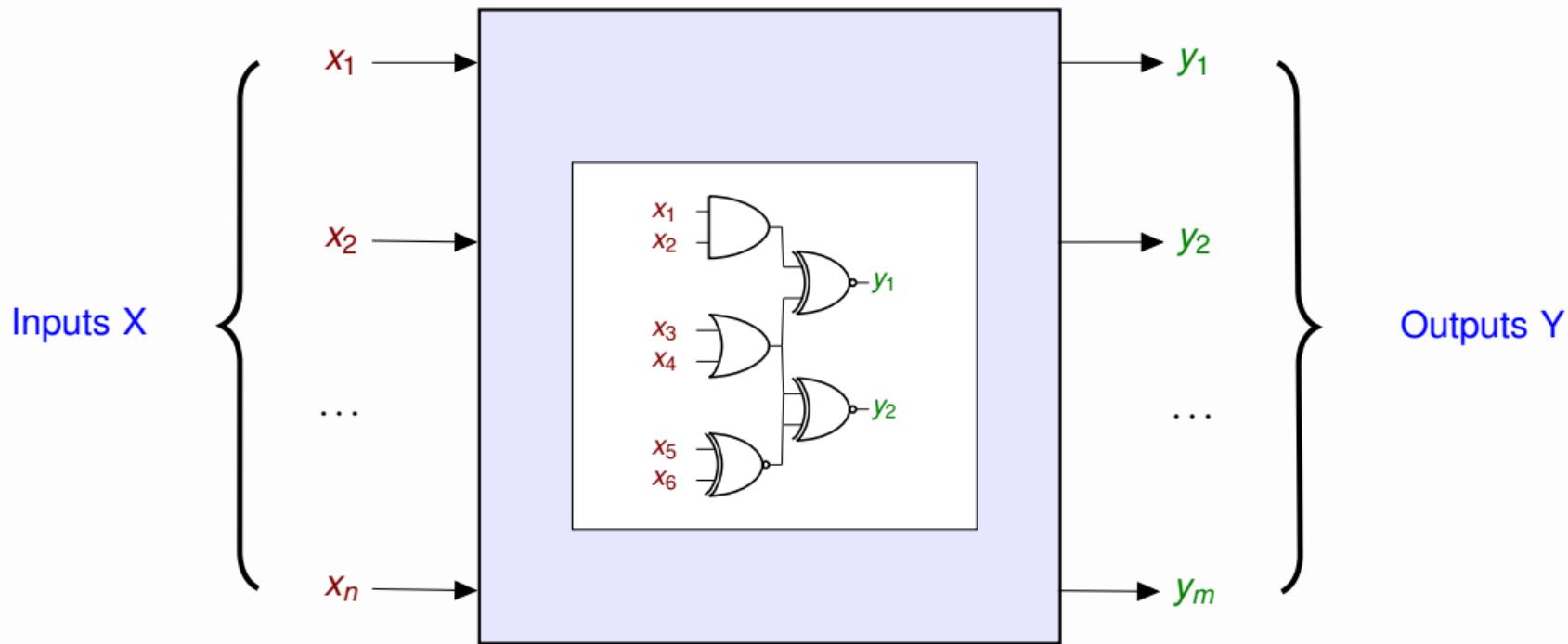
# Synthesis

Specification: Relation  $\varphi(X, Y)$



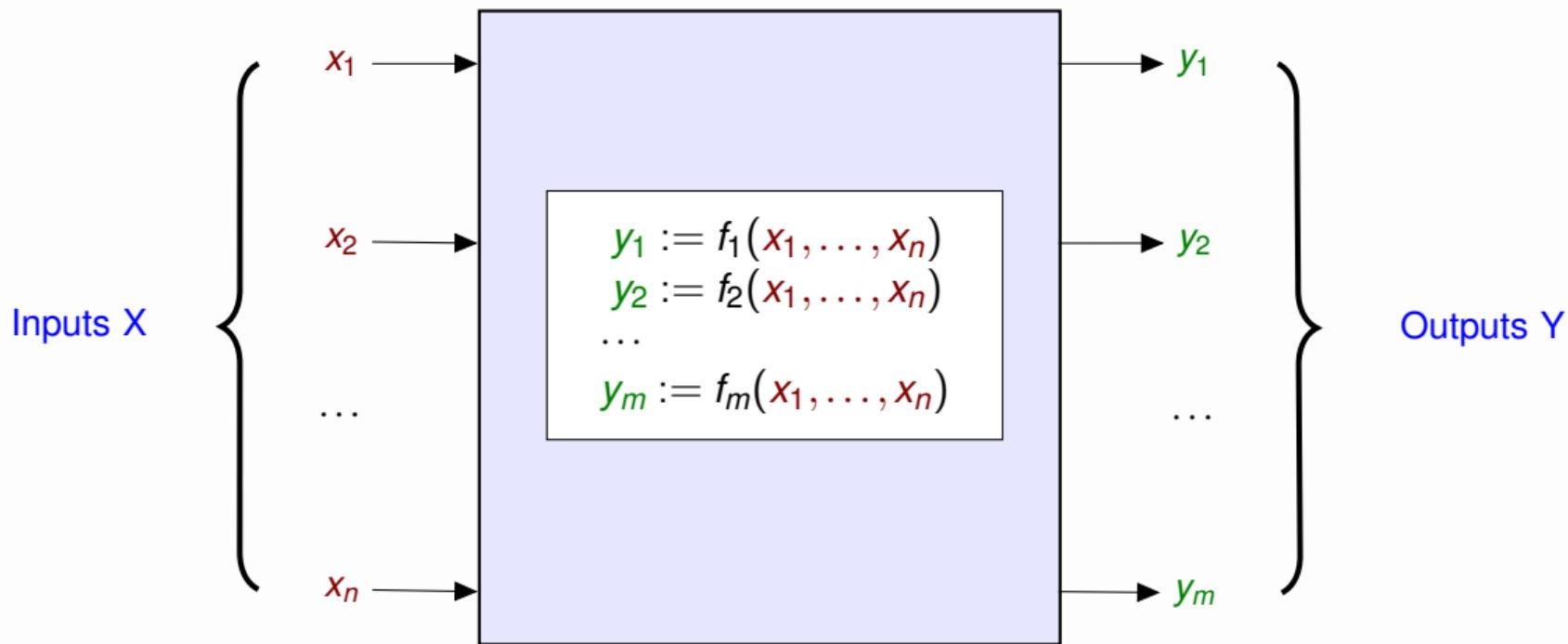
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# Functional Synthesis

Given  $\varphi(\textcolor{red}{X}, \textcolor{green}{Y})$  over inputs  $\textcolor{red}{X} = \{x_1, x_2, \dots, x_n\}$  and outputs  $\textcolor{green}{Y} = \{y_1, y_2, \dots, y_m\}$ .

Synthesize A function vector  $F = \{f_1, f_2, \dots, f_m\}$ , such that  $y_i := f_i(\textcolor{red}{x}_1, \dots, \textcolor{red}{x}_n)$  such that:

$$\exists \textcolor{green}{Y} \varphi(\textcolor{red}{X}, \textcolor{green}{Y}) \equiv \varphi(\textcolor{red}{X}, F(\textcolor{red}{X}))$$

Each  $f_i$  is called Skolem function and  $F$  is called Skolem function vector.

Key Challenge:  $\varphi(\textcolor{red}{X}, \textcolor{green}{Y})$  is a relation

## Non-uniqueness of Skolem Functions

Let  $X = \{x_1, x_2\}$ ,  $Y = \{y_1\}$  and  $\varphi(X, Y) = x_1 \vee x_2 \vee y_1$

Possible Skolem function:  $f(x_1, x_2) := \neg(x_1 \vee x_2)$

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$$\varphi(X, F(X)) = x_1 \vee x_2 \vee (\neg(x_1 \vee x_2))$$

$X$	$\exists Y \varphi(X, Y)$	$\varphi(X, F(X))$	
$x_1 = 0, x_2 = 0$	$y_1 = 1$	True	True
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$\left. \begin{array}{l} \exists Y \varphi(X, Y) \equiv \varphi(X, F(X)) \end{array} \right\}$

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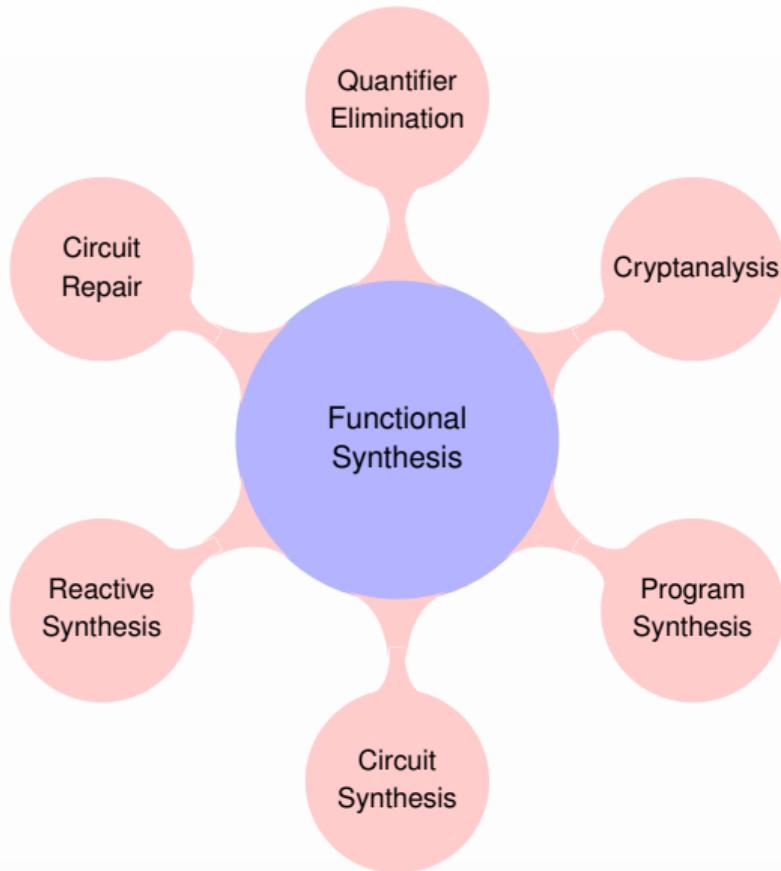
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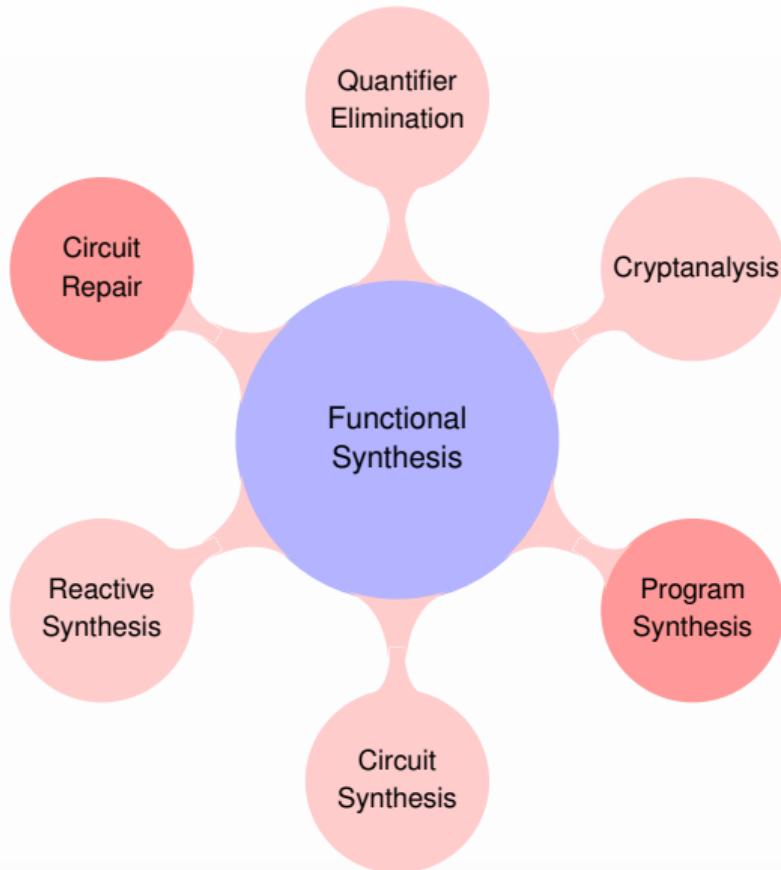
$\left. \begin{array}{l} \exists Y \varphi(X, Y) \\ \varphi(X, F(X)) \end{array} \right\} \exists Y \varphi(X, Y) \equiv \varphi(X, F(X))$

Other possible Skolem functions:  $f_1(x_1, x_2) = \neg x_1$     $f_1(x_1, x_2) = \neg x_2$     $f_1(x_1, x_2) = 1$

# Applications



# Applications



# Application Domain 1: Program Synthesis

Golia et al., IJCAI'21

$$\begin{aligned}g(x_1, x_2) &\geq x_1 \text{ and} \\g(x_1, x_2) &\geq x_2 \text{ and} \\(g(x_1, x_2) &== x_1 \text{ or} \\g(x_1, x_2) &== x_2)\end{aligned}$$

- Synthesize program representing function  $g$  that satisfies the specification.

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$$\begin{aligned}y_1 &\geq x_1 \text{ and} \\y_1 &\geq x_2 \text{ and} \\(y_1 &== x_1 \text{ or} \\y_1 &== x_2)\end{aligned}$$

- Synthesize program representing function  $g$  that satisfies the specification.
- Replace every call of functions  $g$  by a new variable  $y_1$  in the specification.

$$\forall x_1, x_2 \exists y_1 \varphi(x_1, x_2, y_1)$$

# Application Domain 1: Program Synthesis

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$g(x_1, x_2) \geq x_1$  and  
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$y_1 \geq x_1$  and  
 $y_1 \geq x_2$  and  
 $(y_1 == x_1 \text{ or } y_1 == x_2)$

- Synthesize program representing function  $g$  that satisfies the specification.
- Replace every call of functions  $g$  by a new variable  $y_1$  in the specification.
- Works with appropriate caveats, e.g., outputs depend on all inputs.

$$\forall x_1, x_2 \exists y_1 \varphi(x_1, x_2, y_1)$$

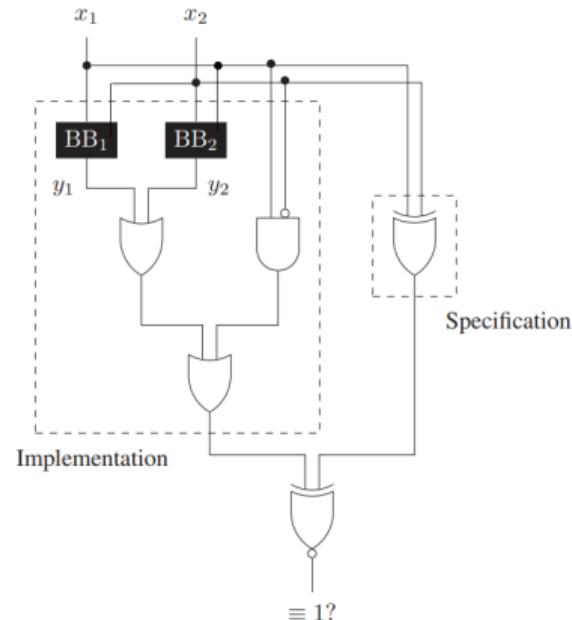
The synthesized skolem function is an implementation of the function  $g(x_1, x_2)$ .

## Application Domain 2: Circuit Repair

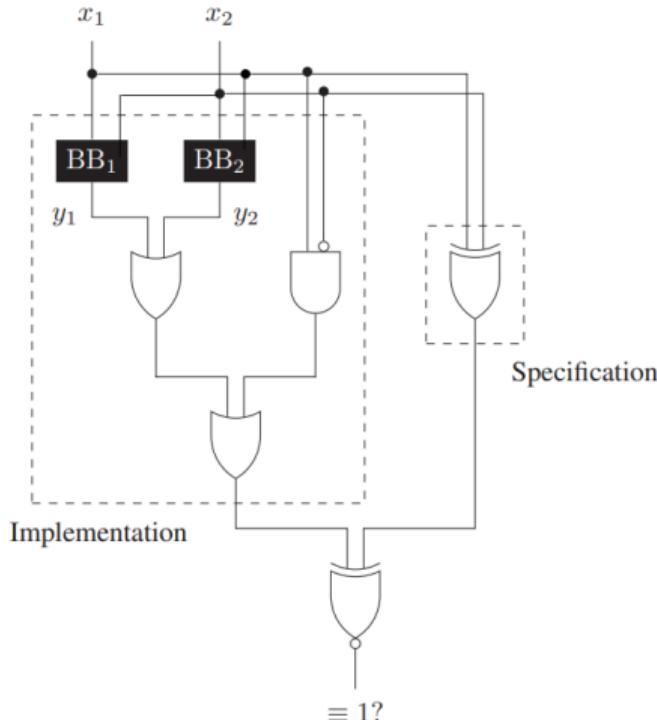
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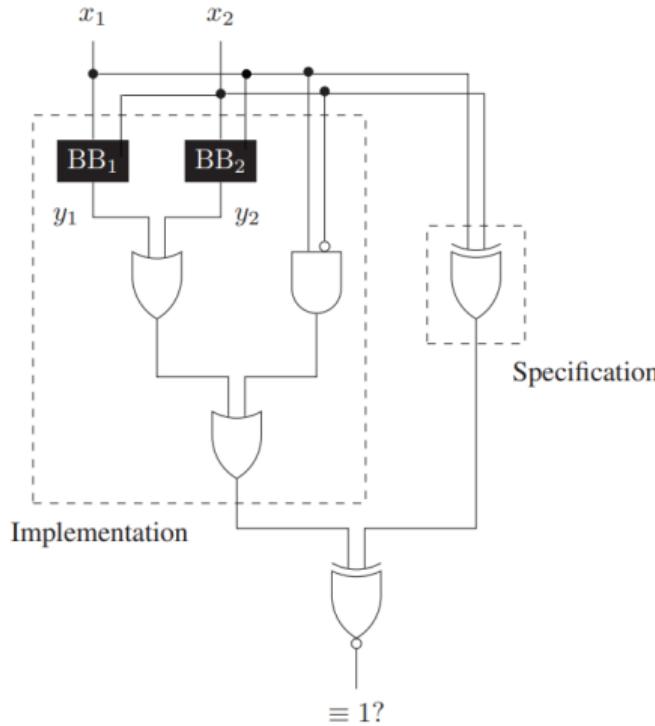


## Application Domain 2: Circuit Repair



- Inputs  $x_1, x_2$ , Outputs  $y_1, y_2$ .
- Synthesise functions(circuits) for  $y_1, y_2$  such that it satisfy the given specification.

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$$\forall x_1, x_2 \exists y_1 y_2 \neg(((y_1 \vee y_2) \vee (x_1 \wedge \neg x_2)) \oplus (x_1 \oplus x_2))$$

Image is taken(modified) from Equivalence Checking of Partial Designs Using Dependency Quantified Boolean Formulae, Gitina et al '13  
Engineering change order for combinational and sequential design rectification, Jiang et. al'20

Synthesis and optimization of multiple portions of circuits for ECO based on set-covering and QBF formulations, Fujita et al'20

# Diverse Approaches

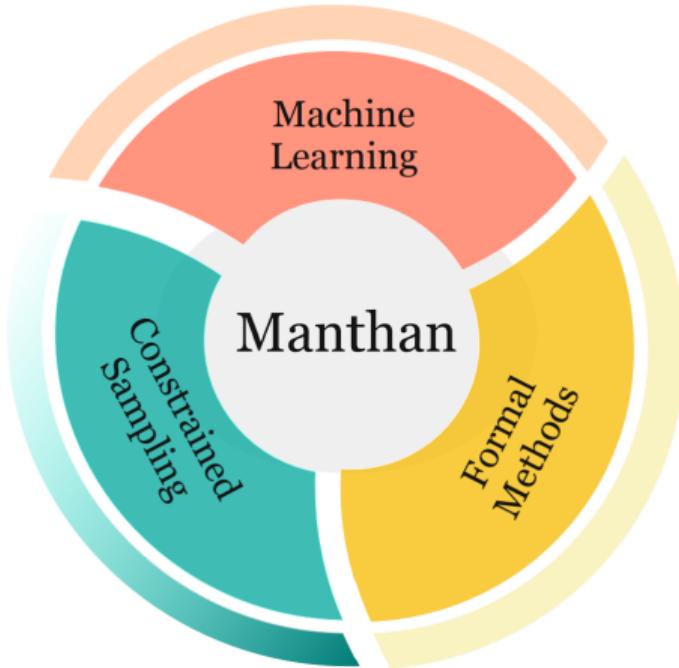
- From the proof of validity of  
 $\forall X \exists Y \varphi(X, Y)$   
(Bendetti et al., 2005)  
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- Quantifier instantiation in SMT solvers  
  
(Barrett et al., 2015)  
(Biere et al., 2017)
- Input-Output Separation  
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- Knowledge representation  
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(Chakraborty et al., 2019)
- Incremental determinization  
(Rabe et al., 2015, 2018, 2019)

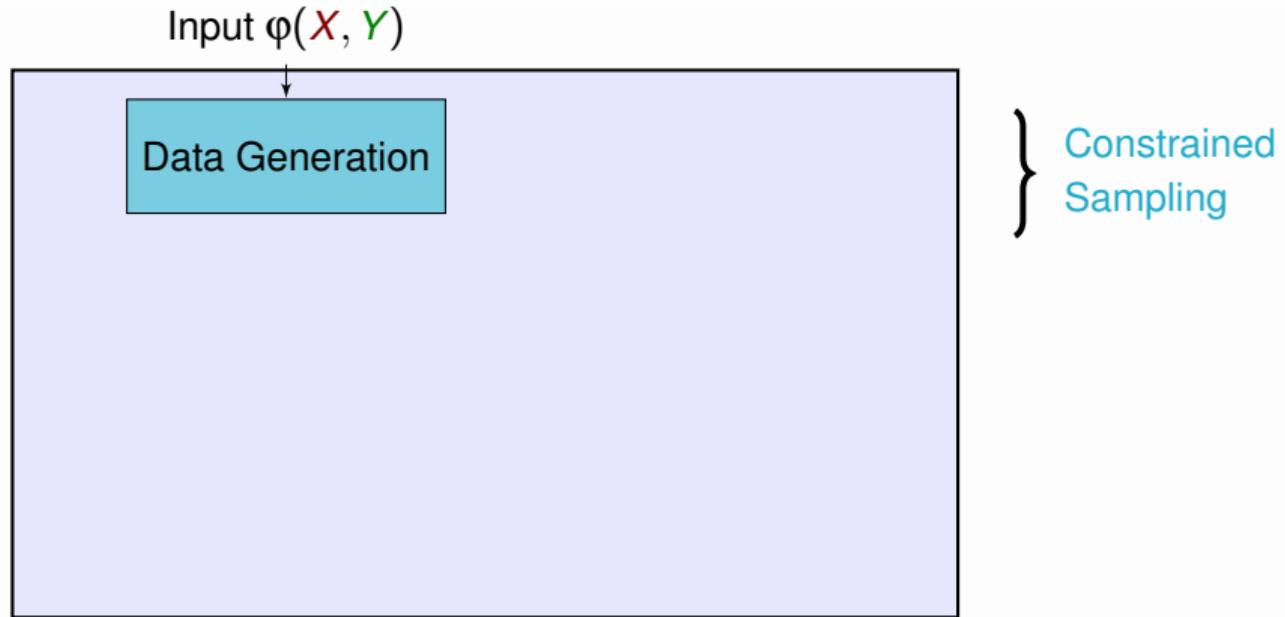
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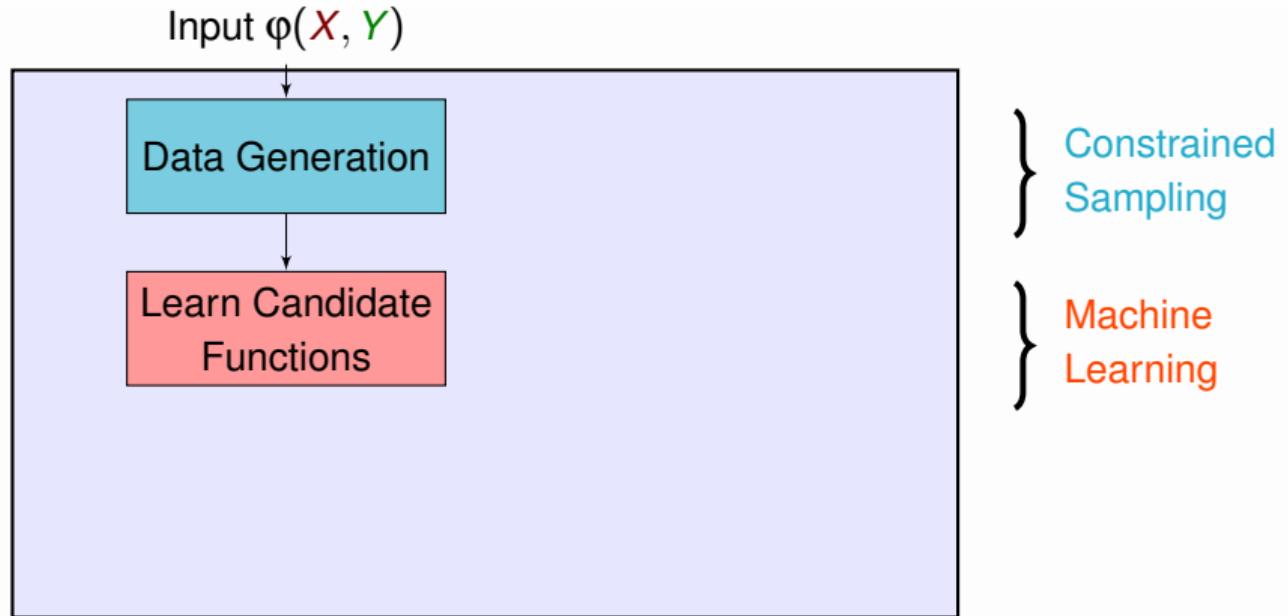
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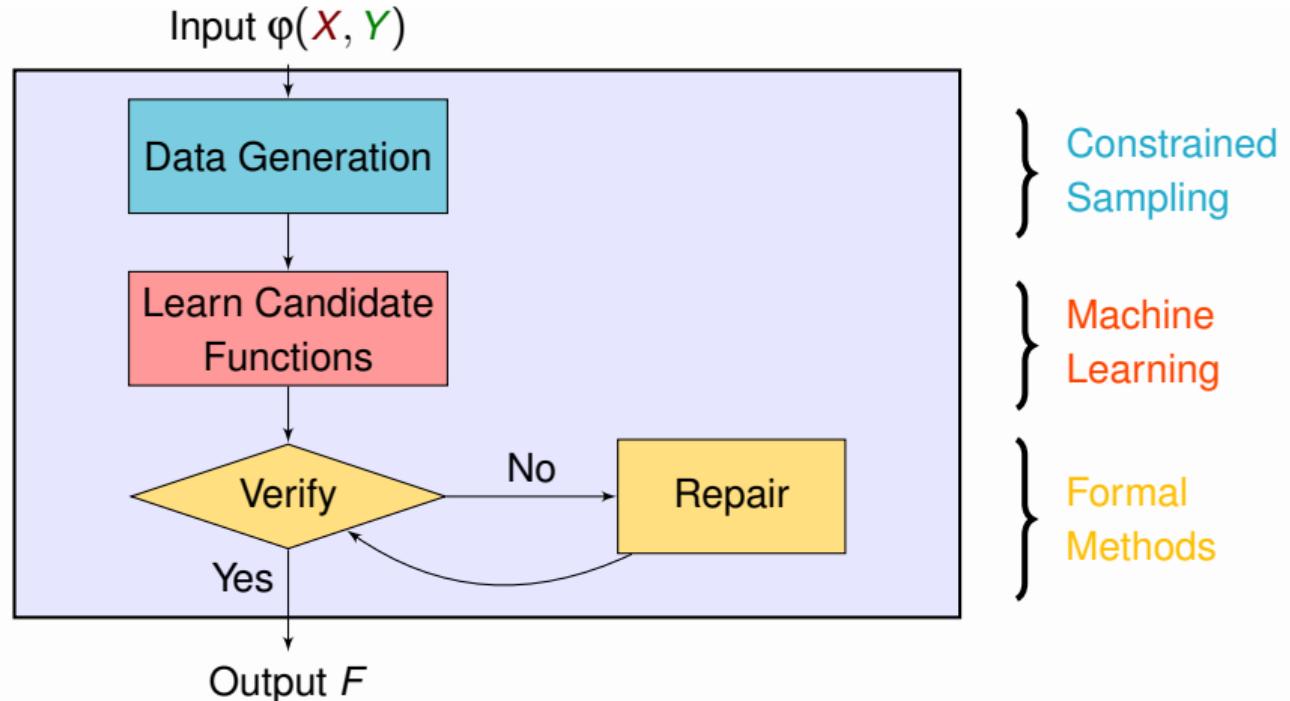
Scalability remains the holy grail

# A Data-Driven Approach for Boolean Functional Synthesis









# Data Generation

## Standing on the Shoulders of Constrained Samplers

$\varphi(x_1, x_2, y_1, y_2)$

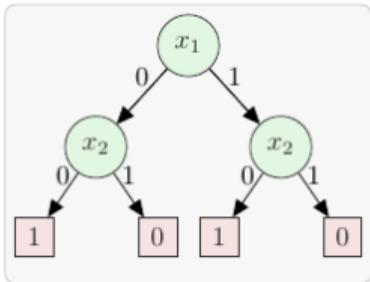


$x_1$	$x_2$	$y_1$	$y_2$
0	0	1	0
0	1	0	1
1	0	1	1
1	1	0	0

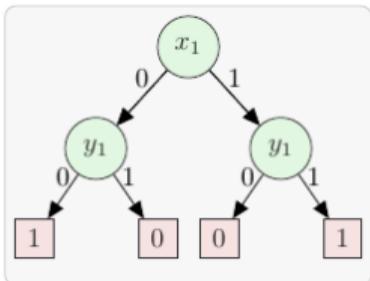
# Learn Candidate Functions

## Taming the Curse of Abstractions via Learning with Errors

$x_1$	$x_2$	$y_1$	$y_2$
0	0	1	0
0	1	0	1
1	0	1	1
1	1	0	0



$p_1 := (\neg x_1 \wedge \neg x_2),$   
 $p_2 := (x_1 \wedge \neg x_2)$   
 $f_1 = \text{if } p_1 \text{ then } 1$   
     $\text{elif } p_2 \text{ then } 1$   
     $\text{else } 0$



$p_1 := (\neg x_1 \wedge \neg y_1),$   
 $p_2 := (x_1 \wedge y_1)$   
 $f_2 = \text{if } p_1 \text{ then } 1$   
     $\text{elif } p_2 \text{ then } 1$   
     $\text{else } 0$

# Verification of Candidate Functions

## Reaping the Fruits of Formal Methods Revolution

$$E(\textcolor{red}{X}, \textcolor{green}{Y}, \textcolor{brown}{Y}') := \varphi(\textcolor{red}{X}, \textcolor{green}{Y}) \wedge \neg\varphi(\textcolor{red}{X}, \textcolor{brown}{Y}') \wedge (\textcolor{brown}{Y}' \leftrightarrow F(\textcolor{red}{X}))$$

(JSCTA'15)

- If  $E(\textcolor{red}{X}, \textcolor{green}{Y}, \textcolor{brown}{Y}')$  is UNSAT:  $\exists \textcolor{green}{Y} \varphi(\textcolor{red}{X}, \textcolor{green}{Y}) \equiv \varphi(\textcolor{red}{X}, F(\textcolor{red}{X}))$ 
  - Return  $F$
- If  $E(\textcolor{red}{X}, \textcolor{green}{Y}, \textcolor{brown}{Y}')$  is SAT:  $\exists \textcolor{green}{Y} \varphi(\textcolor{red}{X}, \textcolor{green}{Y}) \not\equiv \varphi(\textcolor{red}{X}, F(\textcolor{red}{X}))$ 
  - Let  $\sigma \models E(\textcolor{red}{X}, \textcolor{green}{Y}, \textcolor{brown}{Y}')$  be a counterexample to fix.

# The Repair Module

## Reaping the Fruits of Formal Methods Revolution

- $\sigma = \{x_1 \mapsto 1, x_2 \mapsto 1, y_1 \mapsto 1, y_2 \mapsto 0, y'_1 \mapsto 0, y'_2 \mapsto 1\}.$

# The Repair Module

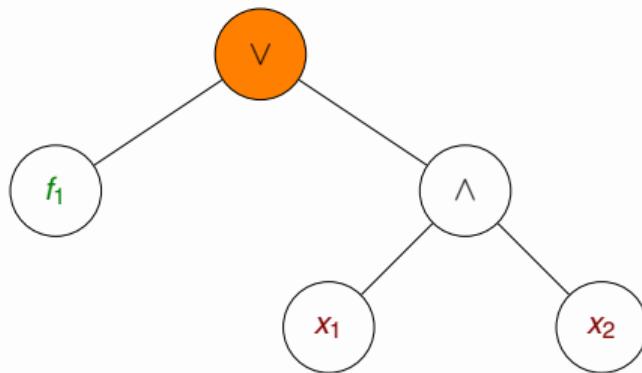
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- $\sigma = \{x_1 \mapsto 1, x_2 \mapsto 1, y_1 \mapsto 1, y_2 \mapsto 0, y'_1 \mapsto 0, y'_2 \mapsto 1\}$ .
- Repair: If  $\underbrace{x_1 \wedge x_2}_{\beta=\{x_1, x_2\}}$  then  $y_1 = 1$

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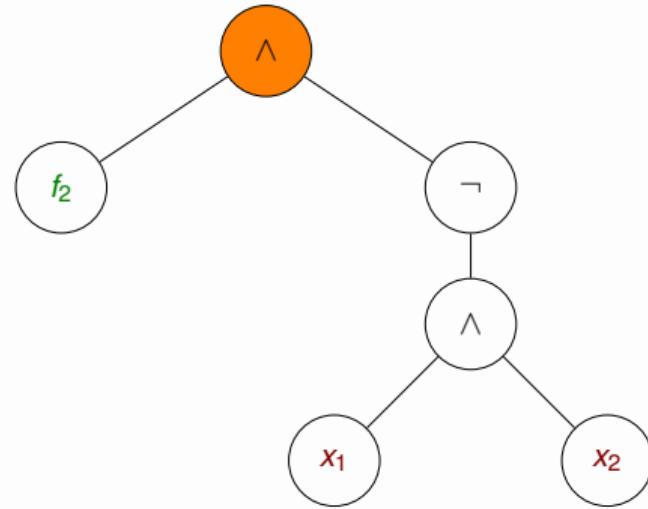
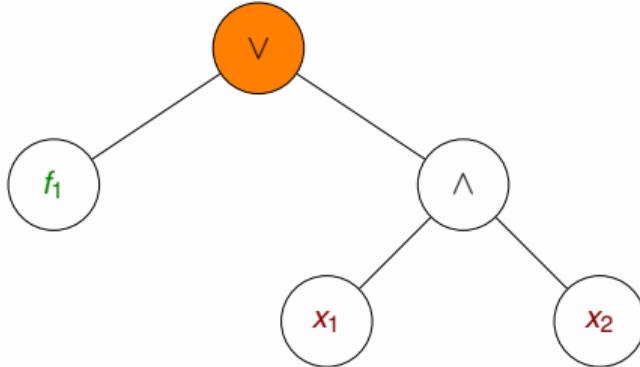
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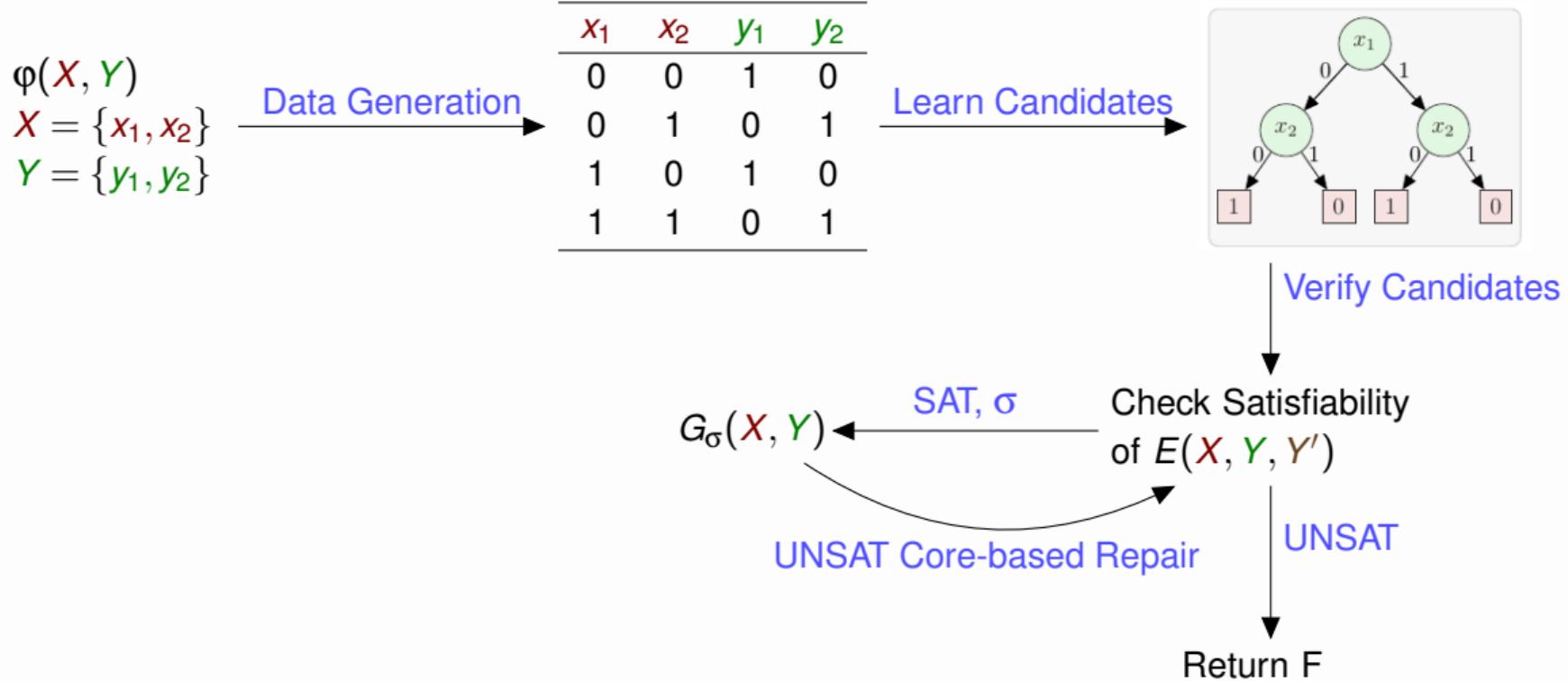


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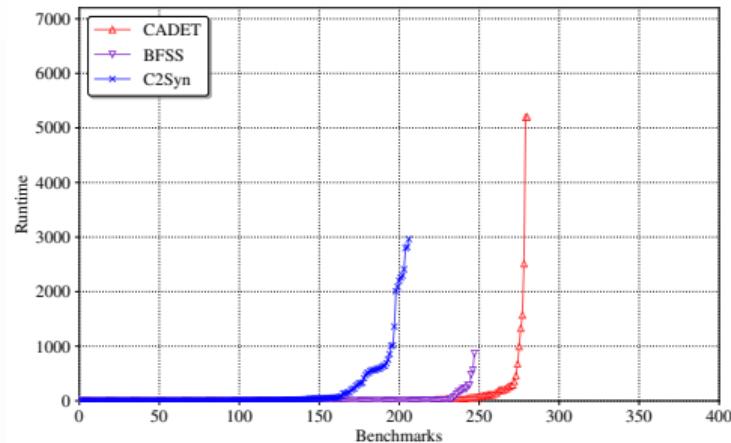




## Experimental Evaluations

- 609 Benchmarks from:
  - QBFEval competition
  - Arithmetic
  - Disjunctive decomposition
  - Factorization
- Compared Manthan with State-of-the-art tools: CADET ([Rabe et al., 2019](#)), BFSS ([Akshay et al. ,2018](#)), C2Syn ([Chakraborty et al., 2019](#)).
- Timeout: 7200 seconds.

# Experimental Evaluations



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C2Syn  
206

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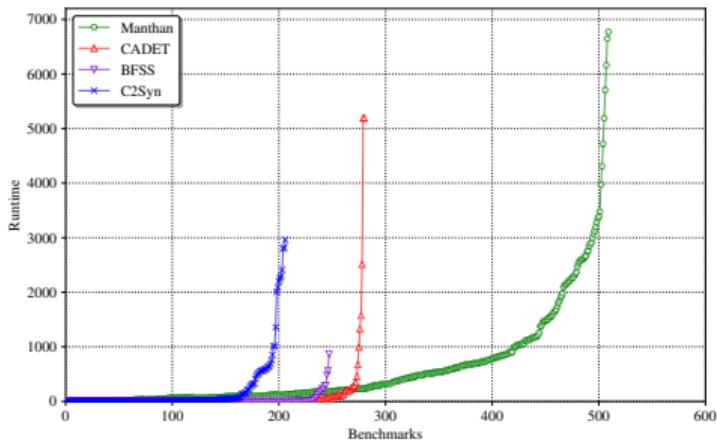
BFSS  
247

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CADET  
280

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C2Syn  
206

BFSS  
247

CADET  
280

Manthan  
509

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An increase of 223 benchmarks.

# Conclusion

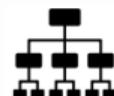
Manthan: A Data-Driven Approach for Boolean Functional Synthesis.



Constrained Sampling



Solves 509 benchmarks — state of the art  
could solve 280



Decision List Classifier



Formal Methods



<https://github.com/meelgroup/manthan>

Thanks!